

Bloch Equations and Relaxation

M219 - Principles and Applications of MRI

Kyung Sung, Ph.D.

1/23/2023

Course Overview

- Course website
 - <https://mrrl.ucla.edu/pages/m219>
- 2023 course schedule
 - https://mrrl.ucla.edu/pages/m219_2023
- Assignments
 - Homework #1 due on 1/30
 - Homework #2 will be out on 1/30
- Office hours, Fridays 10-12pm
 - In-person (Ueberroth, 1417B)
 - Zoom is also available

Last Time...

$$\vec{\tau} = \vec{\mu} \times \vec{B} \quad \vec{S} = \vec{r} \times \vec{p}$$

$$\vec{\tau} = \frac{d\vec{S}}{dt} \quad \vec{\mu} = \gamma \vec{S}$$

$$\frac{d\vec{\mu}}{dt} = \vec{\mu} \times \gamma \vec{B}$$

Equation of Motion for a Magnetic Dipole

$$\vec{M} = \sum_{n=1}^{N_{total}} \vec{\mu}_n$$

$$M_x(t) = M_x^0 \cos(\gamma B_0 t) + M_y^0 \sin(\gamma B_0 t)$$

$$M_y(t) = -M_x^0 \sin(\gamma B_0 t) + M_y^0 \cos(\gamma B_0 t)$$

$$M_z(t) = M_z^0$$

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

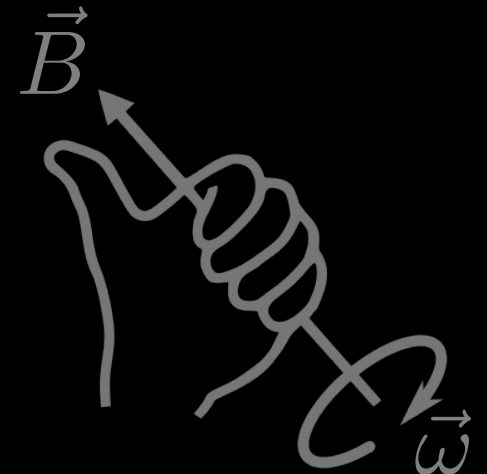
Equation of Motion for the bulk magnetization.

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \begin{pmatrix} \vec{B}_0 \end{pmatrix}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ M_x & M_y & M_z \\ 0 & 0 & \gamma B_0 \end{vmatrix}$$

$$\vec{B}_0 = B_0 \vec{k}$$

Free Precession w/o Relaxation

$$\mathbf{R}_z(\omega_0 t) = \begin{bmatrix} \cos \omega_0 t & \sin \omega_0 t & 0 \\ -\sin \omega_0 t & \cos \omega_0 t & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
A diagram illustrating left-handed precession. A vector \vec{B} points upwards and to the left. A helical path winds around the vector \vec{B} , indicating the path of a magnetization vector. A circular arrow at the bottom right indicates the direction of precession, which is clockwise when viewed from the tip of \vec{B} . A vector $\vec{\omega}$ is shown at the bottom right, pointing downwards and to the right, representing the precession frequency.

Precession is left-handed (clockwise).

$$\vec{M}(t) = \mathbf{R}_z(\omega_0 t) \vec{M}^0$$

Basic RF Pulse

$$\vec{B} = \vec{B}_0 + \vec{B}_1(t)$$

$$\vec{B}_1(t) = B_1^e(t) [\cos(\omega_{RF}t + \theta)\hat{i} - \sin(\omega_{RF}t + \theta)\hat{j}]$$

$$B_1^e(t)$$

pulse envelope function

$$\omega_{RF}$$

excitation carrier frequency

$$\theta$$

initial phase angle

B_1 is perpendicular to B_0 .

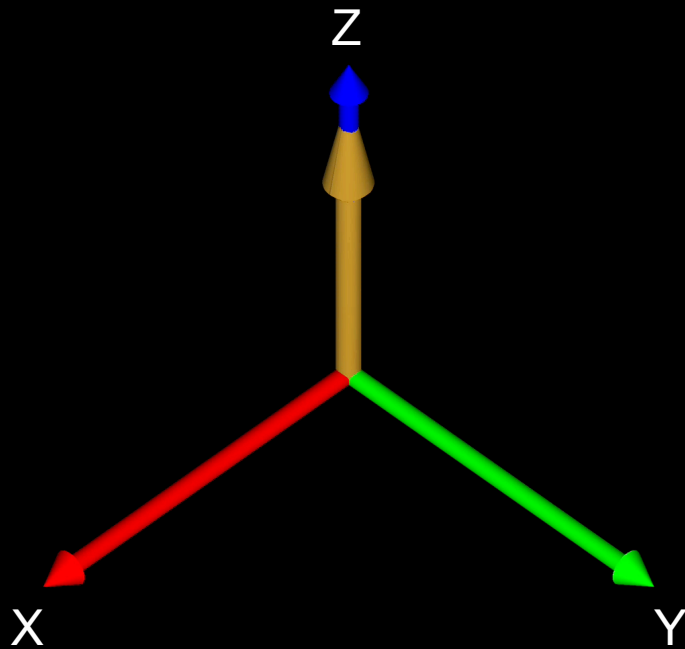
$$\vec{B}_0 = B_0\hat{k}$$

Rotating Frame

Lab vs. Rotating Frame

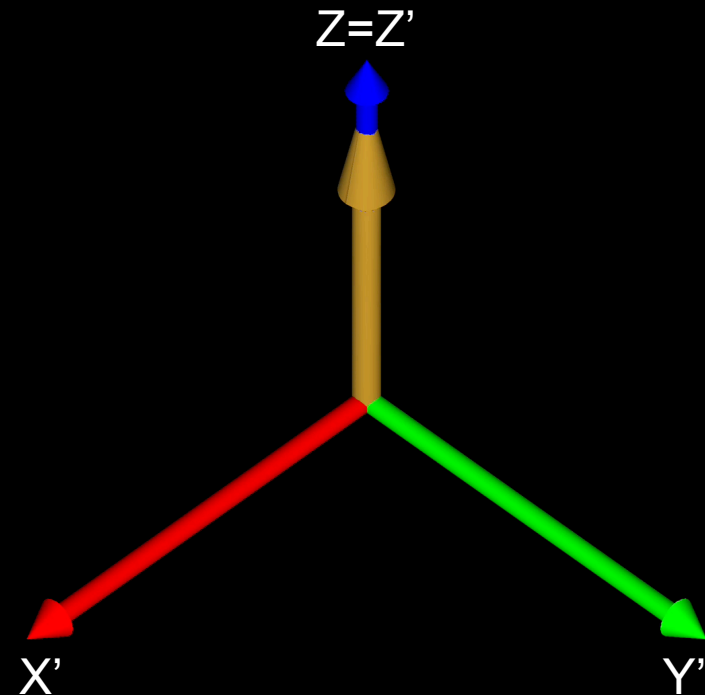
- The rotating frame simplifies the mathematics and permits more intuitive understanding.

90° RF (Laboratory Frame)



Spins Precess

90° RF (Rotating Frame)



Observer Precesses

Note: Both coordinate frames share the same z-axis.

Combined B_0 & B_1 Effects

$$\begin{aligned}\frac{d\vec{M}}{dt} &= \vec{M} \times \gamma \vec{B} \\ &= \vec{M} \times \gamma \left(\vec{B}_0 + \vec{B}_1 \right)\end{aligned}$$

Relationship Between Lab and Rotating Frames

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

Rotating Frame Definitions

$$\vec{M}_{rot} \equiv \begin{bmatrix} M_{x'} \\ M_{y'} \\ M_{z'} \end{bmatrix} \quad \vec{B}_{rot} \equiv \begin{bmatrix} B_{x'} \\ B_{y'} \\ B_{z'} \end{bmatrix} \quad \begin{aligned} B_{z'} &\equiv B_z \\ M_{z'} &\equiv M_z \end{aligned}$$

$$\vec{M}_{lab}(t) = R_Z(\omega_{RF}t) \cdot \vec{M}_{rot}(t)$$

Bulk magnetization components in the rotating frame.

$$\vec{B}_{lab}(t) = R_Z(\omega_{RF}t) \cdot \vec{B}_{rot}(t)$$

Applied B-field components in the rotating frame.

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B} \quad \longrightarrow \quad \frac{d\vec{M}_{rot}}{dt} = \vec{M}_{rot} \times \gamma \vec{B}_{eff}$$

Bloch Equation (Rotating Frame)

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

Equation of motion for an ensemble of spins (isochromats).
[Laboratory Frame]

$$\frac{d\vec{M}_{rot}}{dt} = \vec{M}_{rot} \times \gamma \left(\frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot} \right)$$

Equation of motion for an ensemble of spins (isochromats).
[Rotating Frame]

$$\vec{B}_{eff} \equiv \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot} \quad \vec{\omega}_{rot} = \begin{pmatrix} 0 \\ 0 \\ -\omega_{RF} \end{pmatrix}$$

↑
Effective B-field that M experiences in the rotating frame.

↑
Fictitious field that demodulates the apparent effect of B_0 .

↑
Applied B-field in the rotating frame.

Bloch Equation (Rotating Frame)

$$\vec{B}(t) = B_0 \hat{k} + B_1^e(t) [\cos(\omega_{RF}t + \theta) \hat{i} - \sin(\omega_{RF}t + \theta) \hat{j}]$$

$$\vec{B}_{lab}(t) = \begin{pmatrix} B_1^e(t) \cos(\omega_{RF}t + \theta) \\ -B_1^e(t) \sin(\omega_{RF}t + \theta) \\ B_0 \end{pmatrix} \quad \vec{B}_{rot}(t) = \begin{pmatrix} B_1^e(t) \cos \theta \\ -B_1^e(t) \sin \theta \\ B_0 \end{pmatrix}$$

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Applied B-field in the rotating frame.

Bloch Equation (Rotating Frame)

$$\vec{B}_{eff} \equiv \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot}$$

Assume no RF phase ($\theta = 0$)

$$\vec{B}_{rot}(t) = \begin{pmatrix} B_1^e(t) \\ 0 \\ B_0 \end{pmatrix} \quad \vec{\omega}_{rot} = \begin{pmatrix} 0 \\ 0 \\ -\omega_{RF} \end{pmatrix}$$

$$\vec{B}_{eff}(t) = \begin{pmatrix} B_1^e(t) \\ 0 \\ B_0 \end{pmatrix} \begin{matrix} \omega_{RF} \\ \gamma \end{matrix}$$

Relationship Between Lab and Rotating Frames

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

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Bulk magnetization components in the rotating frame.

$$\vec{B}_{lab}(t) = R_Z(\omega_{RF}t) \cdot \vec{B}_{rot}(t)$$

Applied B-field components in the rotating frame.

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B} \quad \longrightarrow \quad \frac{d\vec{M}_{rot}}{dt} = \vec{M}_{rot} \times \gamma \vec{B}_{eff}$$

Bloch Equation (Rotating Frame)

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

Equation of motion for an ensemble of spins (isochromats).
[Laboratory Frame]

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Equation of motion for an ensemble of spins (isochromats).
[Rotating Frame]

$$\vec{B}_{eff} \equiv \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot} \quad \vec{\omega}_{rot} = \begin{pmatrix} 0 \\ 0 \\ -\omega_{RF} \end{pmatrix}$$

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Effective B-field that M experiences in the rotating frame.

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Fictitious field that demodulates the apparent effect of B_0 .

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Assume no RF phase ($\theta = 0$)

$$\vec{B}_{rot}(t) = \begin{pmatrix} B_1^e(t) \\ 0 \\ B_0 \end{pmatrix} \quad \vec{\omega}_{rot} = \begin{pmatrix} 0 \\ 0 \\ -\omega_{RF} \end{pmatrix}$$

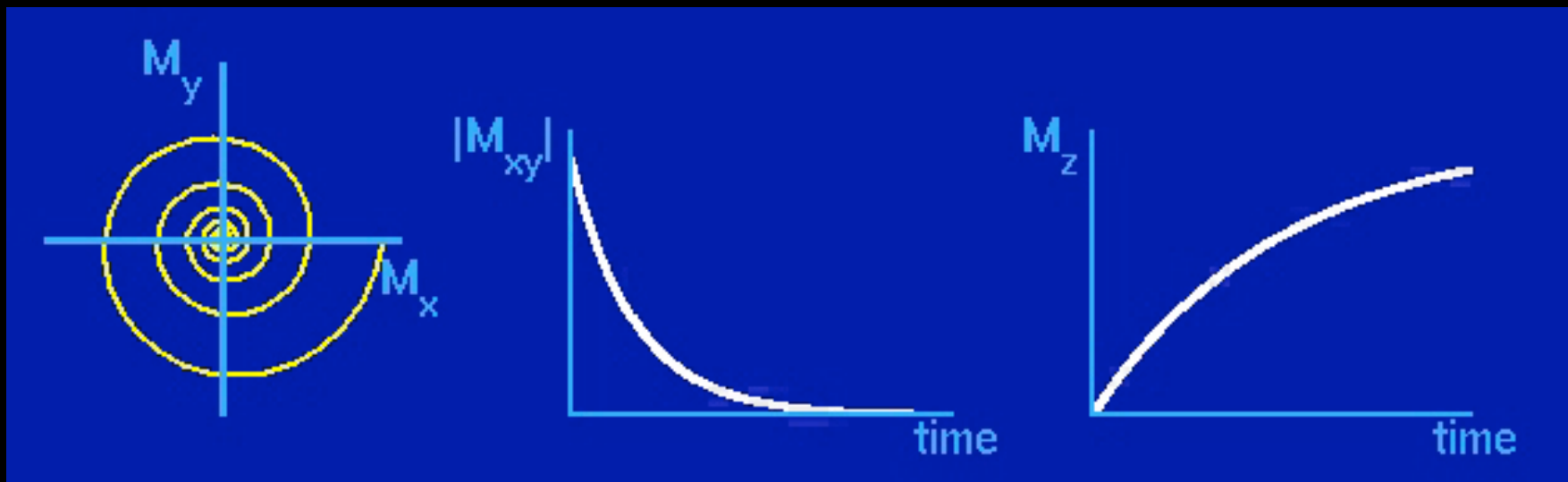
$$\vec{B}_{eff}(t) = \begin{pmatrix} B_1^e(t) \\ 0 \\ B_0 \end{pmatrix} \begin{matrix} \omega_{RF} \\ \gamma \end{matrix}$$

To the Board

T_1 & T_2 Relaxation

Relaxation

- Magnetization returns exponentially to equilibrium:
 - Longitudinal recovery time constant is T1
 - Transverse decay time constant is T2
- Relaxation and precession are independent



T₁ Relaxation

- Longitudinal or spin-lattice relaxation
 - Typically, (10s ms) < T₁ < (100s ms)
- T₁ is long for
 - Small molecules (water)
 - Large molecules (proteins)
- T₁ is short for
 - Fats and intermediate-sized molecules
- T₁ increases with increasing B₀
- T₁ decreases with contrast agents

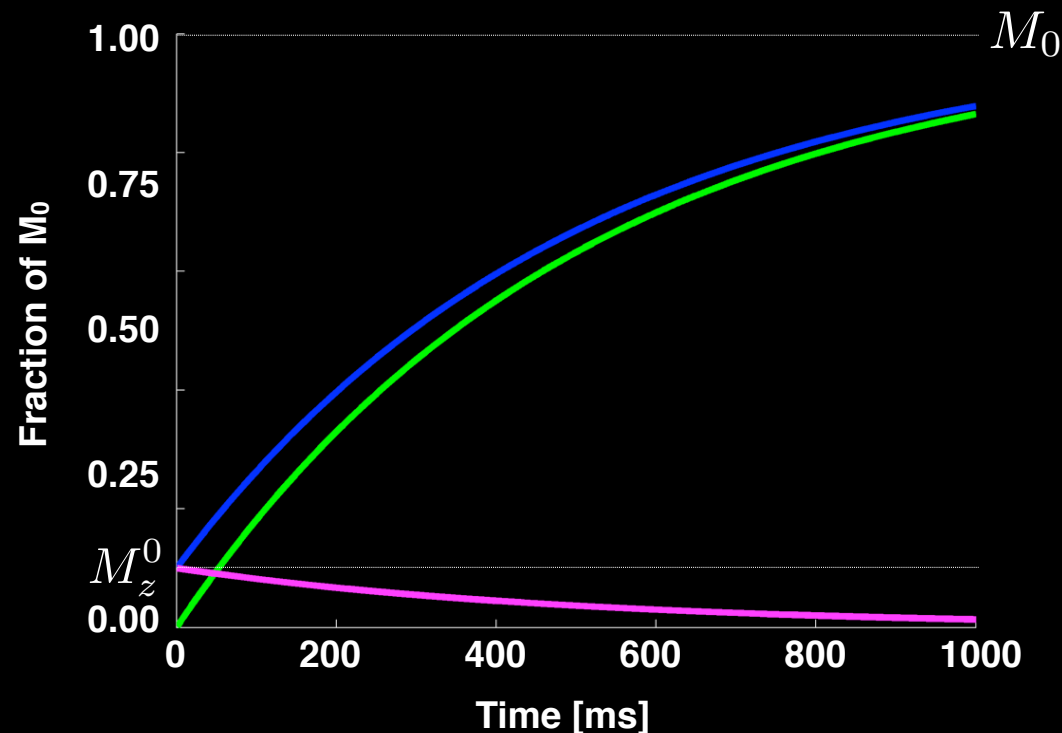
Short T₁s are bright on T₁-weighted image

T₁ Relaxation

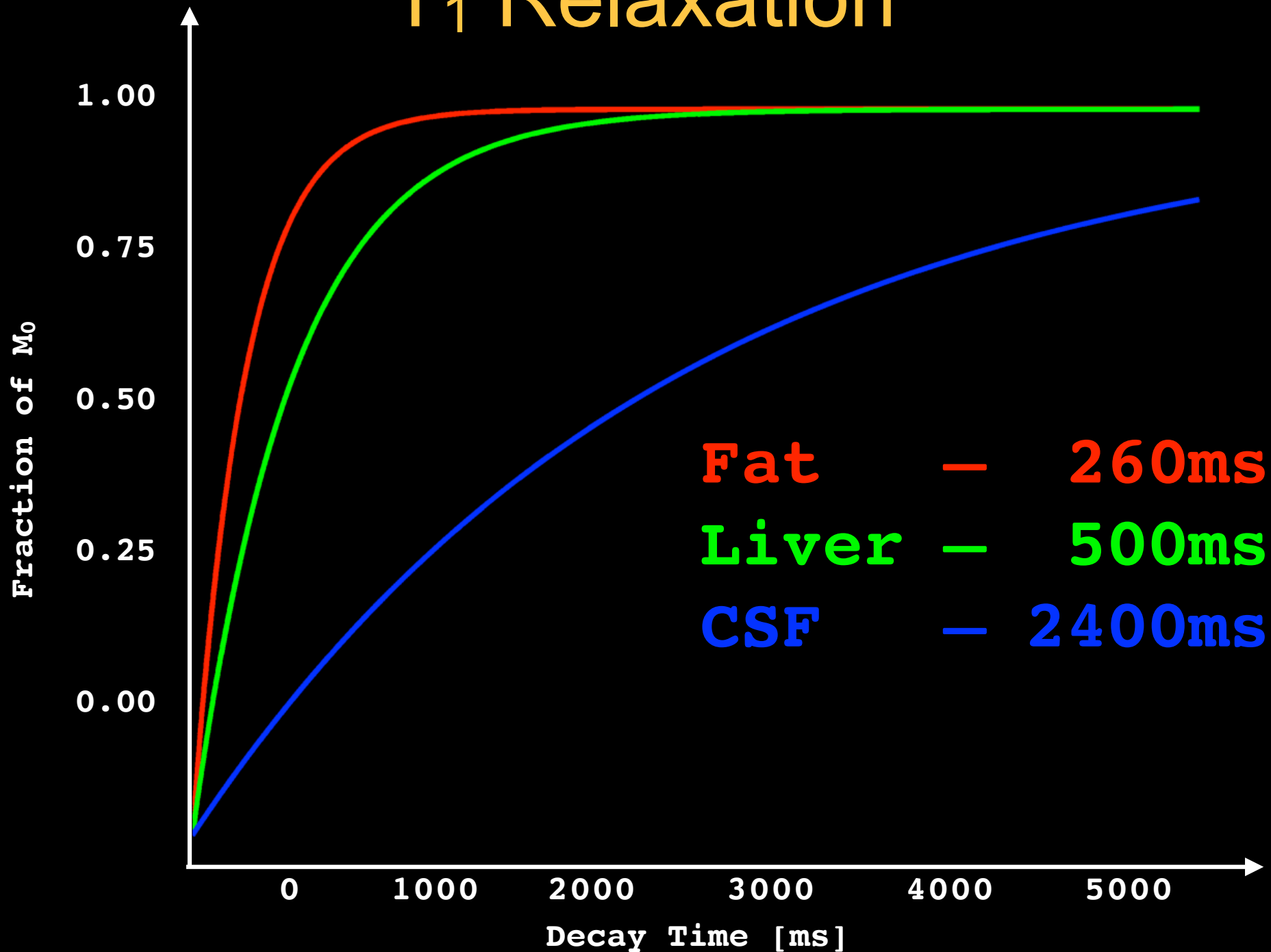
Free Precession in the Lab *or* Rotating Frame with Relaxation

$$M_{z'}(t) = \underbrace{M_z^0}_{\text{Net Magnetization}} e^{-t/T_1} + \underbrace{M_0}_{\text{Prepared Magnetization Decays } (M_z^0)} (1 - e^{-t/T_1})$$

Net Magnetization Prepared Magnetization Decays (M_z^0) Return to Thermal Equilibrium (M_0)

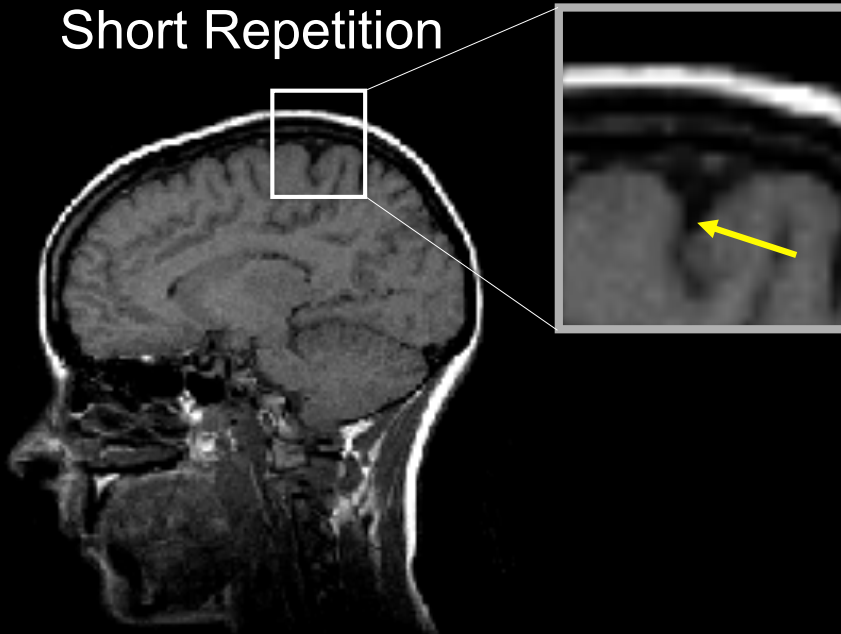


T₁ Relaxation

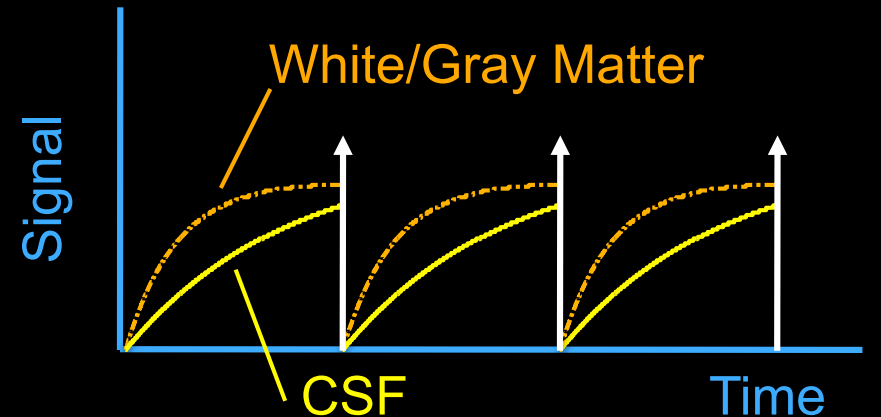
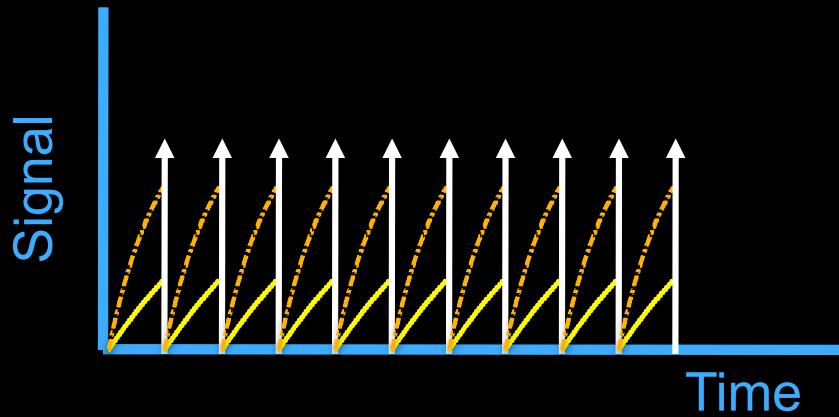
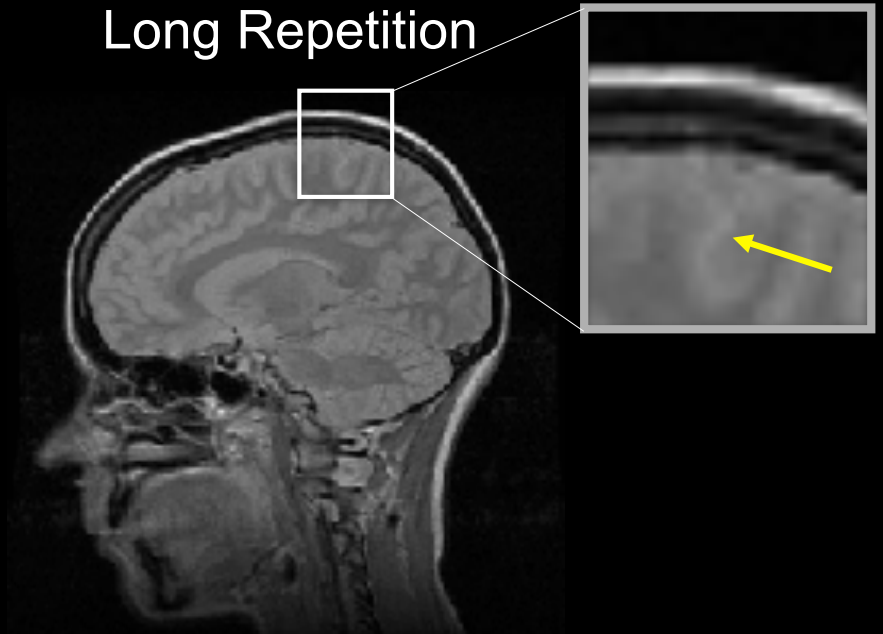


T₁ Contrast

Short Repetition



Long Repetition



T₂ Relaxation

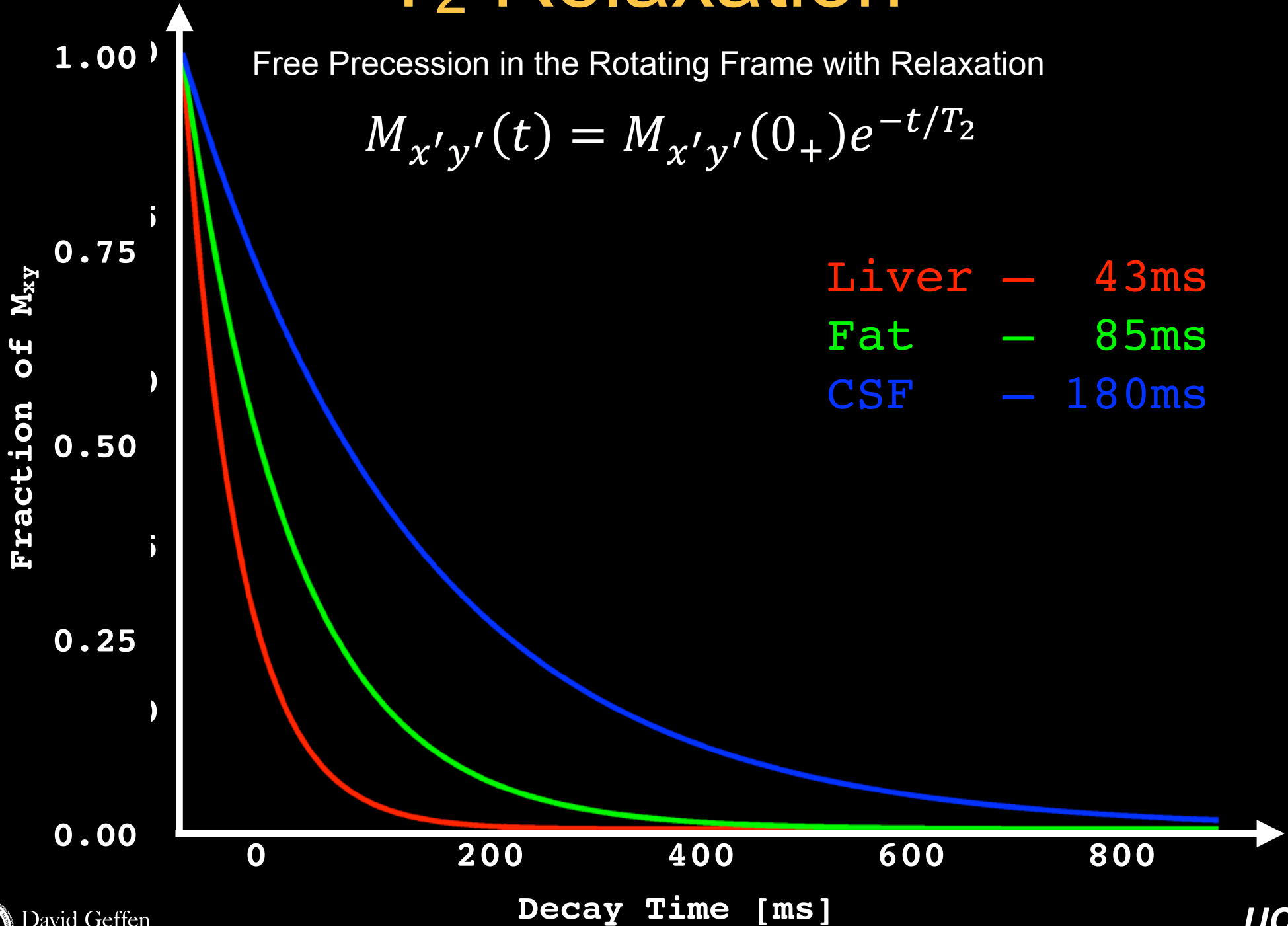
- Transverse or spin-spin relaxation
 - Molecular interaction causes spin dephasing
 - Typically, T₂ < (10s ms)
- Increasing molecular size, decrease T₂
 - Fat has a short T₂
- Increasing molecular mobility, increases T₂
 - Liquids (CSF, edema) have long T₂s
- Increasing molecular interactions, decreases T₂
 - Solids have short T₂s
- T₂ relatively independent of B₀

Long T₂ is bright on T₂ weighted image

T₂ Relaxation

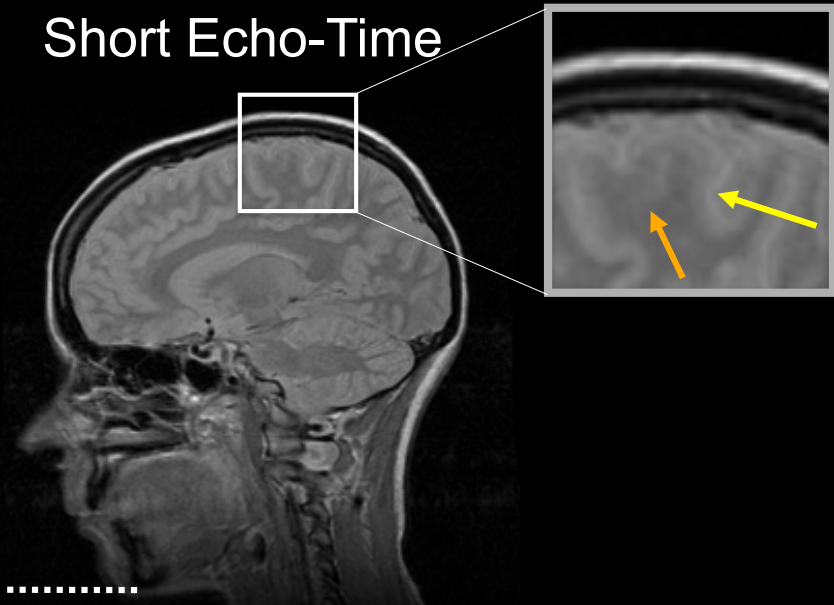
Free Precession in the Rotating Frame with Relaxation

$$M_{x'y'}(t) = M_{x'y'}(0_+)e^{-t/T_2}$$

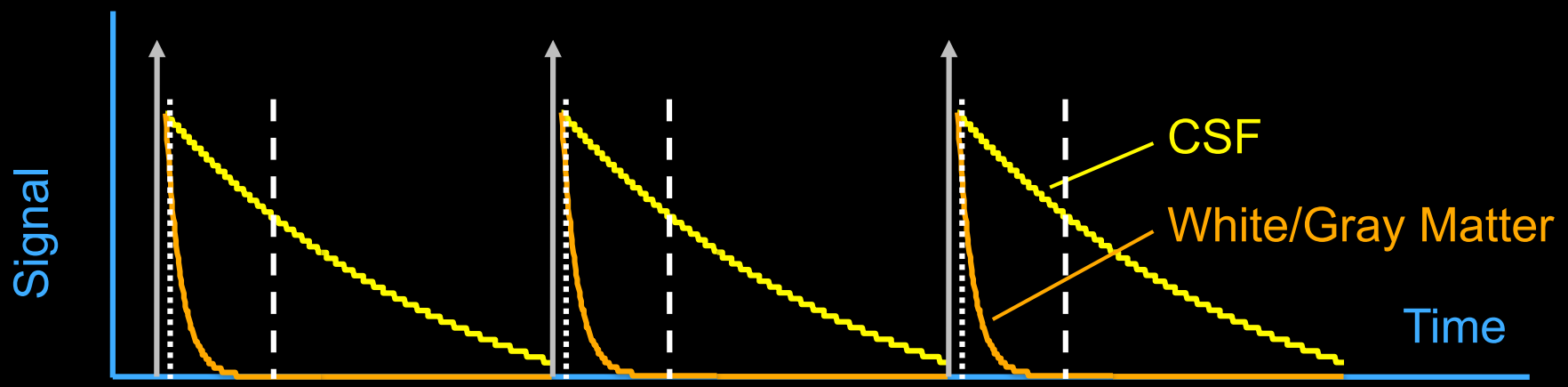
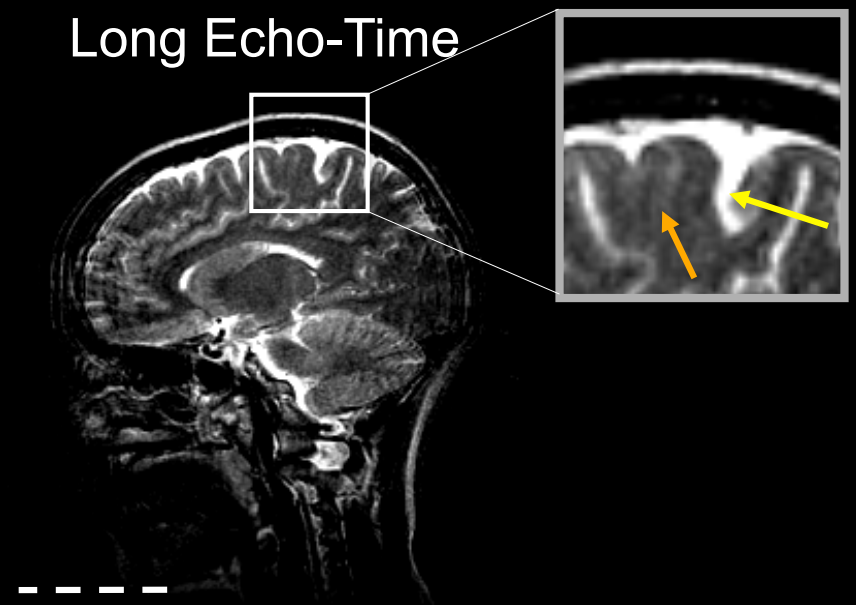


T2 Contrast

Short Echo-Time



Long Echo-Time



T₁ and T₂ Values @ 1.5T

Tissue	T ₁ [ms]	T ₂ [ms]
gray matter	925	100
white matter	790	92
muscle	875	47
fat	260	85
kidney	650	58
liver	500	43
CSF	2400	180

Each tissue has “unique” relaxation properties, which enables “soft tissue contrast”.

T_2^* Relaxation

T_2^* Relaxation

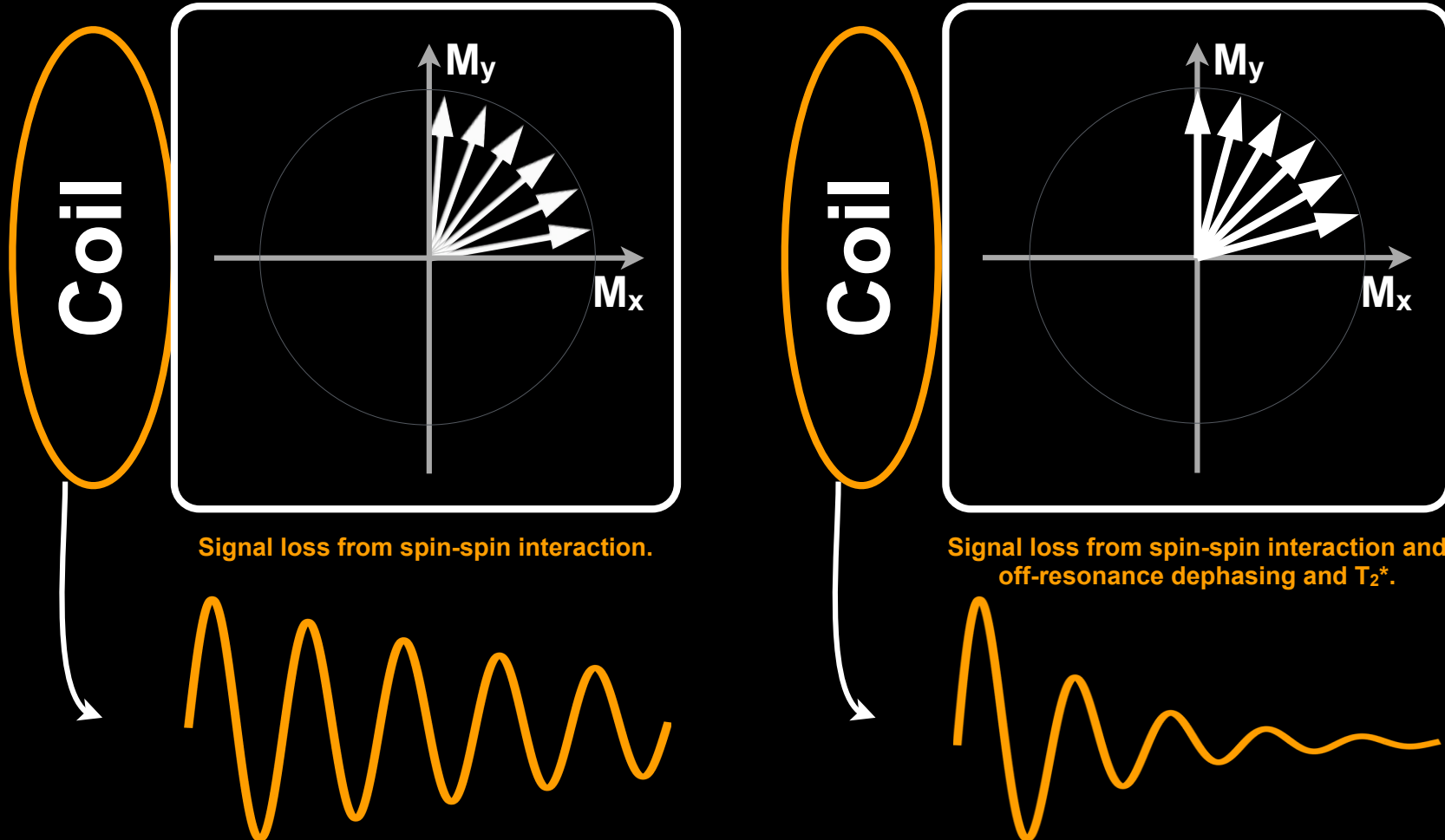
$$\frac{1}{T_2^*} = \frac{1}{T_2} + \gamma \Delta B_0$$

- T_2^* is “observed” transverse relaxation time constant
- T_2^* consists of irreversible spin-spin (T_2) dephasing and reversible intravoxel spin dephasing due to off-resonance
- Sources of off-resonance:
 - B_0 inhomogeneity
 - susceptibility differences (e.g. air spaces)

T_2 versus T_2^*

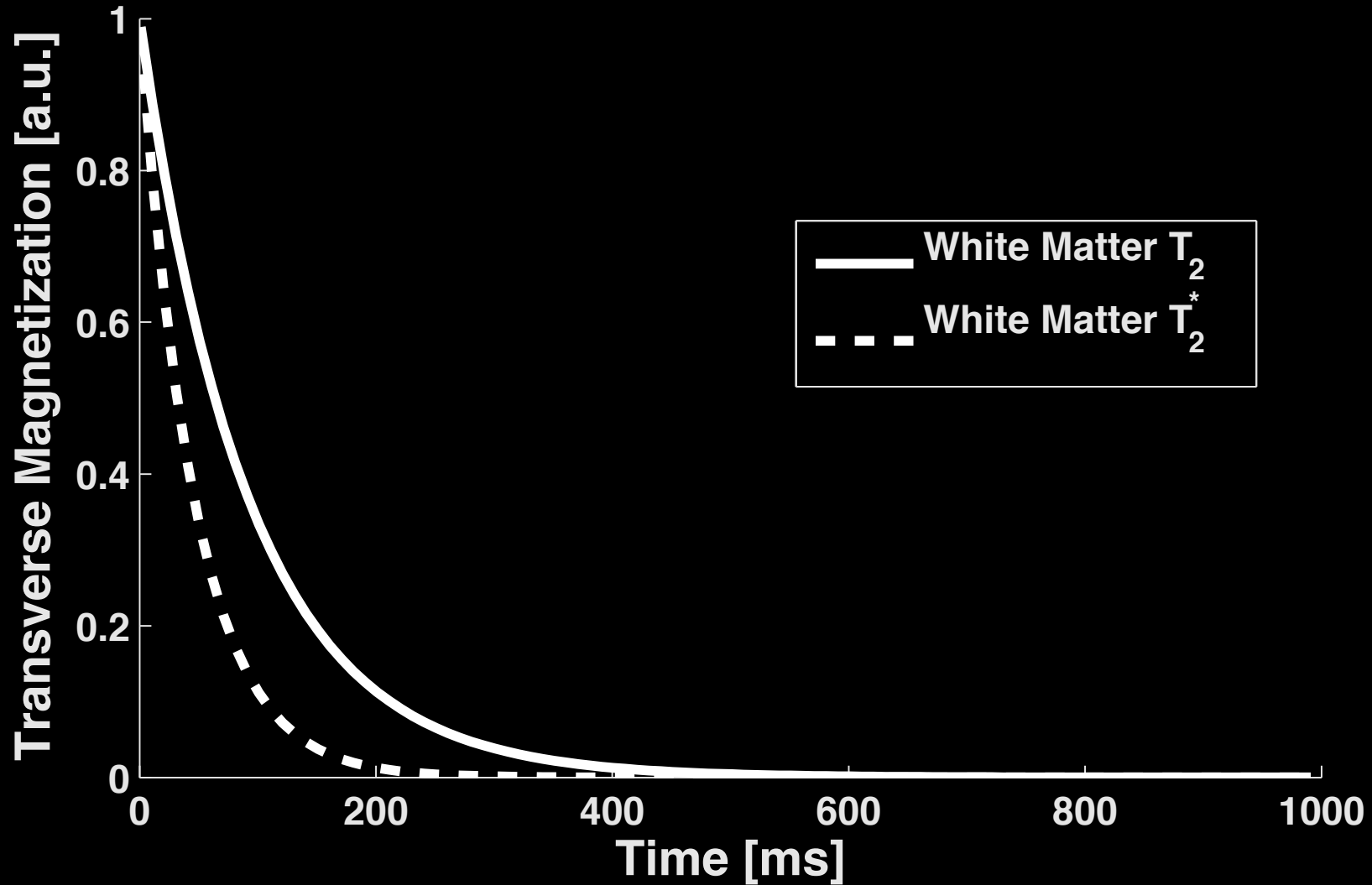
T_2 Decay

T_2^* Decay



T_2^* is signal loss from spin dephasing and T_2

$T_2^* < T_2$ (always!)



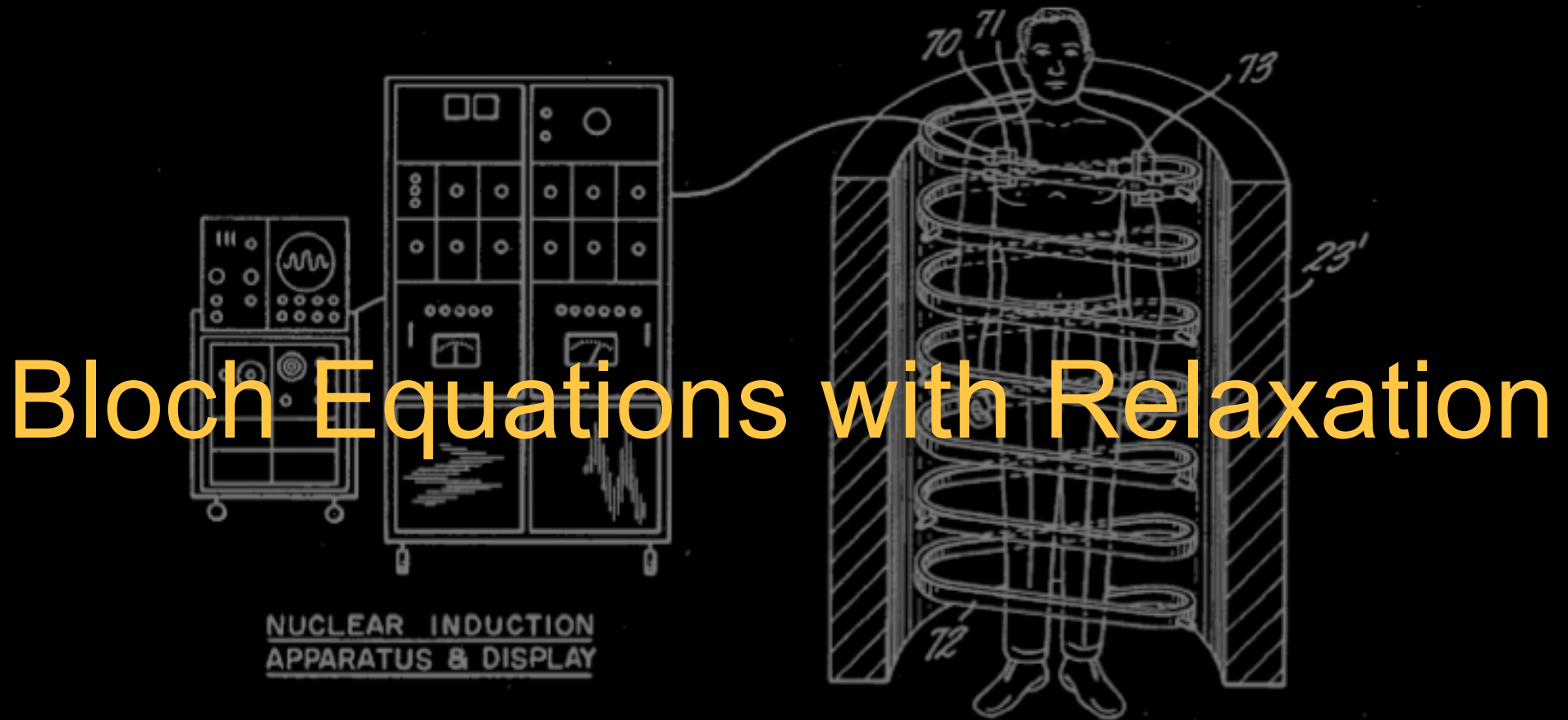


FIG. 2

Bloch Equations with Relaxation



Bloch Equations with Relaxation

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B} - \frac{M_x \hat{i} + M_y \hat{j}}{T_2} - \frac{(M_z - M_0) \hat{k}}{T_1}$$

- **Differential Equation**
 - Ordinary, Coupled, Non-linear
- **No analytic solution, in general.**
 - Analytic solutions for simple cases.
 - Numerical solutions for all cases.
- **Phenomenological**
 - Exponential behavior is an approximation.

Bloch Equations - Lab Frame

$$\frac{d\vec{M}}{dt} = \underbrace{\vec{M} \times \gamma \vec{B}}_{\text{Precession}} - \underbrace{\frac{M_x \hat{i} + M_y \hat{j}}{T_2}}_{\text{Transverse Relaxation}} - \underbrace{\frac{(M_z - M_0) \hat{k}}{T_1}}_{\text{Longitudinal Relaxation}}$$

- Precession
 - Magnitude of M unchanged
 - Phase (rotation) of M changes due to B
- Relaxation
 - T_1 changes are slow O(100ms)
 - T_2 changes are fast O(10ms)
 - Magnitude of M can be ZERO
- Diffusion
 - Spins are thermodynamically driven to exchange positions.
 - Bloch-Torrey Equations

Bloch Equations – Rotating Frame

$$\frac{\partial \vec{M}_{rot}}{\partial t} = \underbrace{\gamma \vec{M}_{rot} \times \vec{B}_{eff}}_{\text{"Precession"}} - \underbrace{\frac{M_{x'} \vec{i}' + M_{y'} \vec{j}'}{T_2}}_{\text{Transverse Relaxation}} - \underbrace{\frac{(M_{z'} - M_0) \vec{k}'}{T_1}}_{\text{Longitudinal Relaxation}}$$

$$\vec{B}_{eff} \triangleq \frac{\vec{\omega}}{\gamma} + \vec{B}_{rot}$$

Effective B-field that M experiences in the rotating frame

The applied B₀ and B₁ field in the rotating frame

Fictitious field created by the rotating frame that demodulates the apparent effect of B₀

Free Precession in the Rotating Frame with Relaxation

Free Precession in the Rotating Frame

$$\frac{\partial \vec{M}_{rot}}{\partial t} = \gamma \vec{M}_{rot} \times \vec{B}_{eff} - \frac{M_{x'} \vec{i}' + M_{y'} \vec{j}'}{T_2} - \frac{(M_{z'} - M_0) \vec{k}'}{T_1}$$

$$\vec{B}_{eff} \triangleq \frac{\vec{\omega}}{\gamma} + \vec{B}_{rot}$$

$$\vec{\omega}_{rot} = \vec{\omega} = -\gamma B_0 \hat{k} \quad \vec{B}_{rot} = B_0 \hat{k}$$

$$\vec{B}_{eff} = \vec{0}$$

$$\frac{\partial \vec{M}_{rot}}{\partial t} = - \frac{M_{x'} \vec{i}' + M_{y'} \vec{j}'}{T_2} - \frac{(M_{z'} - M_0) \vec{k}'}{T_1}$$

Free Precession in the Rotating Frame

$$\frac{\partial \vec{M}_{rot}}{\partial t} = \underbrace{-\frac{M_{x'}\vec{i}' + M_{y'}\vec{j}'}{T_2}}_{\text{Transverse Relaxation}} - \underbrace{\frac{(M_{z'} - M_0)\vec{k}'}{T_1}}_{\text{Longitudinal Relaxation}}$$

- **No precession**
- **T₁ and T₂ Relaxation**
- **Drop the diffusion term**
- **System of first order, linear, separable ODEs!**

Free Precession in the Rotating Frame

$$\frac{\partial \vec{M}_{rot}}{\partial t} = \underbrace{-\frac{M_{x'}\vec{i}' + M_{y'}\vec{j}'}{T_2}}_{\text{Transverse Relaxation}} - \underbrace{\frac{(M_{z'} - M_0)\vec{k}'}{T_1}}_{\text{Longitudinal Relaxation}}$$

Solution:

$$M_{z'}(t) = M_z^0 e^{-t/T_1} + M_0(1 - e^{-t/T_1})$$

$$M_{x'y'}(t) = M_{x'y'}(0_+) e^{-t/T_2}$$

Forced Precession in the Rotating Frame with Relaxation

Forced Precession in the Rot. Frame with Relaxation

$$\frac{\partial \vec{M}_{rot}}{\partial t} = \gamma \vec{M}_{rot} \times \vec{B}_{eff} - \frac{M_{x'} \vec{i}' + M_{y'} \vec{j}'}{T_2} - \frac{(M_{z'} - M_0) \vec{k}'}{T_1}$$

$$\vec{B}_{eff} \triangleq \frac{\vec{\omega}}{\gamma} + \vec{B}_{rot}$$

$$\vec{\omega}_{rot} = \vec{\omega} = -\gamma B_0 \hat{k} \quad \vec{B}_{rot} = B_0 \hat{k} + B_1^e(t) \hat{i}'$$

$$\vec{B}_{eff} = B_1^e(t) \hat{i}'$$

Forced Precession in the Rot. Frame with Relaxation

$$\frac{\partial \vec{M}_{rot}}{\partial t} = \gamma \vec{M}_{rot} \times \vec{B}_{eff} - \frac{M_{x'} \vec{i}' + M_{y'} \vec{j}'}{T_2} - \frac{(M_{z'} - M_0) \vec{k}'}{T_1}$$

$$\vec{B}_{eff} = B_1^e(t) \hat{i}'$$

- **B1 induced nutation**
- **T₁ and T₂ Relaxation**
- **Drop the diffusion term**
- **System or first order, linear, coupled PDEs!**
- **When does this equation apply?**

Forced Precession in the Rotating Frame with Relaxation

- RF pulses are short
 - $100\mu\text{s}$ to 5ms
- Relaxation time constants are long
 - T_1 $O(100\text{s})$ ms
 - T_2 $O(10\text{s})$ ms
- Complicated Coupling
- Best suited for simulation

Free? Forced? Relaxation?

- **We've considered all combinations of:**
 - Free and forced precession
 - With and without relaxation
 - Laboratory and rotating frames
- **Which one's concern M219 the most?**
 - Free precession in the rotating frame with relaxation
 - Forced precession in the rotating frame without relaxation.
- **We can, in fact, simulate all of them...**

Questions?

- Related reading materials
 - Nishimura - Chap 4 and 5

Kyung Sung, Ph.D.

KSung@mednet.ucla.edu

<http://mrrl.ucla.edu/sunglab>