

Imperfections & Artifacts

Daniel B. Ennis, Ph.D.

Magnetic Resonance Research Labs

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David Geffen
School of Medicine

UCLA
Radiology

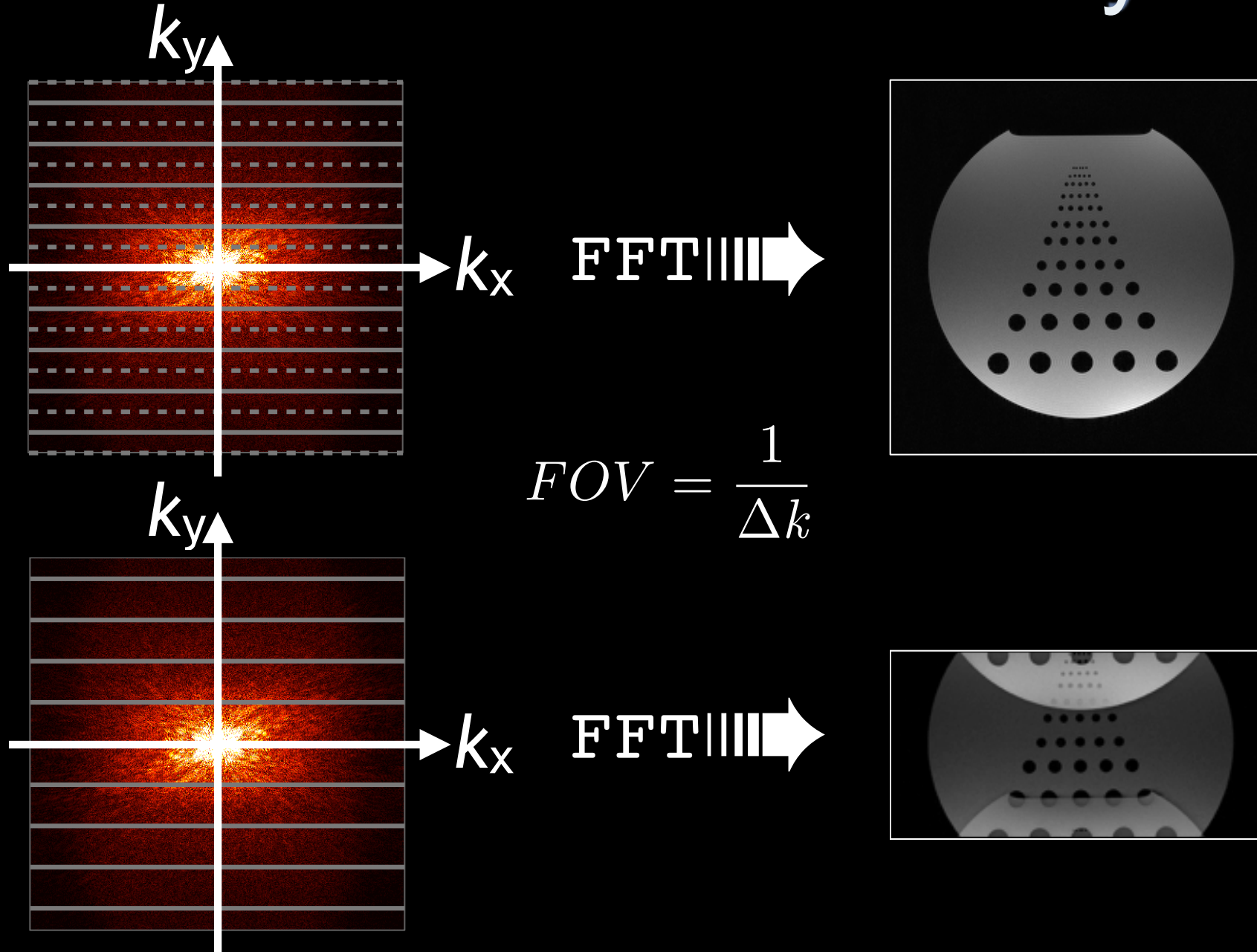
Class Business

- **Thursday (2/23) from 6-9pm**
 - **6:00-7:30pm Groups**
 - **Avanto**
 - Binru Chen, Junjie Chen, Yuhua Chen
 - **Skyra**
 - Jie Fu, Qihui Lyu, Cass Wong
 - **Prisma**
 - Nyasha Maforo, Fadil Ali, Vahid Ghodrati
 - **7:30-9:00pm Groups**
 - **Avanto**
 - Sara Said, Yara Azar, April Pan
 - **Skyra**
 - Timothy Marcum, Diana Lopez, Zhaohuan Zhang
 - **Prisma**
 - Daisong Zhang, Jingwen Yao, Fang-Chu Lin, Andy Vuong
- **BRING THE COMPLETED SCREENING FORM**
- **Re-grade opportunity.**

Lecture #13 - Learning Objectives

- **Understand how to combine data from several receiver channels.**
- **Appreciate how the final image is obtained from the sum over all sampled spatial frequency (Fourier) patterns.**
- **Define how the field-of-view and the number of acquired data points impacts spatial resolution.**
- **Describe the parameters that control the field of view.**
- **Understand the applications of zero padding and windowed reconstructions.**
- **Identify sources of Gibb's ringing.**

Lecture #13 Summary



Uniformly skipping lines in k -space causes *aliasing*.

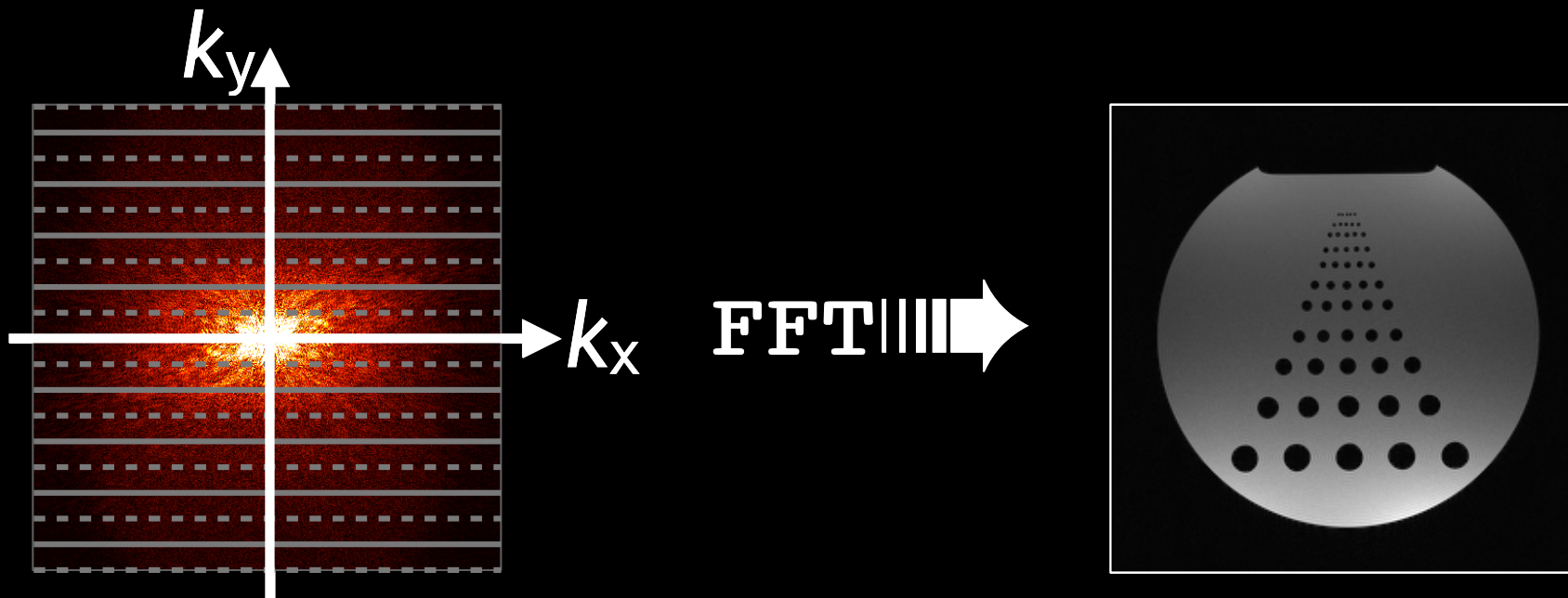
Lecture #13 Summary

$$W_h = \frac{1}{N \Delta k} = \frac{FOV}{N}$$

Fourier Pixel Size

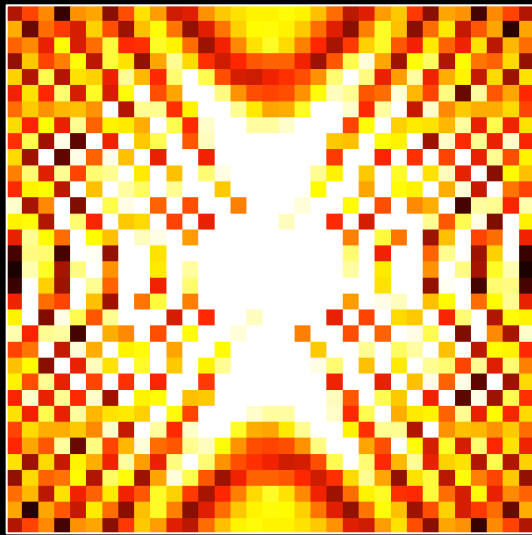
$$W_h \geq \frac{1}{N \Delta k}$$

Fourier Pixel Size
for Windowed
Reconstructions

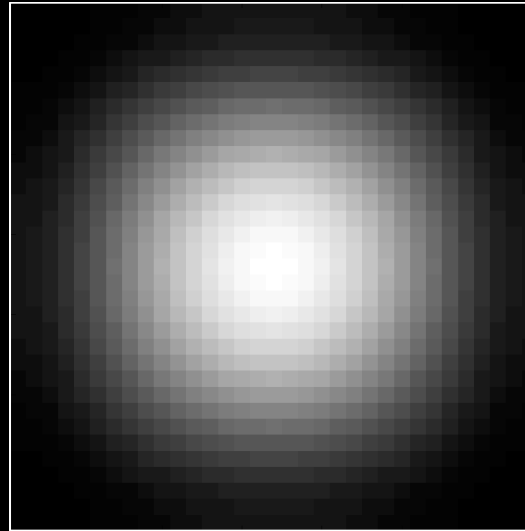


Acquiring fewer high phase encodes decreases resolution.

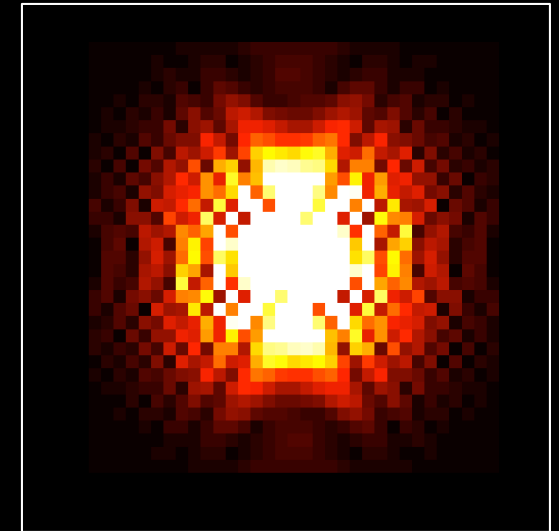
Lecture #13 Summary



●
Dot
Multiply



=



FFT

$$\hat{I}(x) = \Delta k \sum_{n=-N/2}^{N/2-1} S(n\Delta k) w_n e^{i2\pi n\Delta k x}$$

FFT



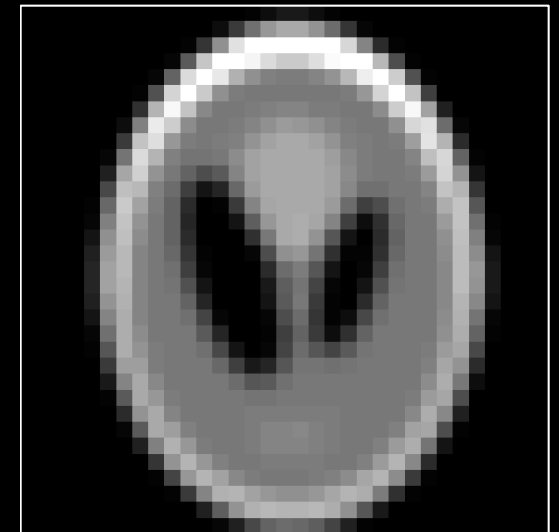
On...
 $|x| < \frac{1}{\Delta k}$

Series
Coefficient

Window
Weight

Spatial
Frequency
Encoding

Fourier
Step-size



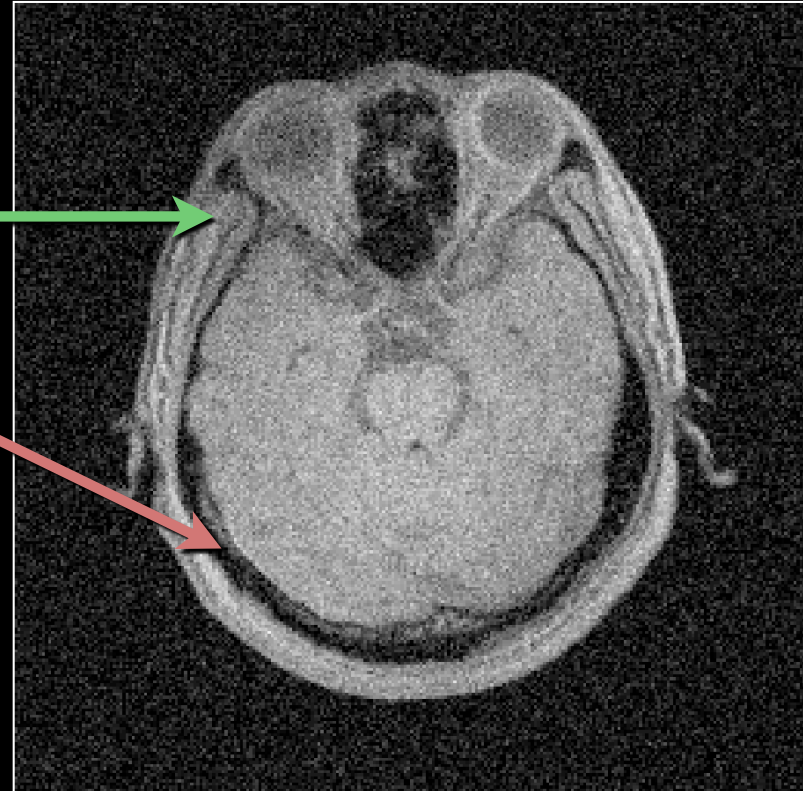
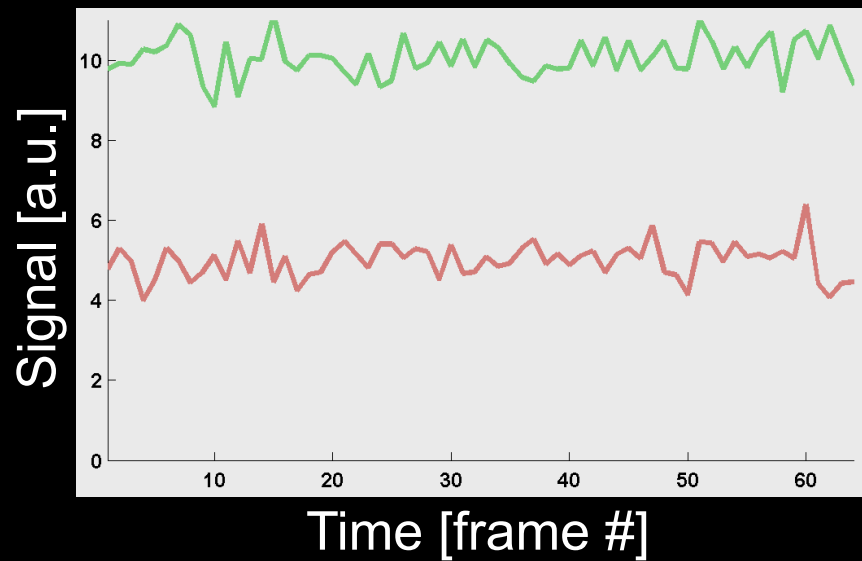
Artifacts

Artifacts

- Aliasing
- Gibb's Ringing
- Noisy spike artifacts
- Noise
- Chemical shift
- Motion Artifacts
- Metal artifacts
- Gradient Non-linearity
- Data clipping
- RF interference
- And more...

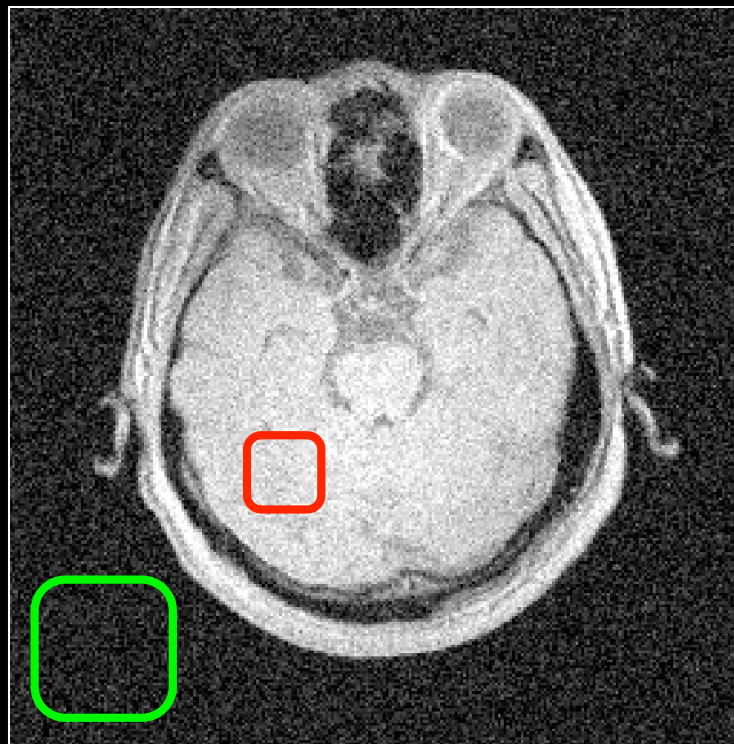
Noise

Signal-to-Noise Ratio



Signal-to-Noise Ratio

- **SNR – Signal-to-noise ratio**
 - **Signal** – Mean signal intensity in ROI. Assumes:
 - 1) Tissue homogeneity
 - 2) Noise is only source of variance
 - **Noise** – SD of background ROI outside object. Assumes:
 - 1) Noise is only source of variance



This method of measuring the SNR is widespread, but imperfect.

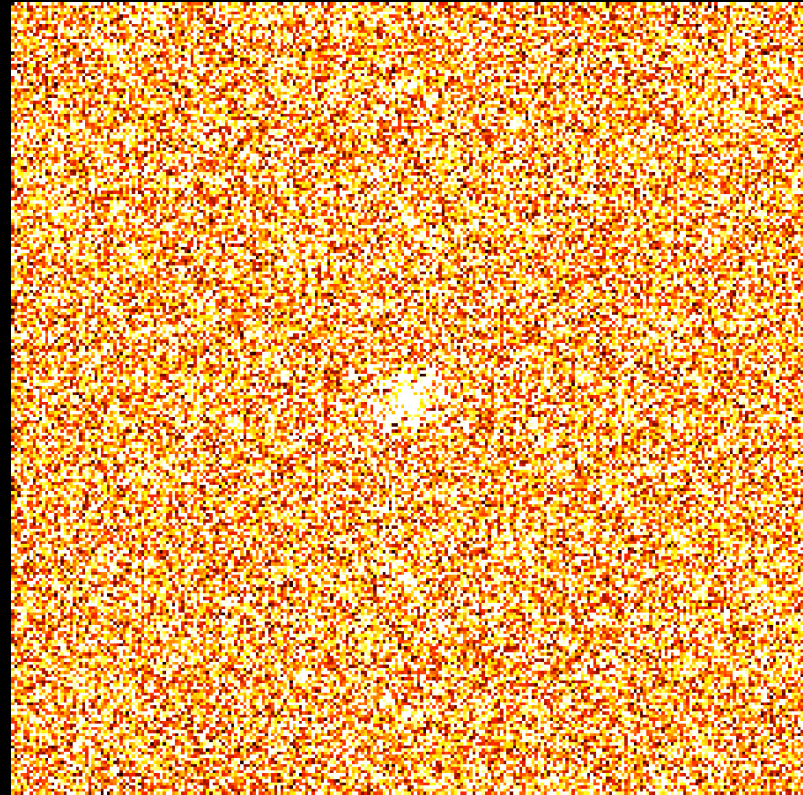
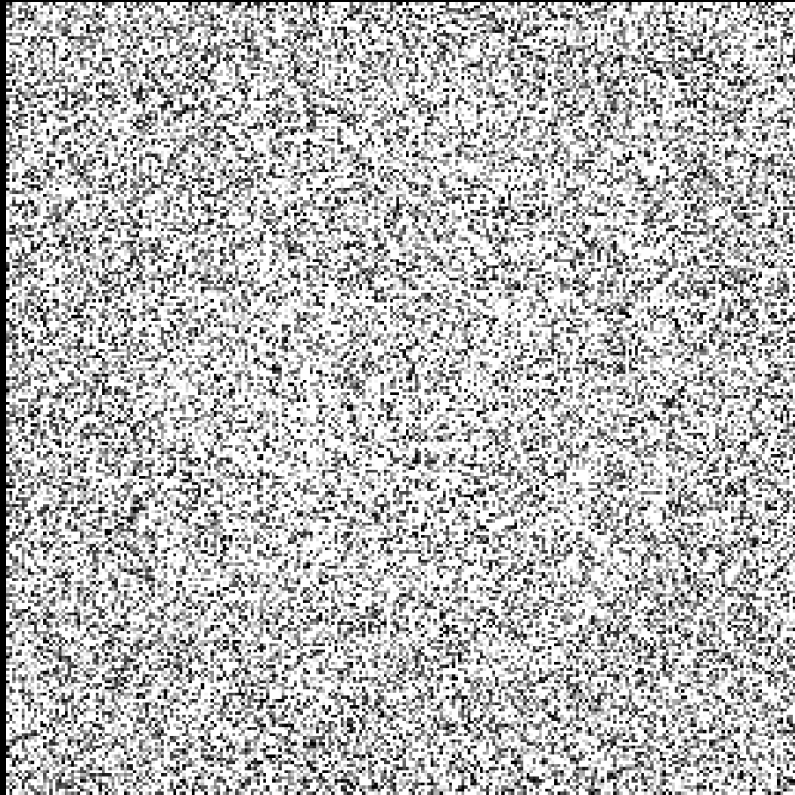
Signal-to-Noise Ratio

$$SNR \triangleq \frac{\text{signal amplitude}}{\text{standard deviation of noise}}$$

- **SNR – Signal-to-noise ratio**
 - **Signal** – Mean signal intensity in ROI
 - **Noise** – Standard deviation of noise
- **CNR - Contrast-to-noise ratio**
 - **Signal Difference**
 - Difference between mean signal intensity in two ROIs
 - **Noise** - Standard deviation of noise

$$CNR \triangleq \frac{\text{signal difference}}{\text{standard deviation of noise}}$$

What is the FT of noise? Noise.



To The Board...

Signal-to-noise Ratio

$$SNR \propto V \sqrt{t}$$

Large Voxels (Low Resolution) \Leftrightarrow High SNR

Long Scan Time \Leftrightarrow High SNR

High Resolution + Fast Imaging Severely Compromises SNR

Signal-to-noise Ratio

$$SNR \propto V \sqrt{t}$$

- **V – Voxel Volume**
 - Slice-thickness (h) x X-res x Y-res
 - X-res = FOV_x / N_{kx}
 - Y-res = FOV_y / N_{ky}
- **t – Data acquisition time**
 - $(N_{kx} \times N_{ky} \times N_{averages}) / \text{bandwidth}$

$$SNR \propto \frac{FOV_x}{N_{kx}} \frac{FOV_y}{N_{ky}} h \sqrt{\frac{N_{kx} N_{ky} N_{avg}}{BW}}$$

Signal-to-noise Ratio

$$SNR \propto V \sqrt{t}$$

- **Example #1**

- Halving slice thickness requires 4x averages to maintain SNR

- **Example #2**

- Doubling slice thickness requires 25% time to maintain SNR

- **Example #3**

- FOV is, in general, fixed.
- To increase resolution we increase N_{k_x} or N_{k_y} .
- This results in increased scan time, but
- The SNR decreases.

$$SNR \propto \frac{FOV_x}{N_{k_x}} \frac{FOV_y}{N_{k_y}} h \sqrt{\frac{N_{k_x} N_{k_y} N_{avg}}{BW}}$$

Parallel Imaging and SNR

$$SNR_{P.I.} = \frac{SNR}{g\sqrt{R}}$$

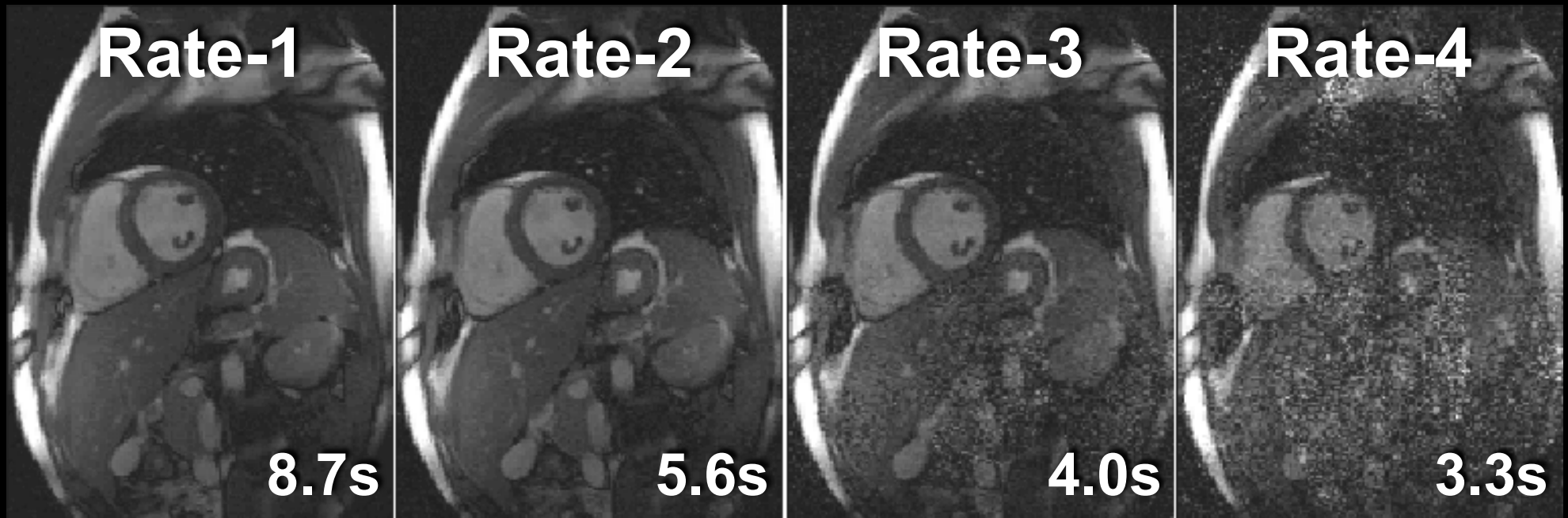
- **g - geometry factor**
 - Loss associated with coil noise-correlation
 - For R=1, g=1
 - For R=2, g=~1.1-1.5
- **R - reduction or acceleration factor**
 - Loss associated with scan time reduction
 - Typically ~1/2 N-coils
- **SNR for P.I. is spatially dependent**
 - Higher in areas of aliasing

Parallel imaging has additional SNR penalties, but decreases scan time.

Impact of Acceleration

High SNR
“Long” Acq.

Low SNR
Short Acq.



P. Kellman (NIH)

High acceleration rates lead to local noise amplification.

Readout Bandwidth

Receiver Bandwidth

- **Receiver Bandwidth (RBW, Δf)**
 - The range of frequencies across the FOV
 - \pm kHz [range across FOV]
 - Alternately range of frequencies per pixel
 - Pixel bandwidth [Hz/pixel]
 - ...during *readout*.



$f_0 - \Delta f/2$ f_0 $f_0 + \Delta f/2$

$$\Delta f = \frac{1}{2} \frac{\gamma}{2\pi} G_x \cdot FOV_x$$

User can pick 2 of 3 (Δf , G_x , FOV_x)

Temporal Nyquist Sampling Requires: $\Delta t = \frac{1}{2\Delta f}$

k-space Nyquist Sampling Requires: $\Delta k_x = \frac{\gamma}{2\pi} G_x \Delta t$



$$\Delta k_x = \frac{1}{FOV_x}$$

$$N_x \cdot \Delta k_x = \frac{N_x}{FOV_x} = \frac{1}{\Delta x}$$

Receiver Bandwidth

- **High Receiver Bandwidth (RBW, Δf)**
 - Stronger gradients
 - Larger range of frequencies across the FOV (or pixel)
 - Less chemical shift (smaller freq. difference per pixel)
 - Lower SNR (shorter acquisition time)
 - Shorter TE (move across k -space faster)



$$\Delta f = \frac{1}{2} \frac{\gamma}{2\pi} G_x \cdot FOV_x$$

User can pick 2 of 3 (Δf , G_x , FOV_x)

Temporal Nyquist Sampling Requires: $\Delta t = \frac{1}{2\Delta f}$

k -space Nyquist Sampling Requires: $\Delta k_x = \frac{\gamma}{2\pi} G_x \Delta t$



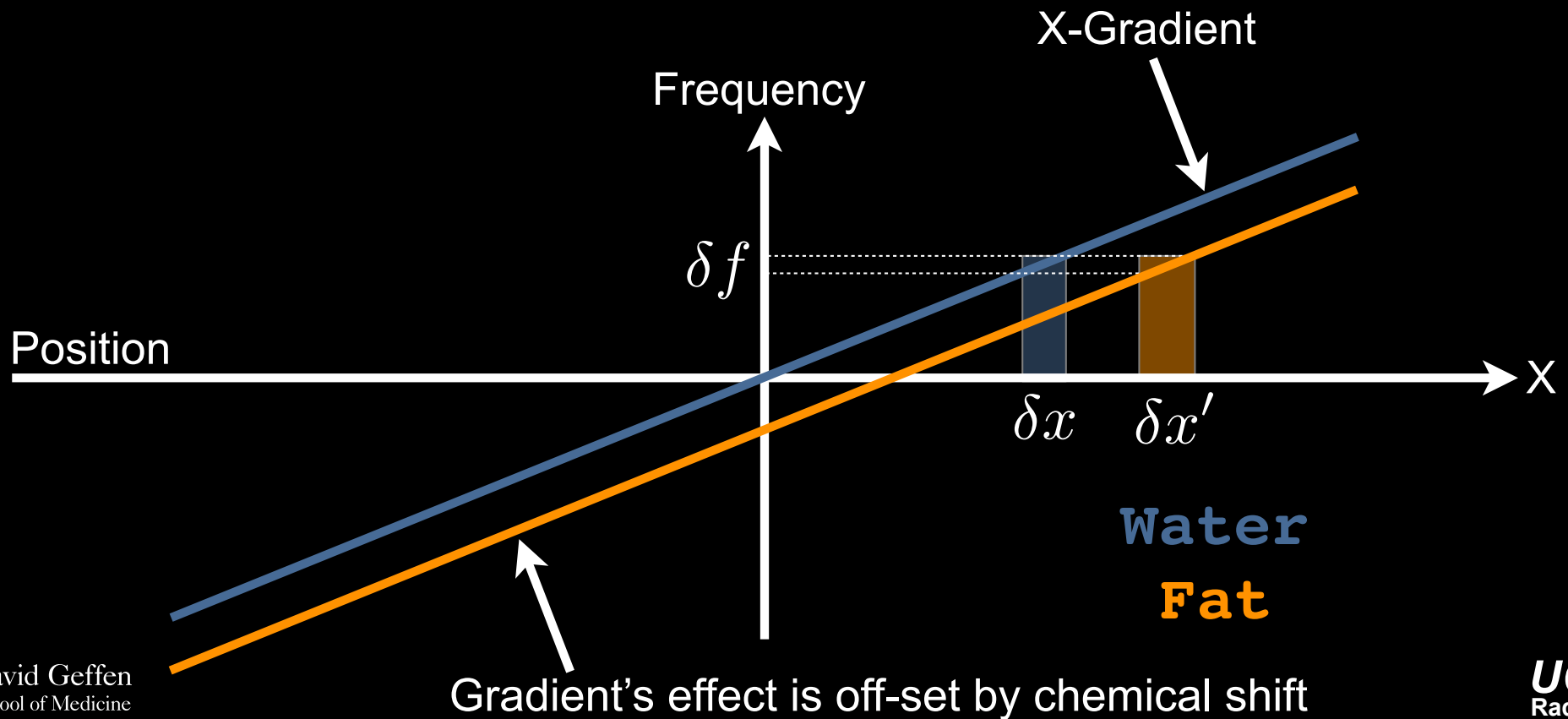
$$\Delta k_x = \frac{1}{FOV_x}$$

$$N_x \cdot \Delta k_x = \frac{N_x}{FOV_x} = \frac{1}{\Delta x}$$

Chemical Shift

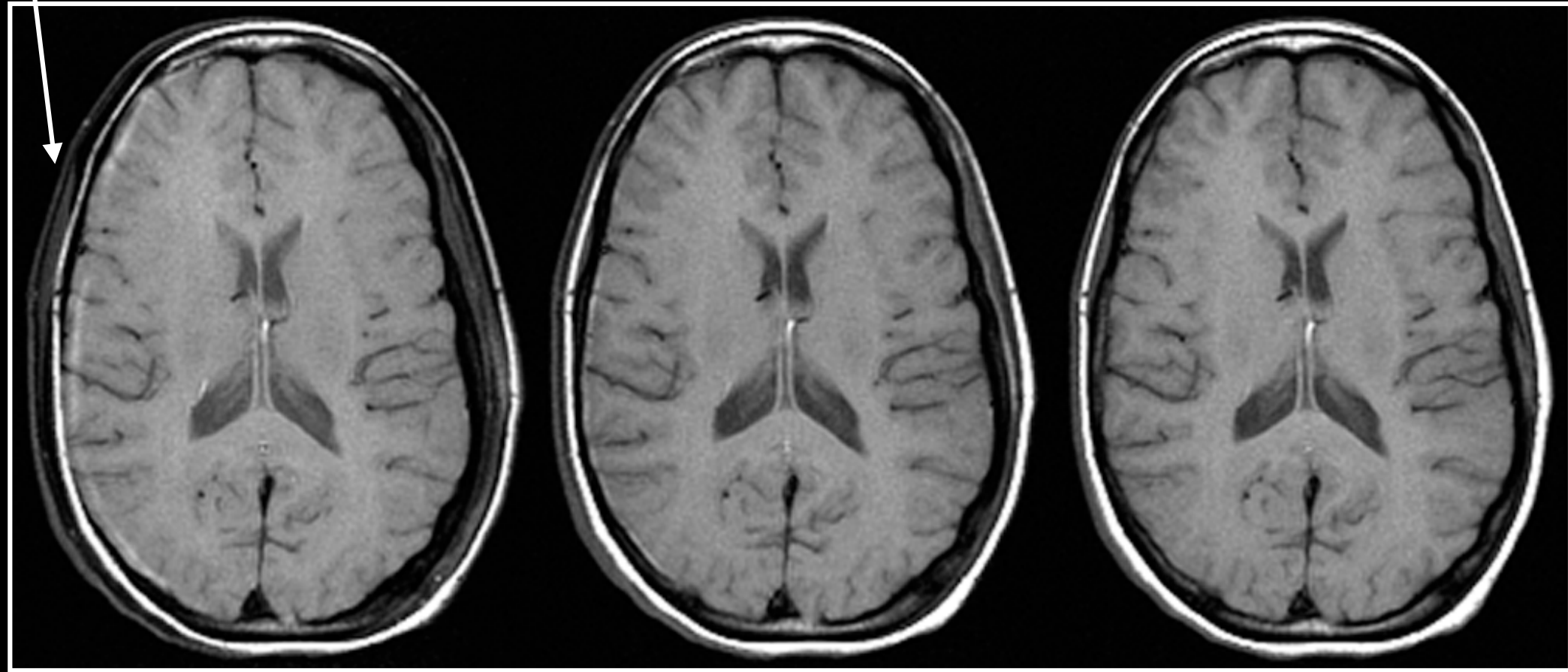
Chemical Shift Artifact

- Gradients provide linear variation in frequency
- Fat has a 3.5ppm lower frequency than water
 - -222Hz @ 1.5T and -444Hz @ 3.0T
- Scanner detects frequency, then maps to position
- Scanner “assumes” everything is water, therefore fat (lower frequency) is interpreted as lower frequency (shifted position) water.



Chemical Shift Artifact

← Readout



$BW = \pm 4\text{kHz}$

$BW = \pm 8\text{kHz}$

$BW = \pm 16\text{kHz}$

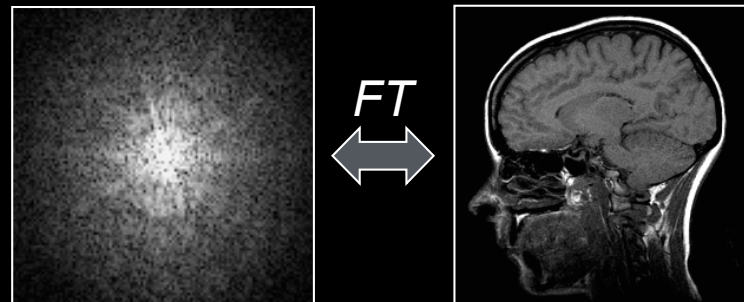
Solution

- **High bandwidth pulse sequences**
 - **Degrades SNR (reduces acquisition time)**
 - **Reduces chemical shift artifact**
- **Fat saturation pulses/techniques**

Motion Artifacts

Motion in MRI

- **Motion is responsible for a corruption in spatial localization in PE direction, resulting in a blurring and/or ghosting artifacts**
- **Typical types of motion in body**
 - Patient motion
 - Respiration
 - Cardiac motion and vascular pulsation
 - Peristalsis & bowel gas
- **Recording signal in k -space not image domain!**



Motion Artifacts - Part I

Slow/Bulk Motion

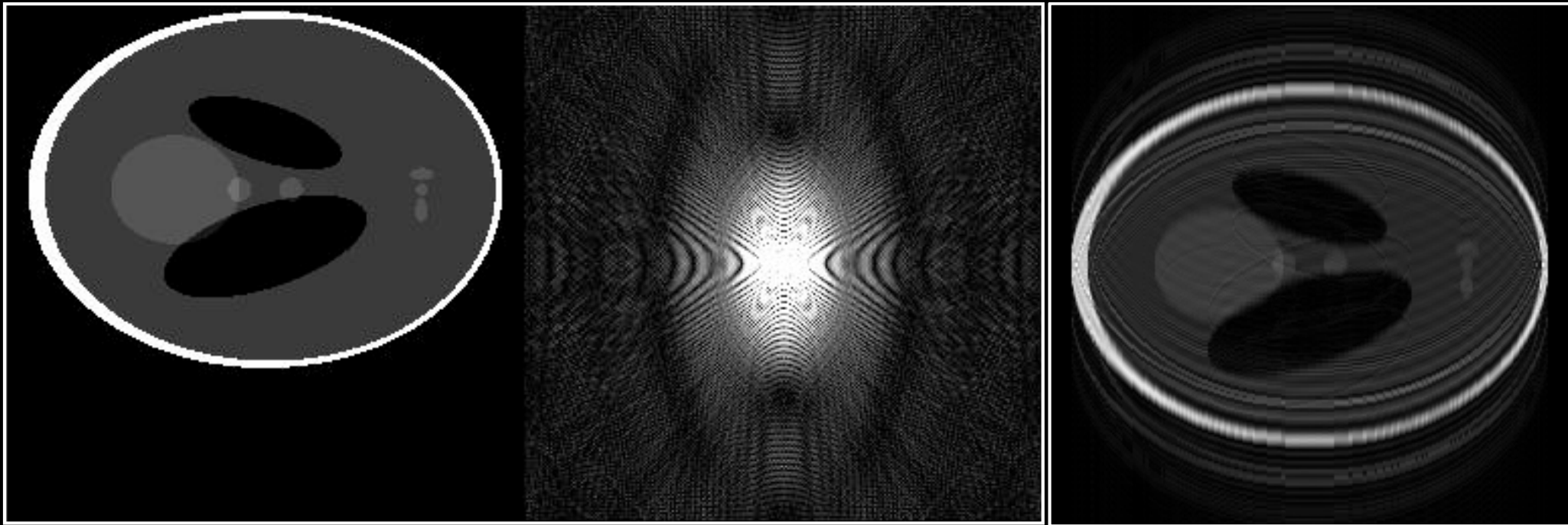


Examples:

- Respiration
- Feet motion
- Swallowing

Motion Artifacts - Part I

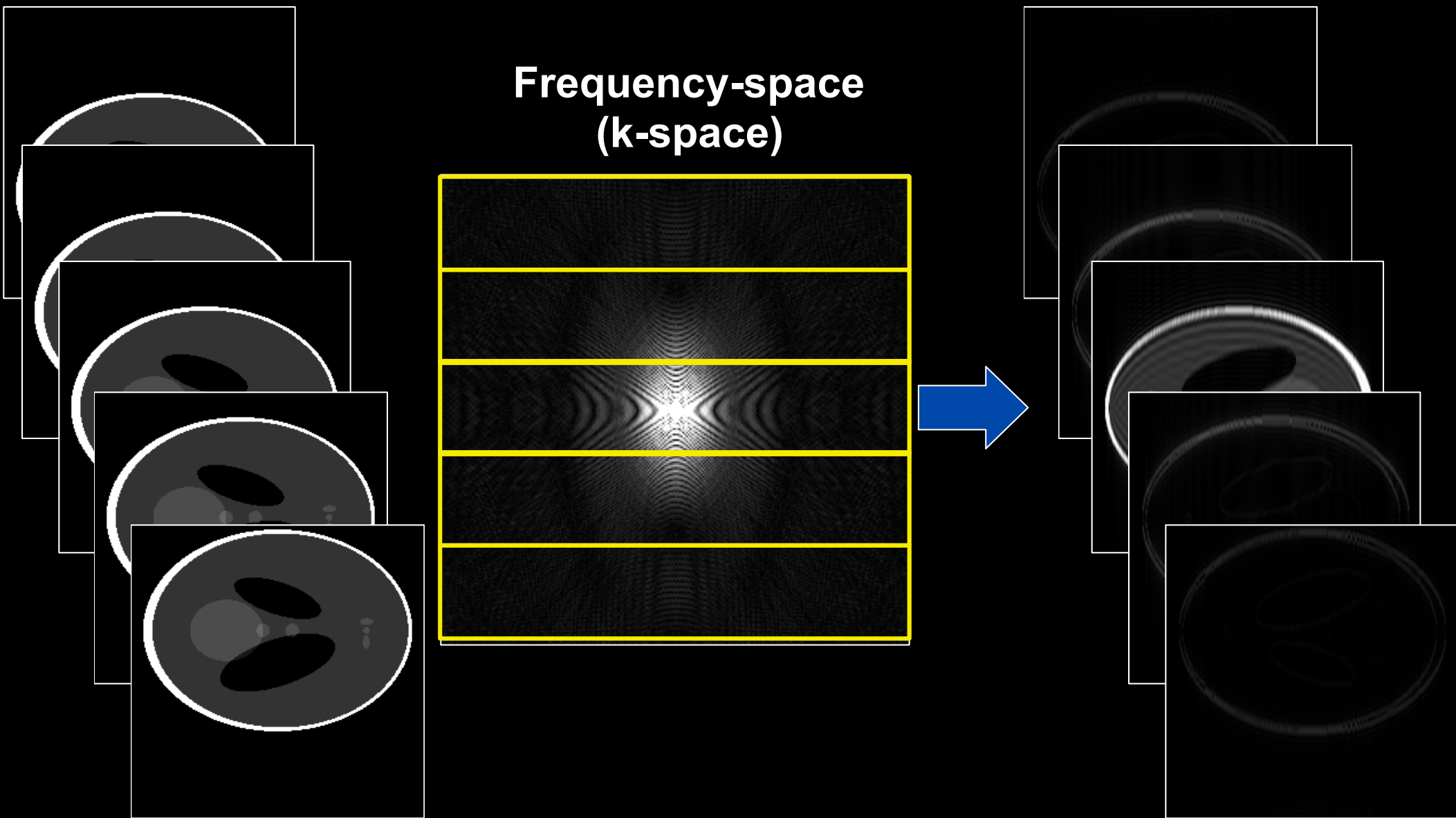
Slow/Bulk Motion



MR Image with
Motion Artifacts

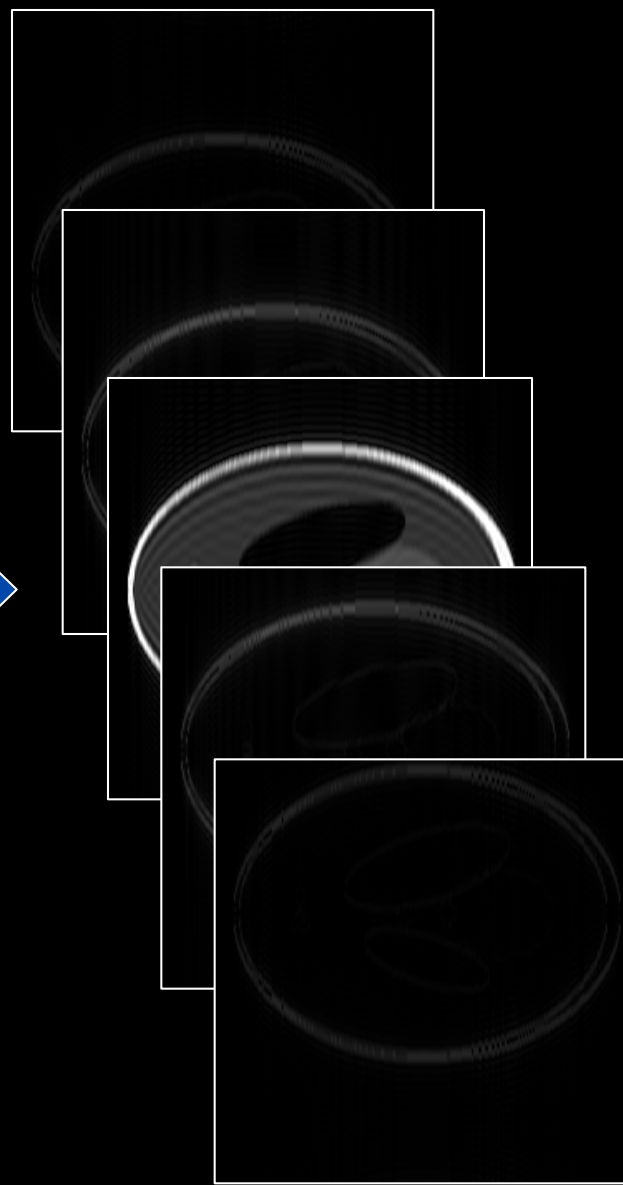
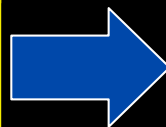
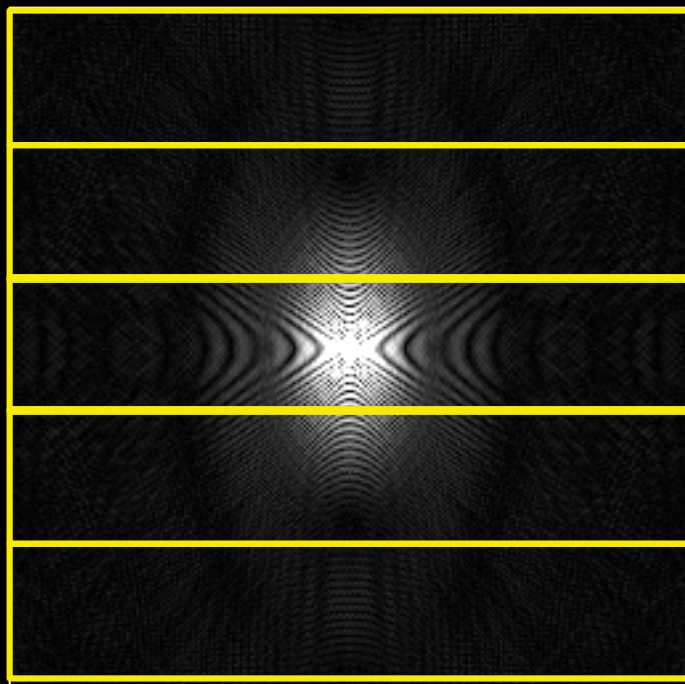
Fourier
Transform

Motion Artifacts - Part I



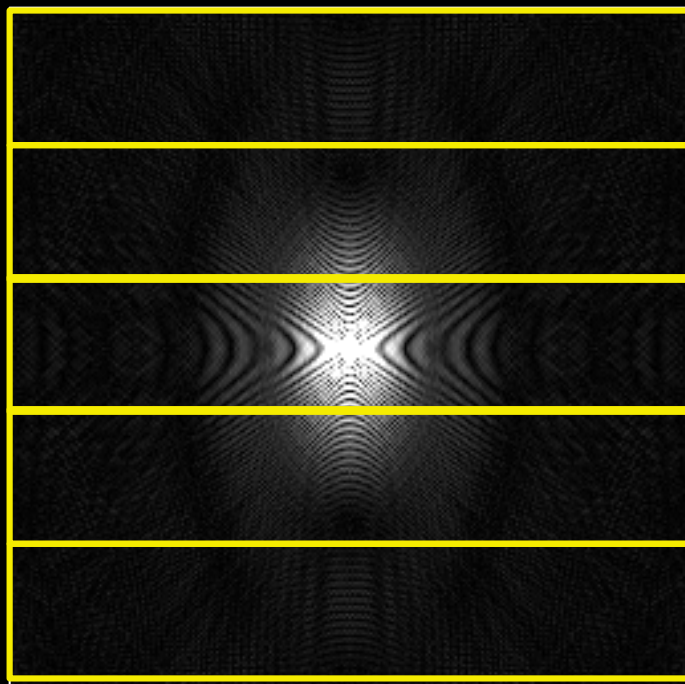
Motion Artifacts - Part I

Frequency-space
(k-space)

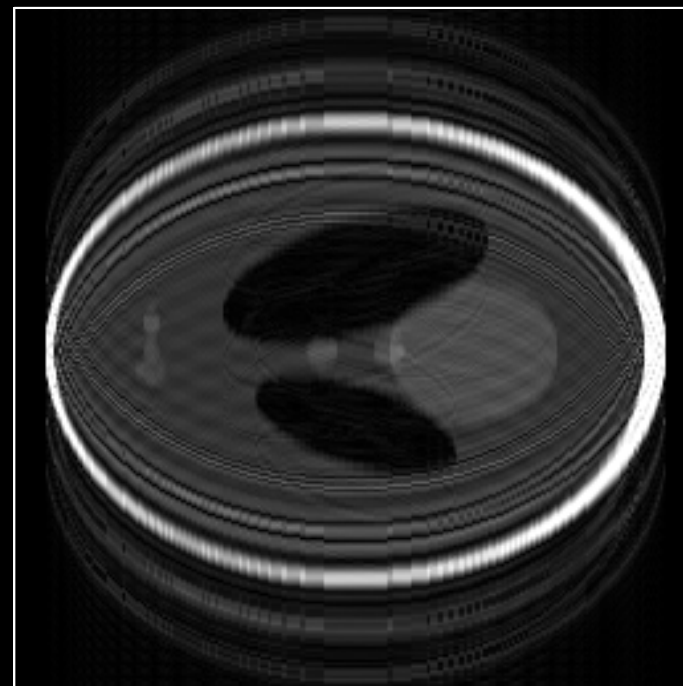


Motion Artifacts - Part I

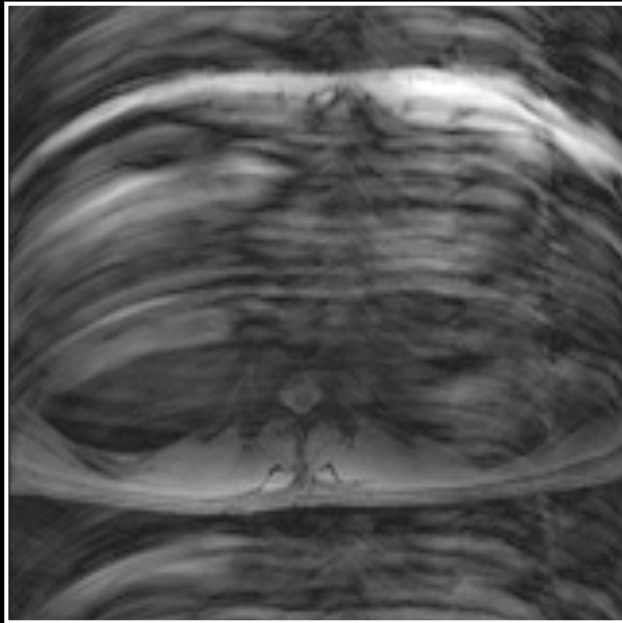
Frequency-space
(k-space)



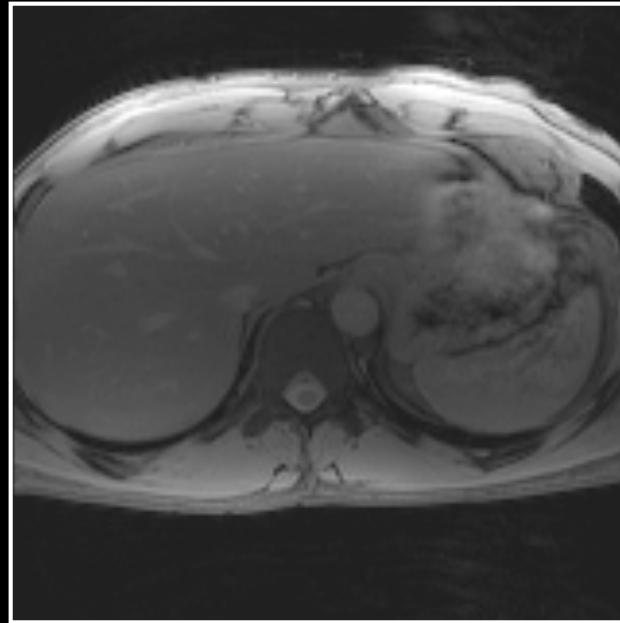
MR Image with
Motion Artifacts



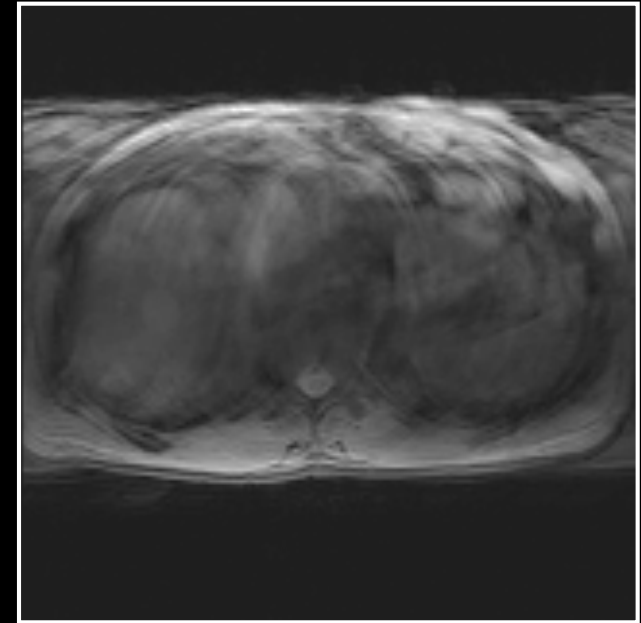
Breathing (Motion) Artifacts



Free Breathing



Breath held



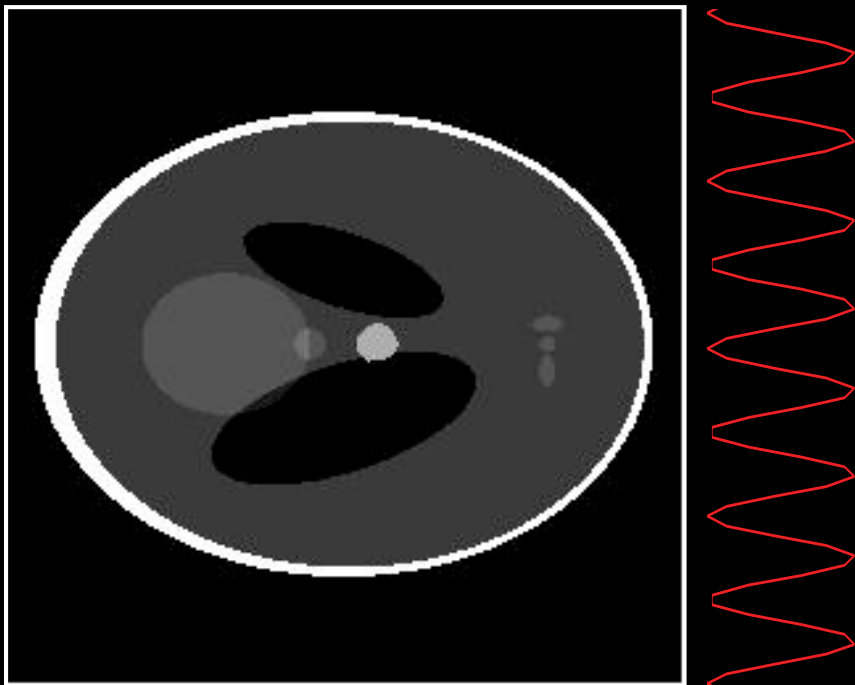
Free Breathing

Remedies (and Penalties)

- **Possible solutions?**
 - **Breath-holding**
 - **Respiratory gating**
 - **Reduces body movements**
 - **Patient coaching, physical restraint, sedation**
- **Disadvantages**
 - **Requires fast sequences**
 - **Increases the scan time; restricts the available TRs**
 - **Patients acceptance and discomfort**

Motion Artifacts - Part II

Periodic Motion



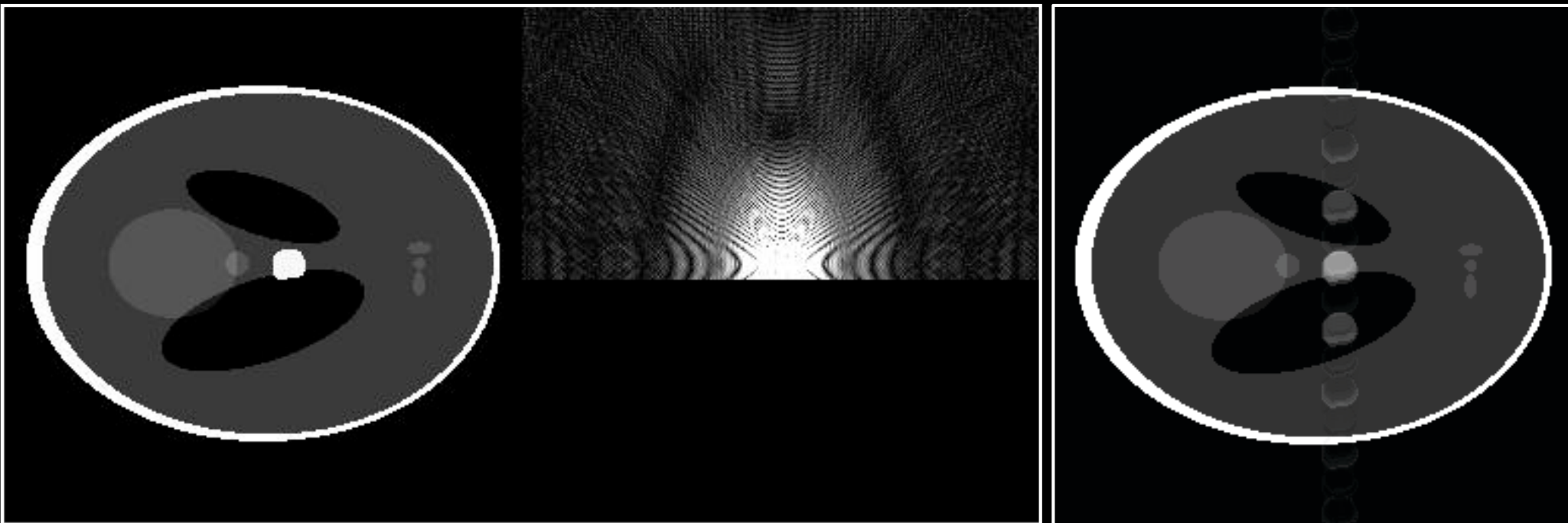
Examples:

- Aortic Pulsation
- Arterial Pulsation

Motion Artifacts - Part II

Periodic Motion

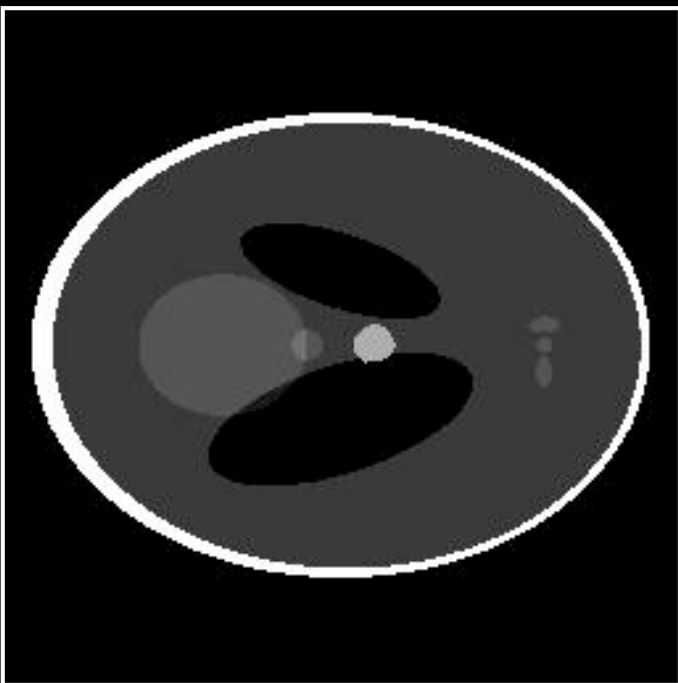
MR Image with
Motion Artifacts



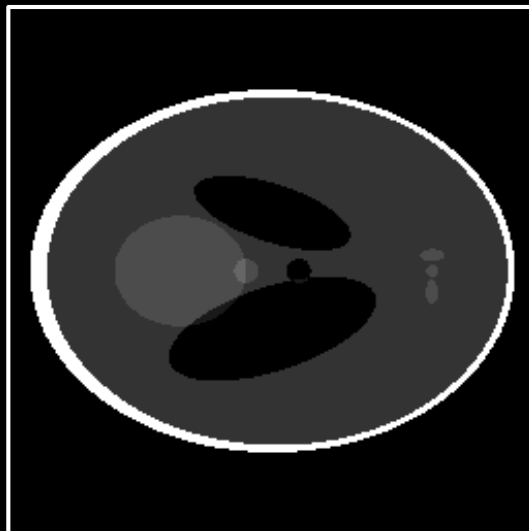
Fourier
Transform

Motion Artifacts - Part II

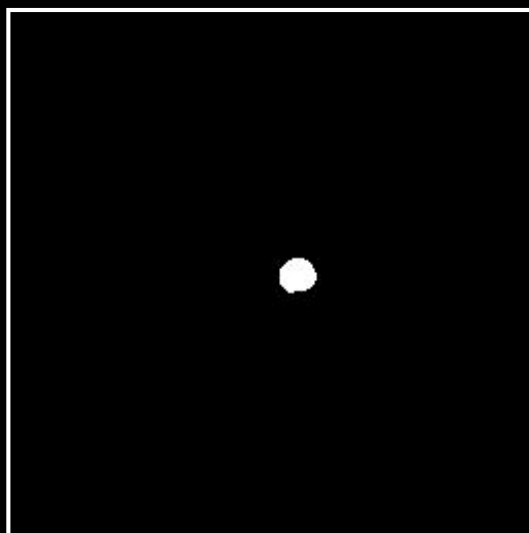
Periodic Motion



Static Part

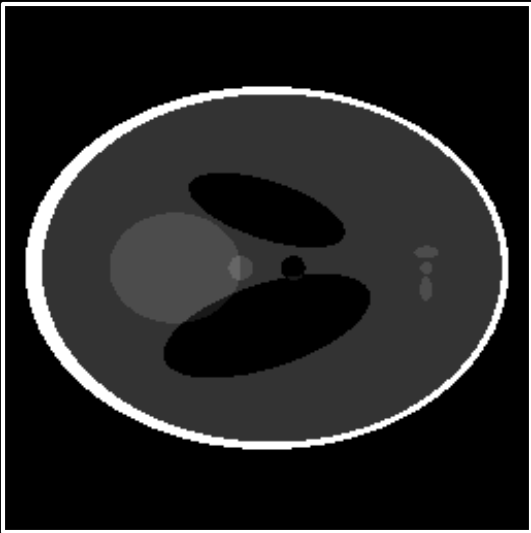


Moving Part

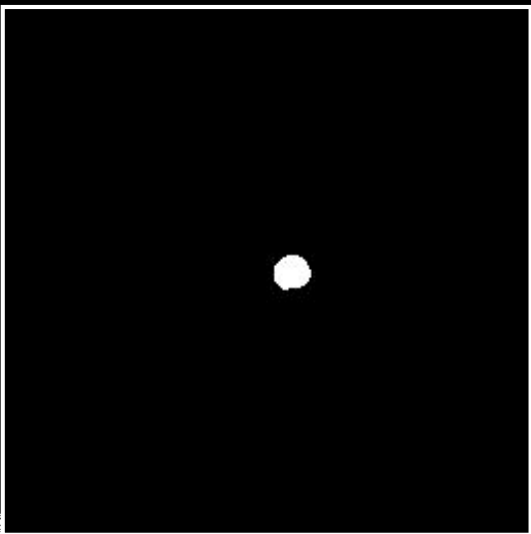


Motion Artifacts - Part II

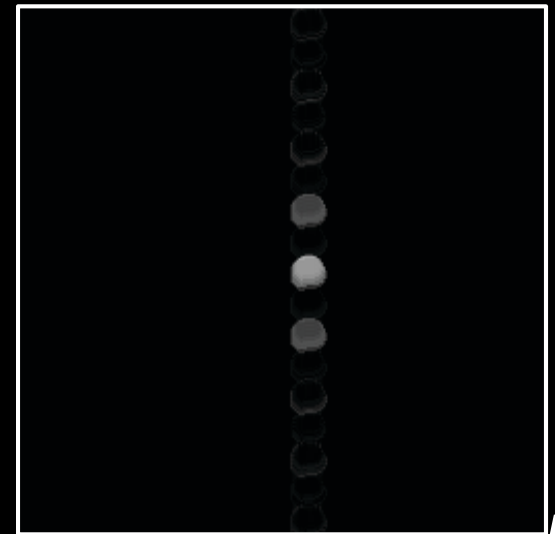
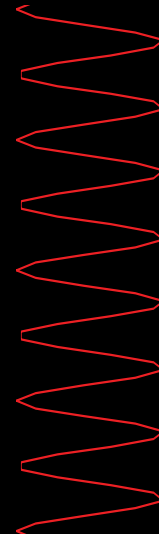
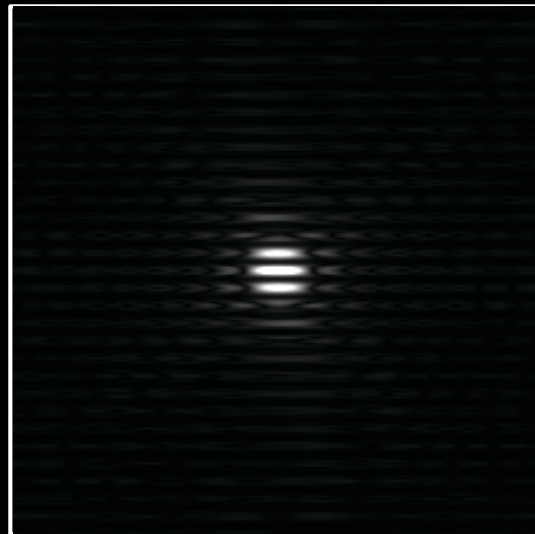
Static Part



Moving Part

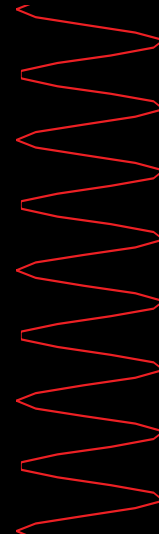
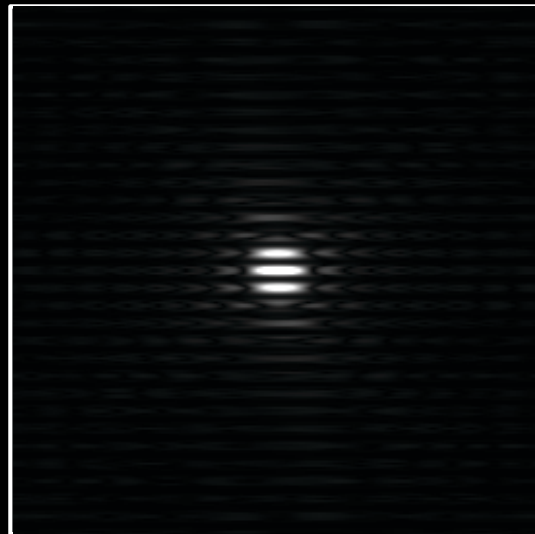
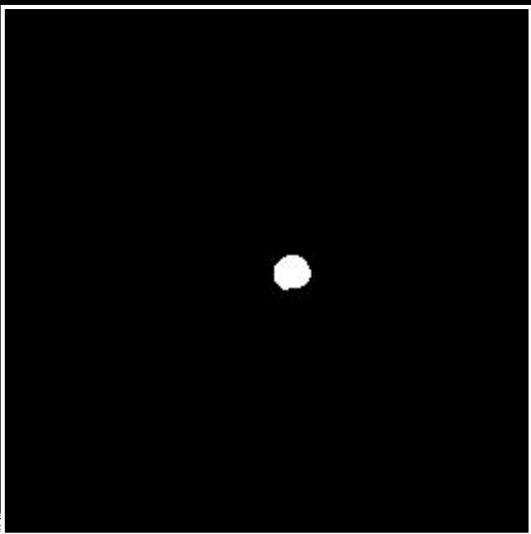


Fourier Transform

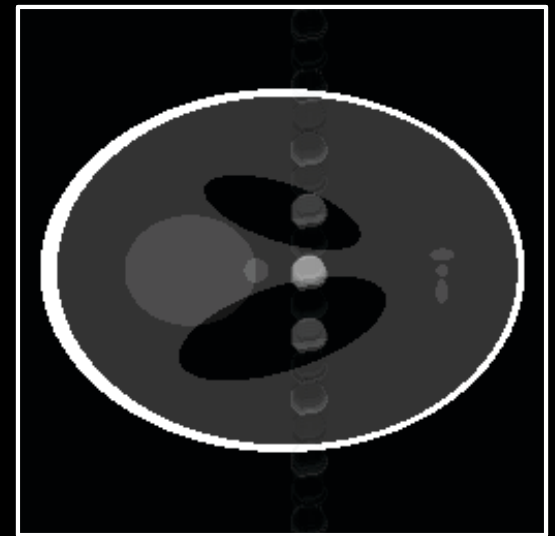


Motion Artifacts - Part II

Moving Part

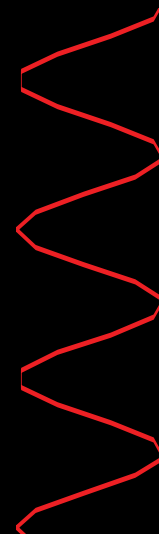
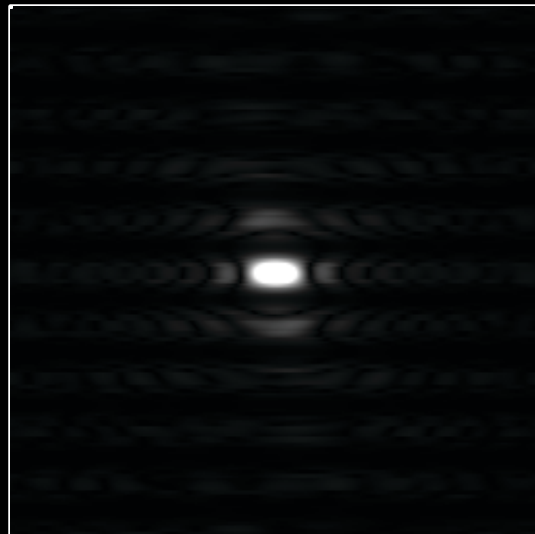
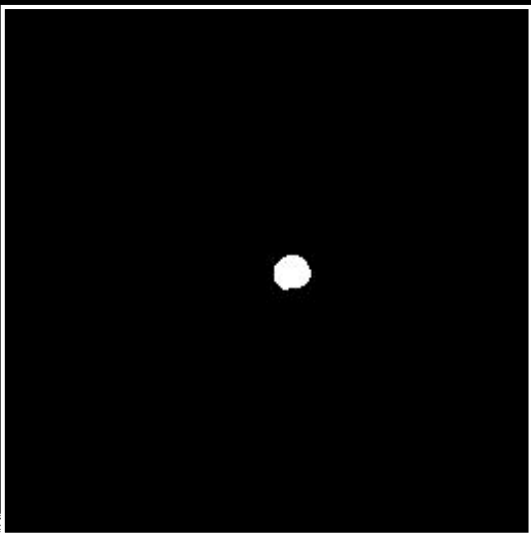


MR Image with Ghosting Artifacts

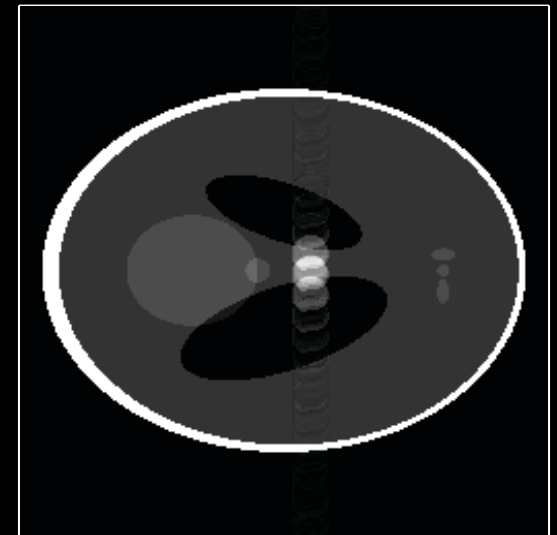


Motion Artifacts - Part II

Moving Part



MR Image with Ghosting Artifacts

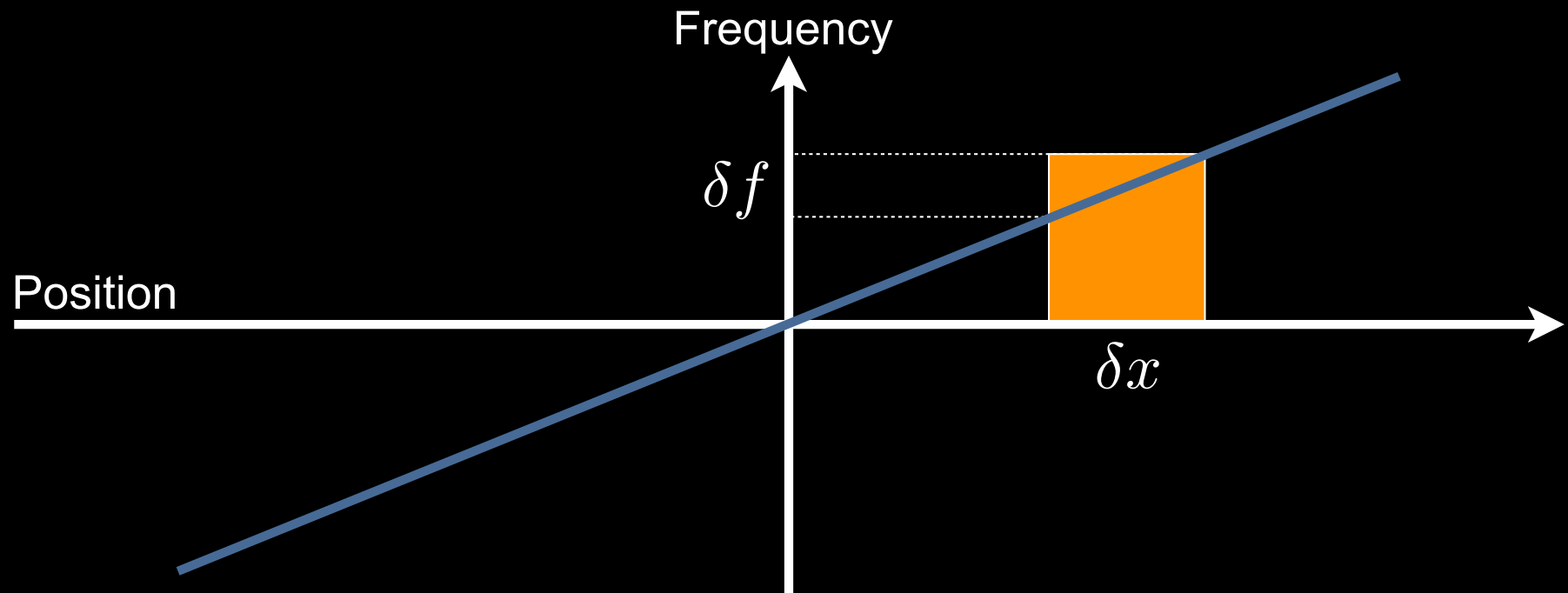


Remedies (and Penalties)

- **Possible solutions?**
 - Cardiac gating \pm segmented imaging.
 - Signal suppression of moving tissues.
 - Swapping phase-encoding and frequency encoding directions
- **Disadvantages**
 - Increases scan time.
 - Increases TR (due to preparation pulses).
 - Only shifts the artifacts.

Metal Artifacts

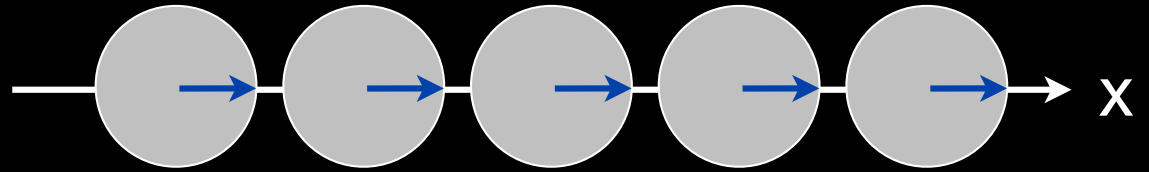
Frequency Encoding Artifacts



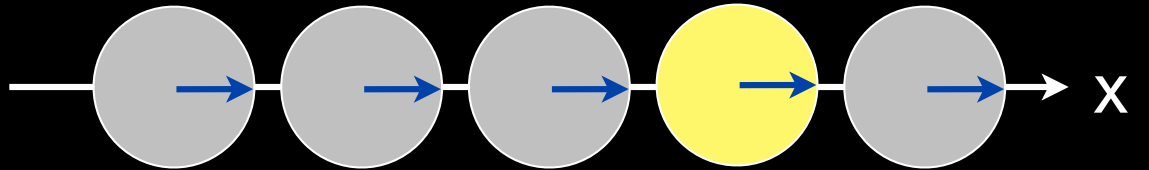
$$\delta x = \frac{2\pi\delta f}{\gamma G_x}$$

Severe Off-Resonance

Normal Spins

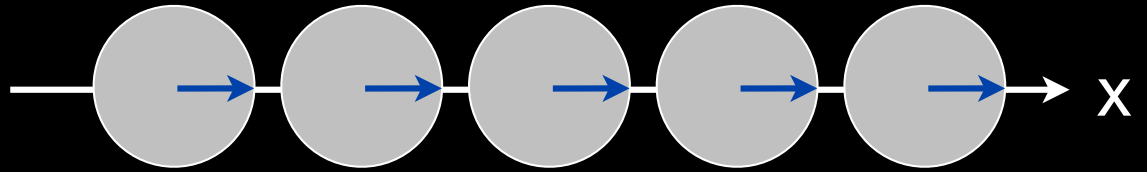


Off-Resonant Spin

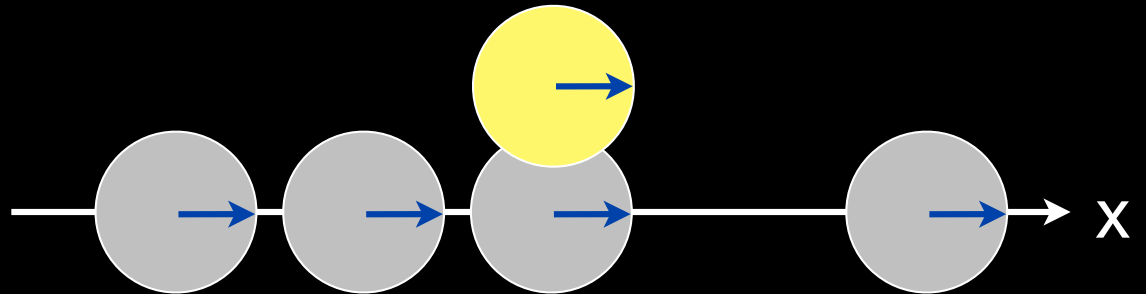


Severe Off-Resonance

Normal Spins



Off-Resonant Spin



"Pile-up"

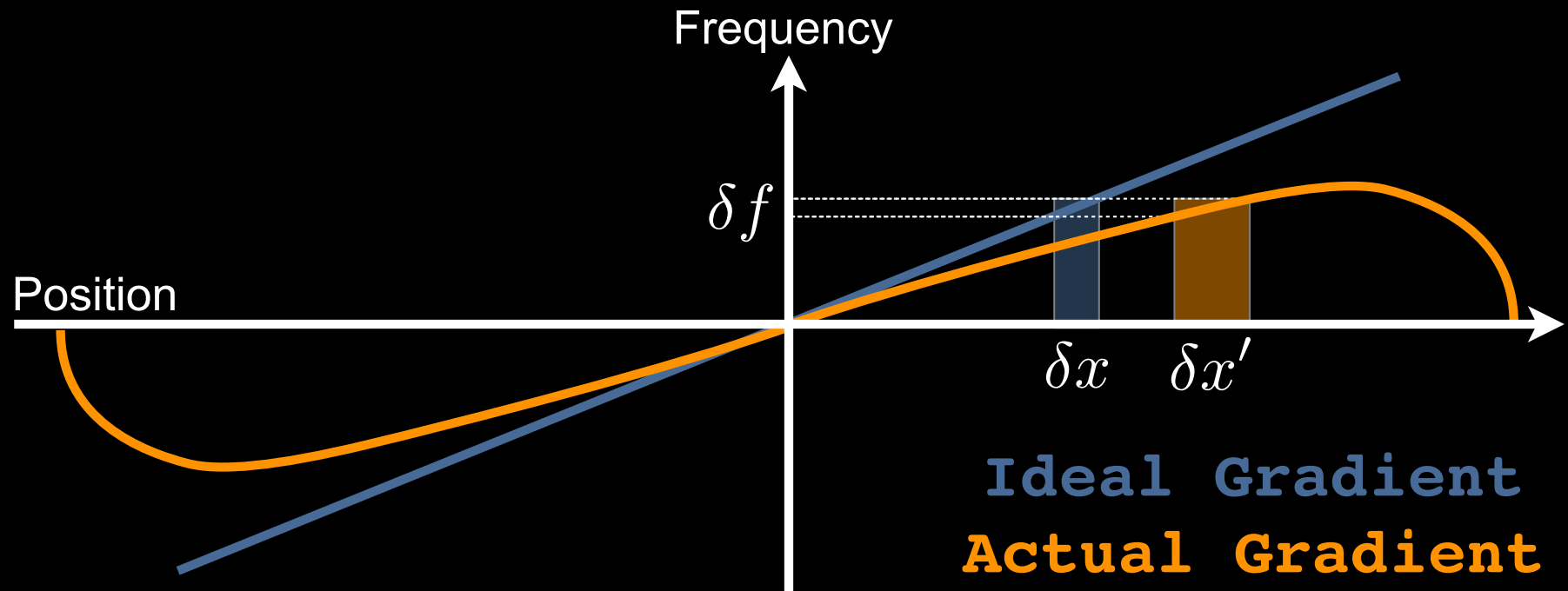
Signal Loss

Gradient Non-linearity

Gradient Non-linearity

- **Basic assumption in MRI is that the z-component of the B-field created by the gradient coils varies linearly with x, y, or z over the FOV.**
- **Higher gradient amplitudes and slewrates can be achieved by compromising on spatial linearity.**
- **Gradient non-linearity causes geometric and intensity distortions.**

Gradient Non-linearity

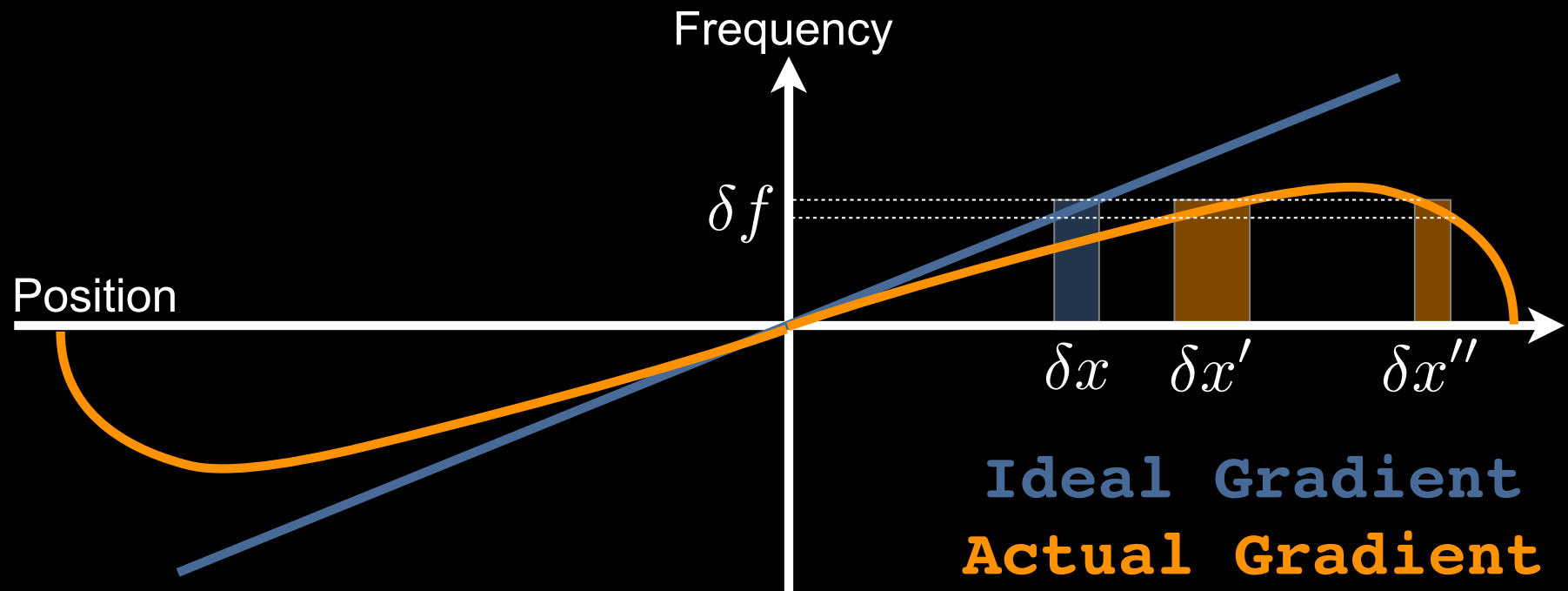


The mapping between position (x) and frequency (f) becomes non-linear.
The mapping between Δx and Δf becomes non-linear.

Gradient Non-linearity



Gradient Roll-off



Spins outside the desired FOV, if excited and near to the coil can become spatially mis-encoded.

Solution

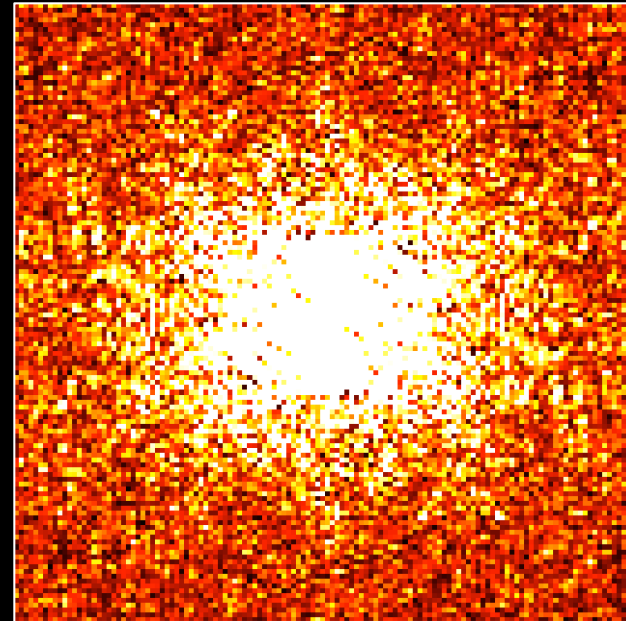
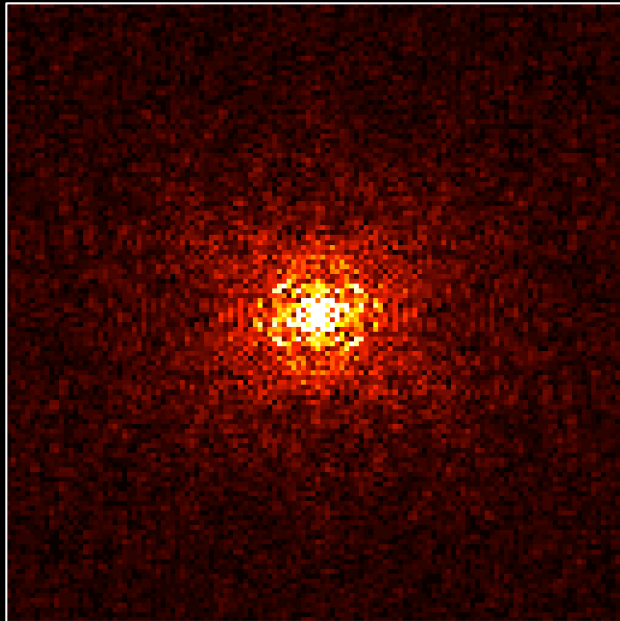
- **Image warping parameters that are system specific and applied to all images.**
 - Works well qualitatively.
 - Can be problematic quantitatively.
- **Transmit (B_1) coils with coverage over smaller volumes.**
- **Receiver coil (B_r) sensitivity only over ROI.**

Data Clipping

Data Clipping

- **Received signal saturates the receiver.**
- **Peak signal usually in the middle of k -space, therefore lose low spatial frequency information:**
 - **Contrast**
 - **Intensity**
- **Pre-scan procedure usually avoids data clipping by adjusting receiver gains.**

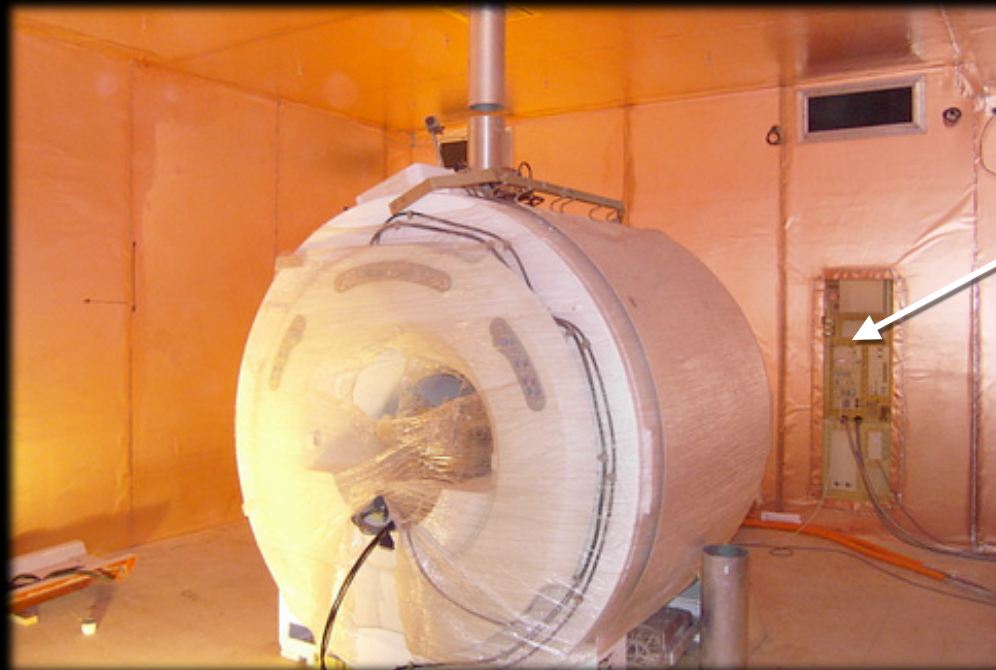
Data Clipping



Radio Frequency Interference

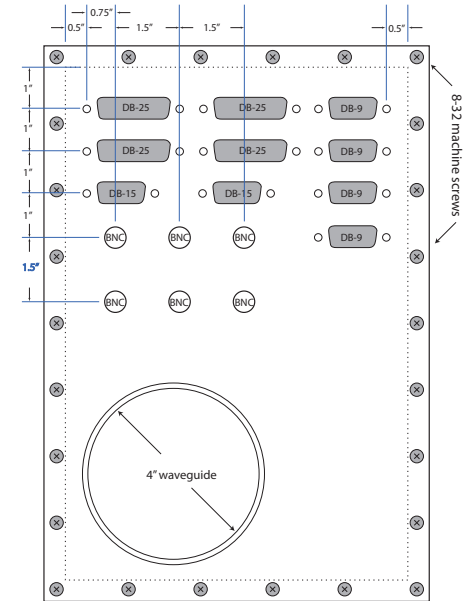
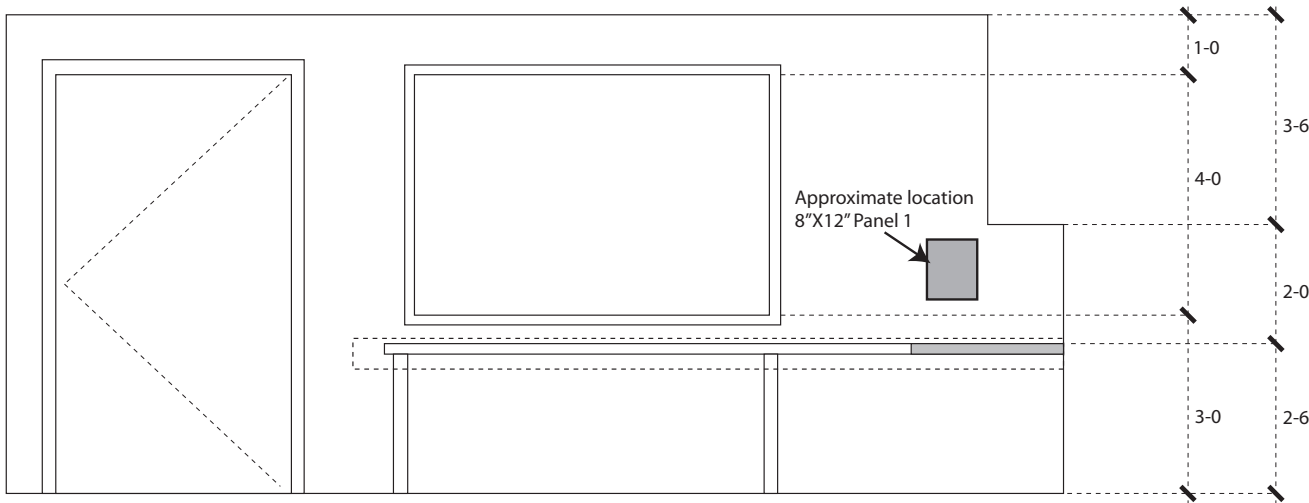
RF Shielding

- **RF fields are close to FM radio**
 - ^1H @ 1.5T \Rightarrow 63.85 MHz
 - ^1H @ 3.0T \Rightarrow 127.71 MHz
 - KROQ \Rightarrow 106.7 MHz
- **Need to shield local sources from interfering**
- **Copper room shielding required**

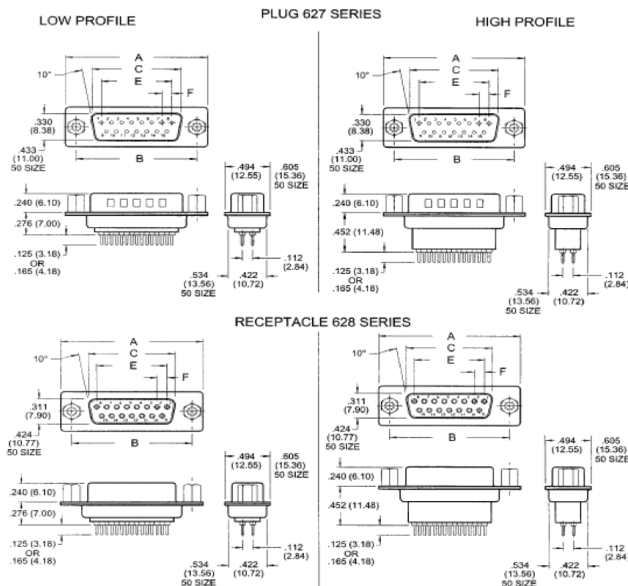


Penetration Panel

Penetration Panel

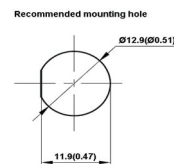


Panel 1 - between scan room and console room
8" X 12" penetration (panel size is 9" X 13")



NUMBER OF CONTACTS	A		B		C		C		E		F	
	Inch	(mm)	Inch	(mm)	Inch	(mm)	Inch	(mm)	Inch	(mm)	Inch	(mm)
9	1.214	(30.84)	.984	(24.99)	.667	(16.82)	.640	(16.26)	.432	(10.97)	.108	(2.74)
15	1.545	(39.24)	1.312	(33.32)	.994	(25.25)	.967	(24.56)	.756	(19.20)	.108	(2.74)
25	2.088	(53.04)	1.852	(47.04)	1.534	(38.98)	1.508	(38.30)	1.304	(33.12)	.109	(2.76)
37	2.730	(69.34)	2.500	(63.50)	2.182	(53.08)	2.156	(54.76)	1.956	(49.88)	.109	(2.76)
50	2.640	(67.05)	2.406	(61.11)	2.080	(52.83)	2.054	(52.17)	1.740	(44.20)	.109	(2.76)

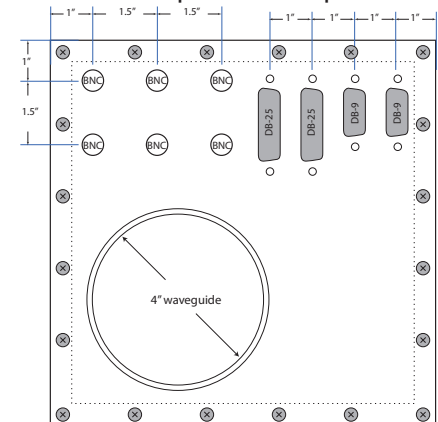
DB cutout dimensions



BNC Hole Dimensions

Penetration panels should be made from 16 ga. steel or aluminum

Location of Panel 2 is to be in the proximity of the Siemens penetration panel.



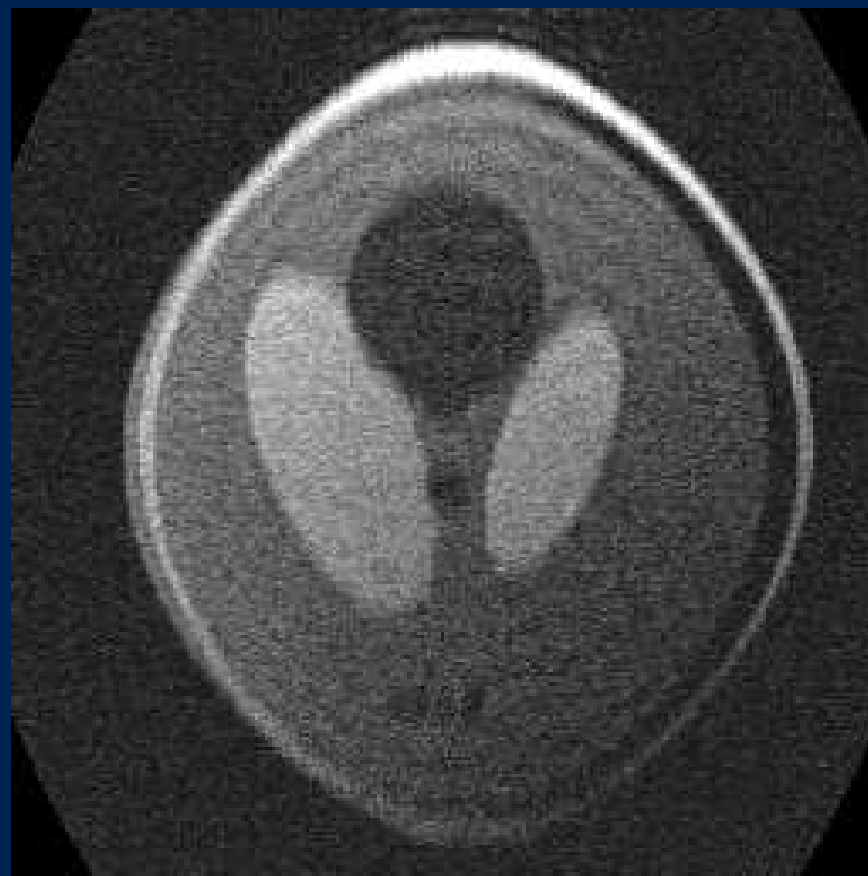
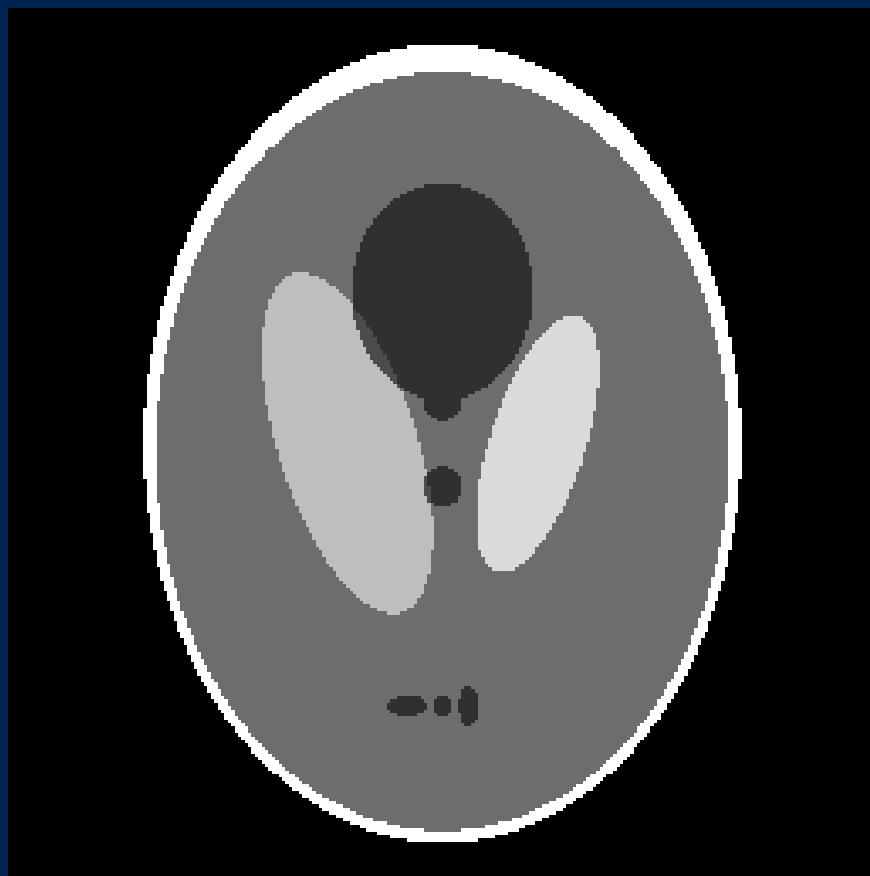
8" Penetration (panel size is 9")
Panel 2 - between equipment room and scan room

Radiofrequency Interference

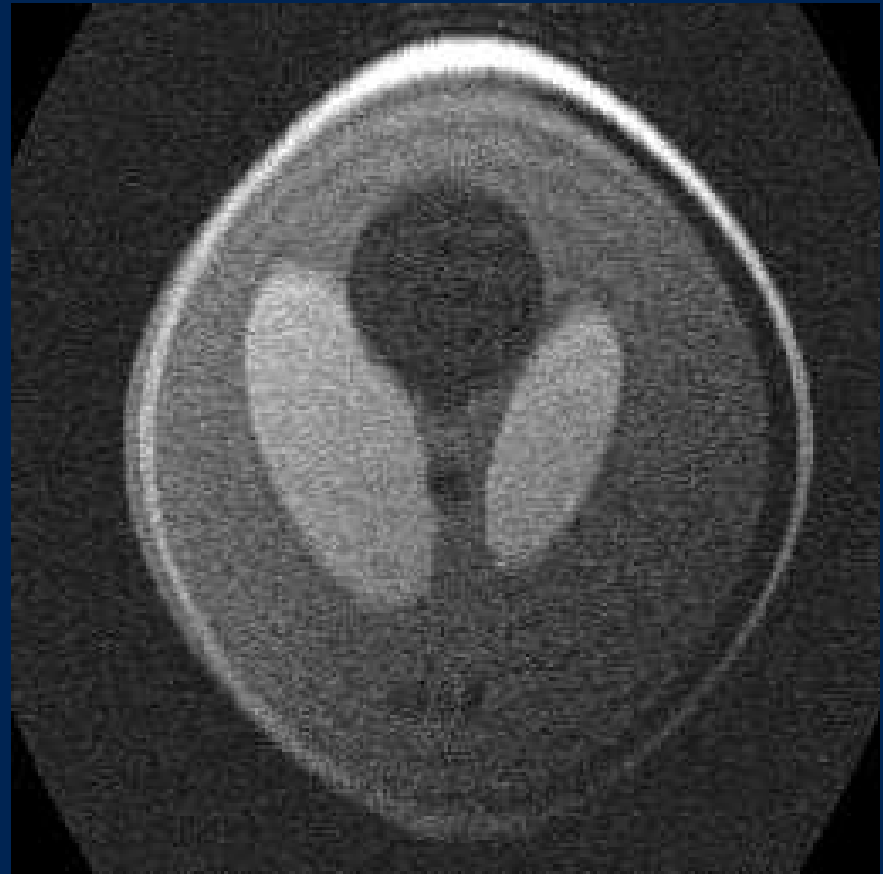
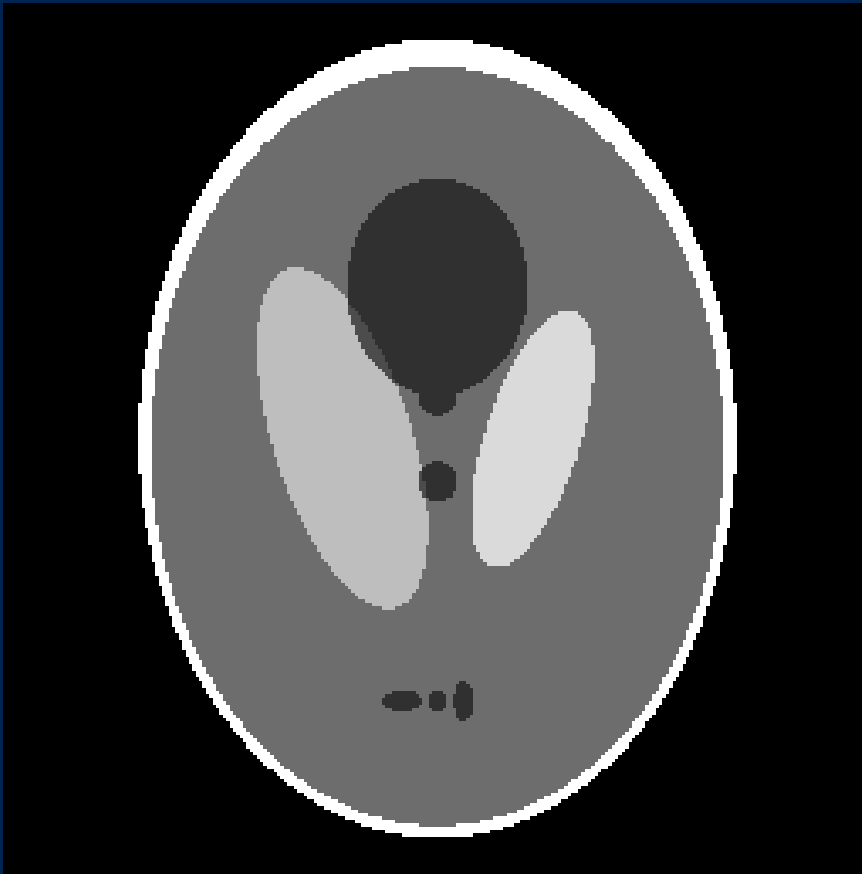
- **Caused by RF leak**
 - Scanner Door is Open
 - Wires running in/out of scan room
 - Faulty Room Shielding



How many artifacts can you see?



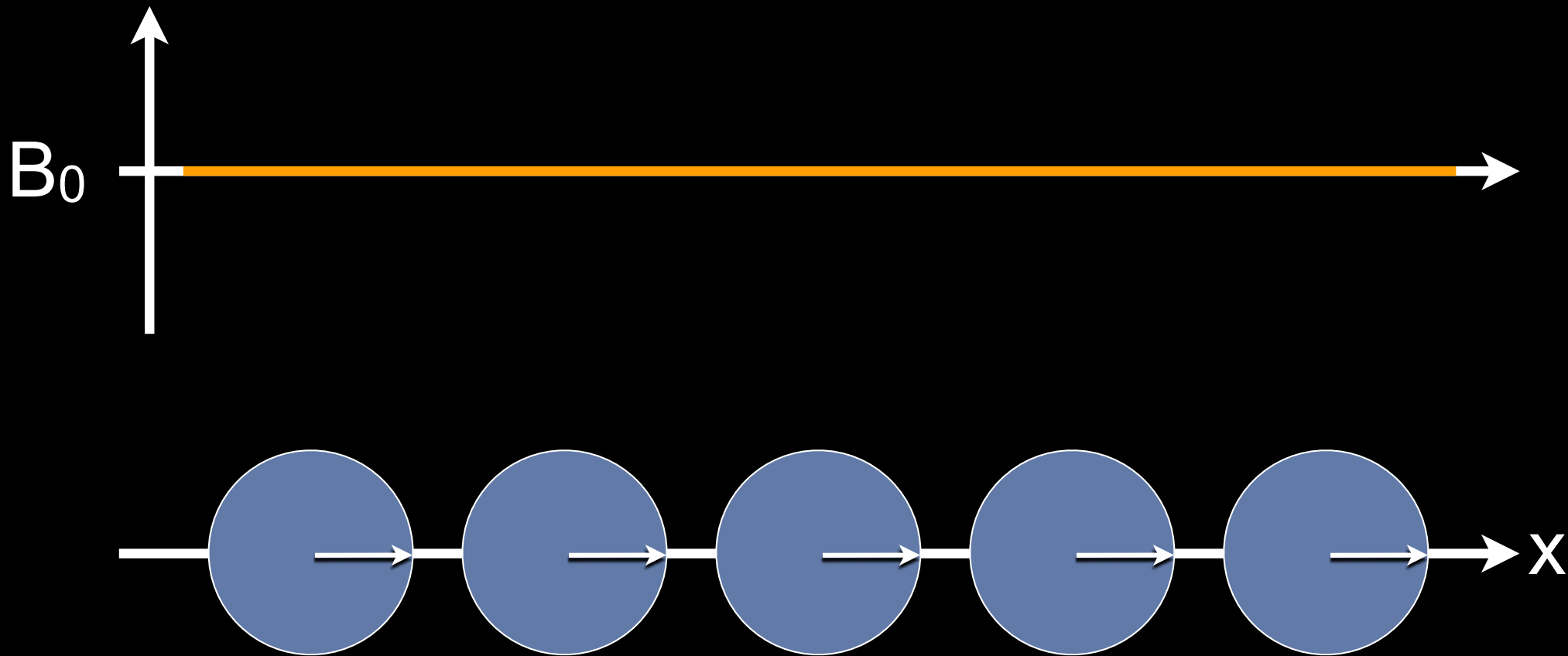
How many artifacts can you see?



Noise
Gradient Distortion
Gibb's Ringing
Chemical Shift
Coil shading

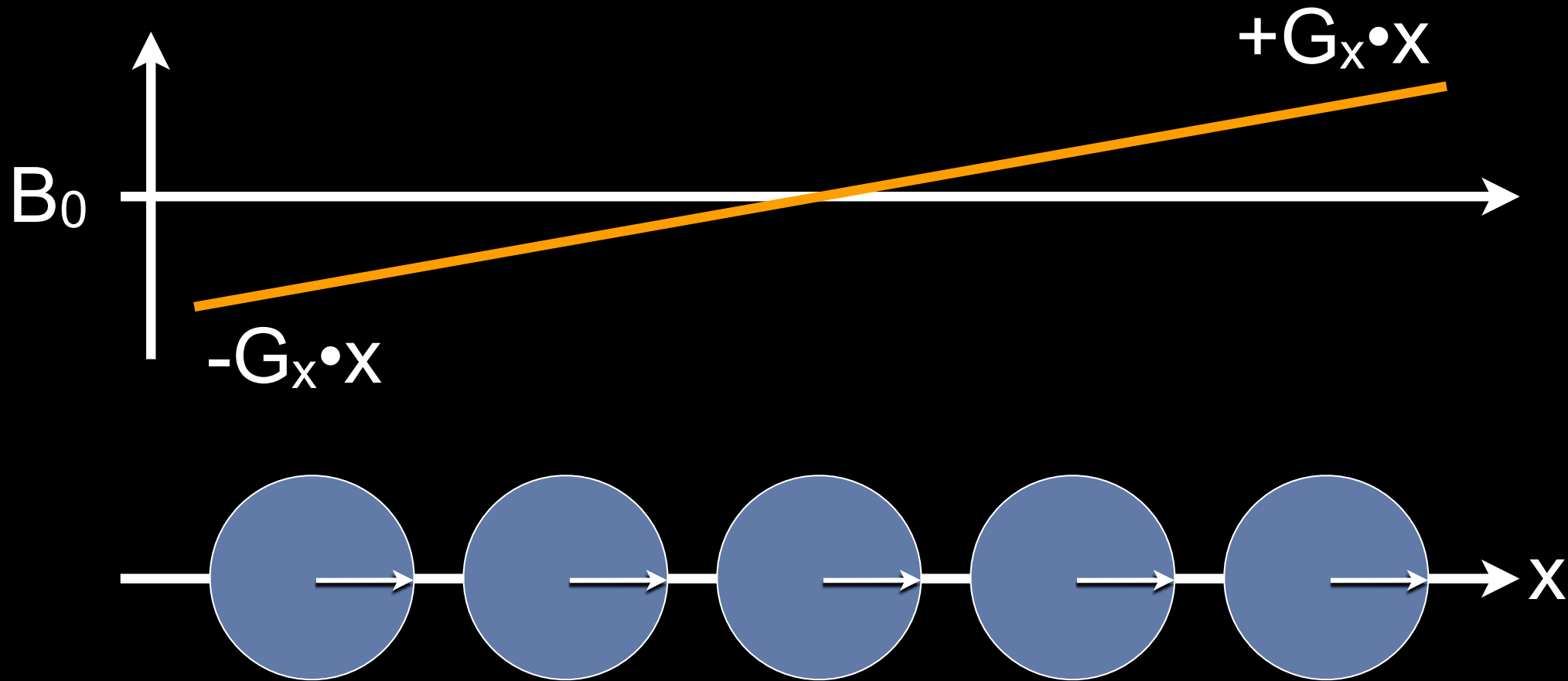
Gradient Echoes & Fat

GRE & Fat/Water Frequency



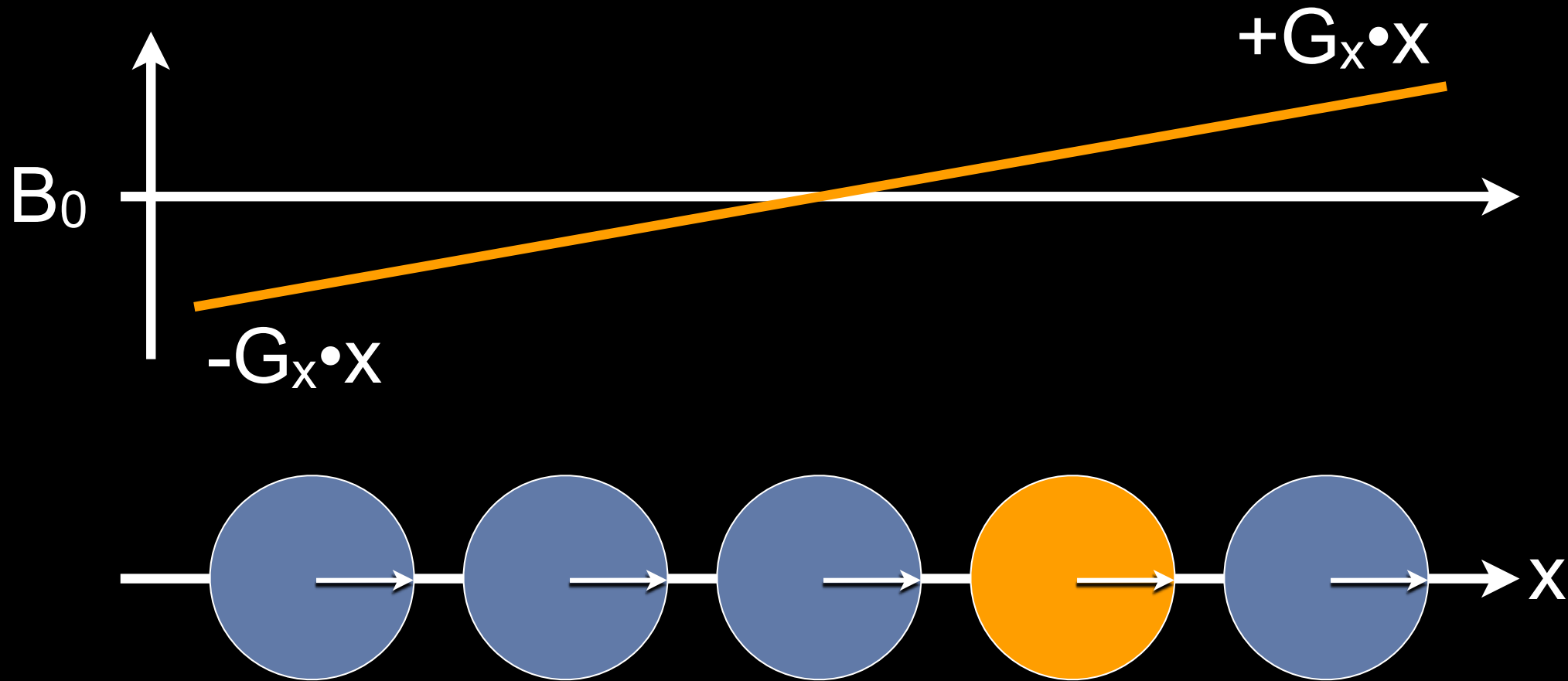
Water Spins in a Uniform Field

GRE & Fat/Water Frequency



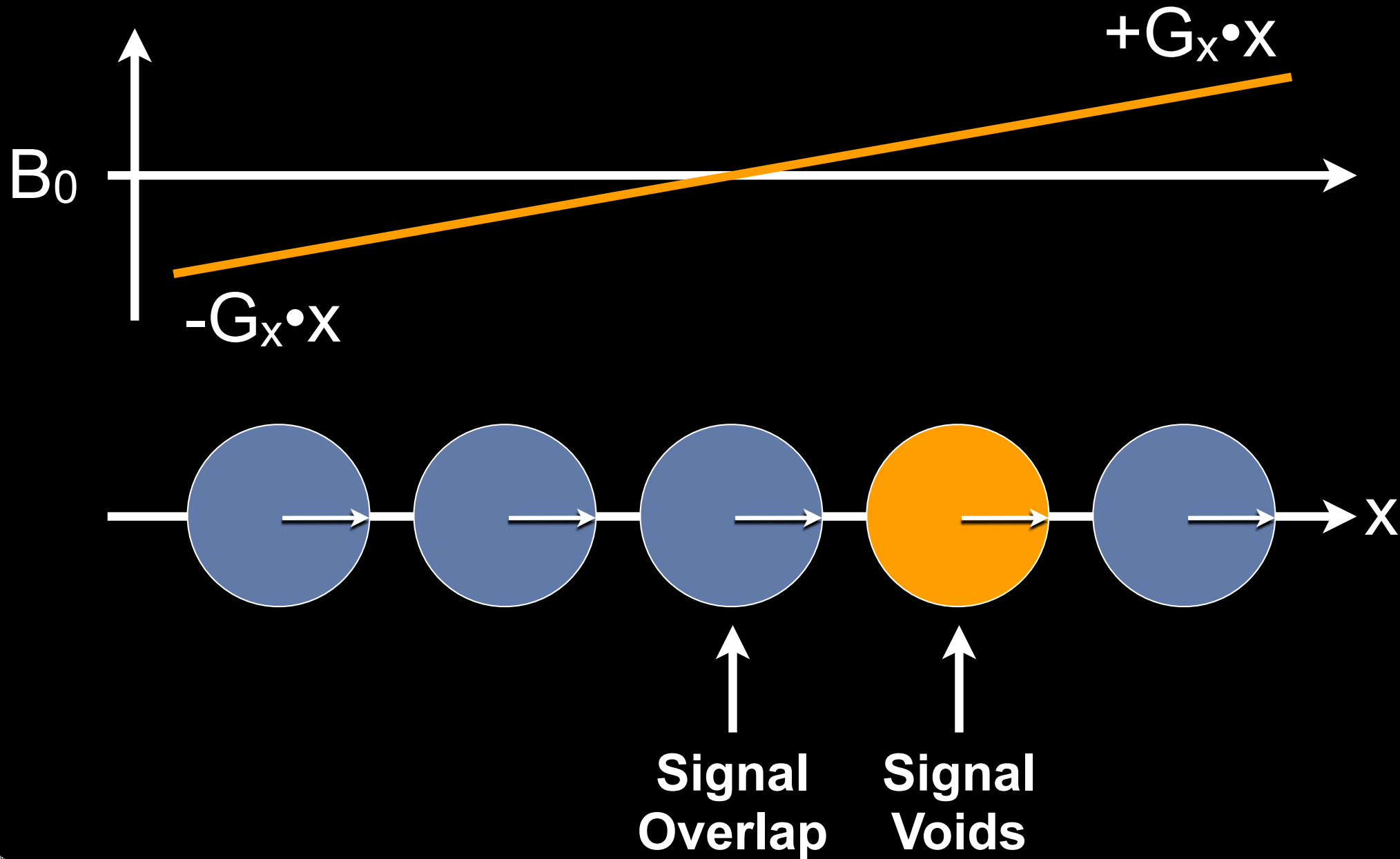
Water Spins in a Gradient Field

GRE & Fat/Water Frequency



Water & Fat Spins in a Gradient Field

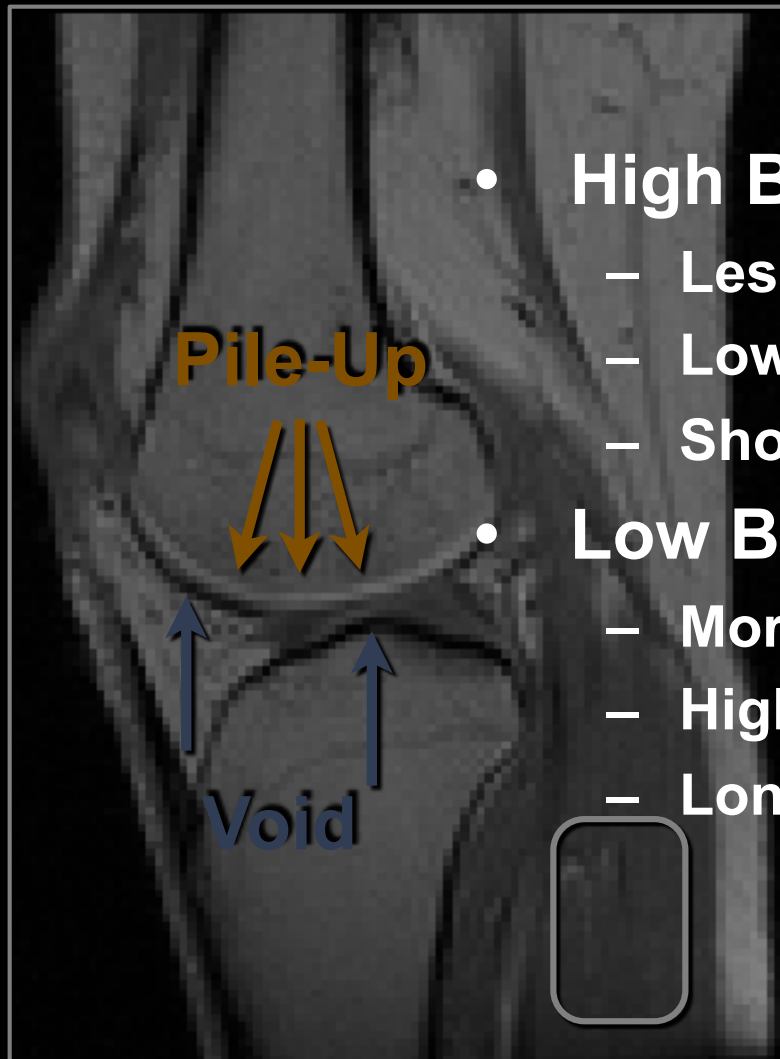
GRE & Fat/Water Frequency



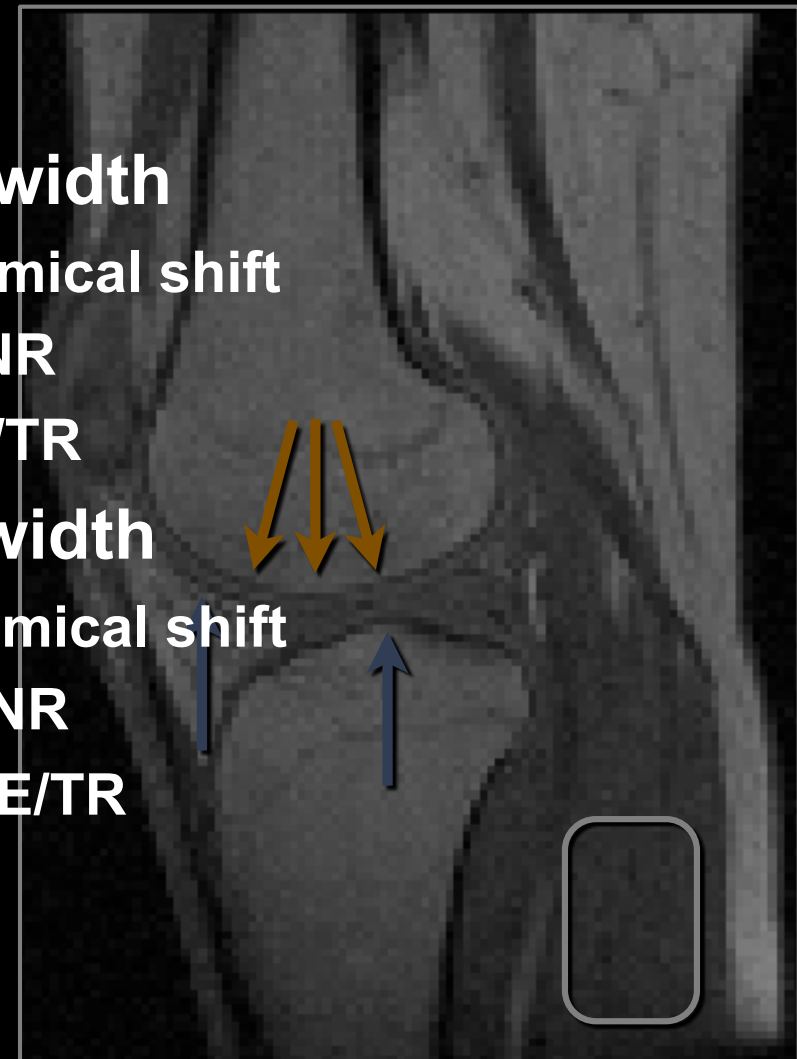
GRE & Fat/Water Frequency

Low Bandwidth

High Bandwidth

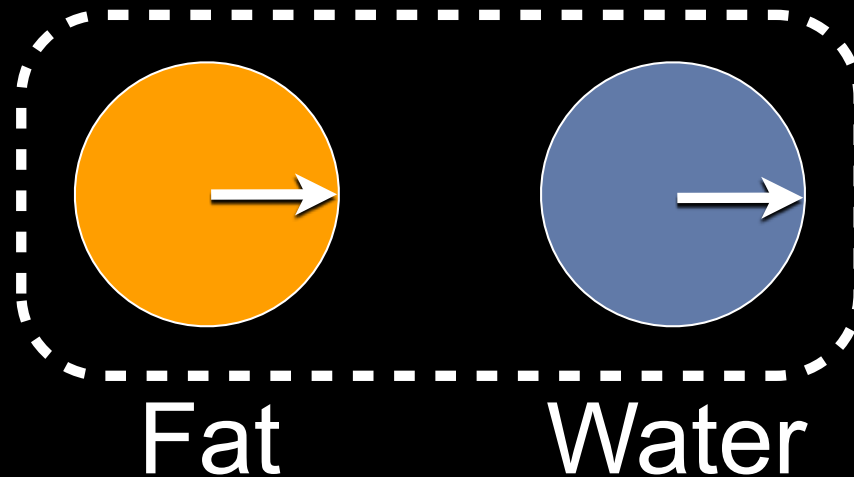


- High Bandwidth
 - Less chemical shift
 - Lower SNR
 - Short TE/TR
- Low Bandwidth
 - More chemical shift
 - Higher SNR
 - Longer TE/TR



GRE and Fat/Water Phase

- Pixels are frequently a mixture of fat and water
- Pixel intensity is the vector sum of fat and water



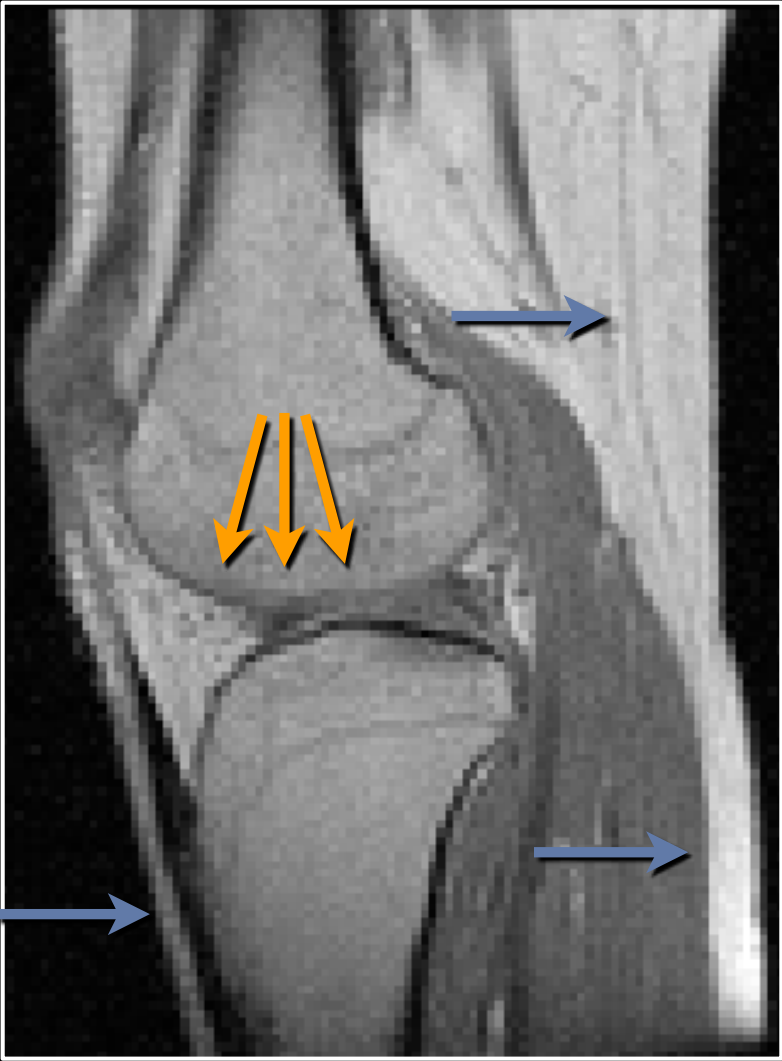
In-Phase
→ + → > 0

Opposed-Phase
← + → = 0

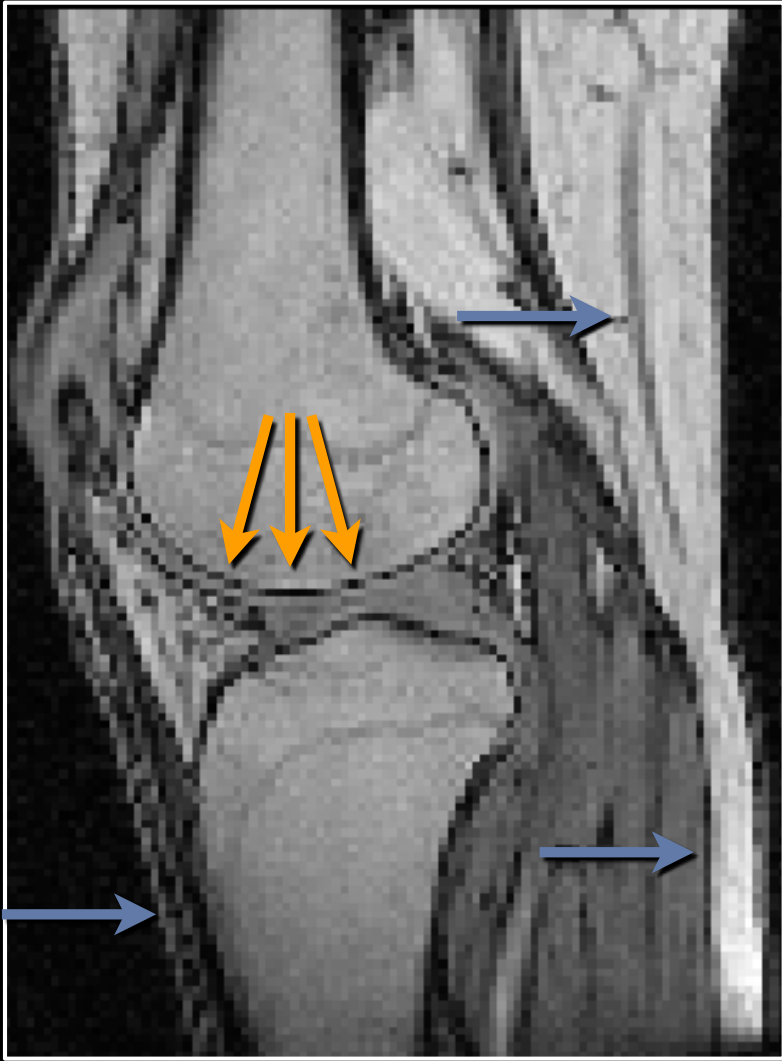
The TE controls the phase between fat and water.

GRE and Fat/Water Phase

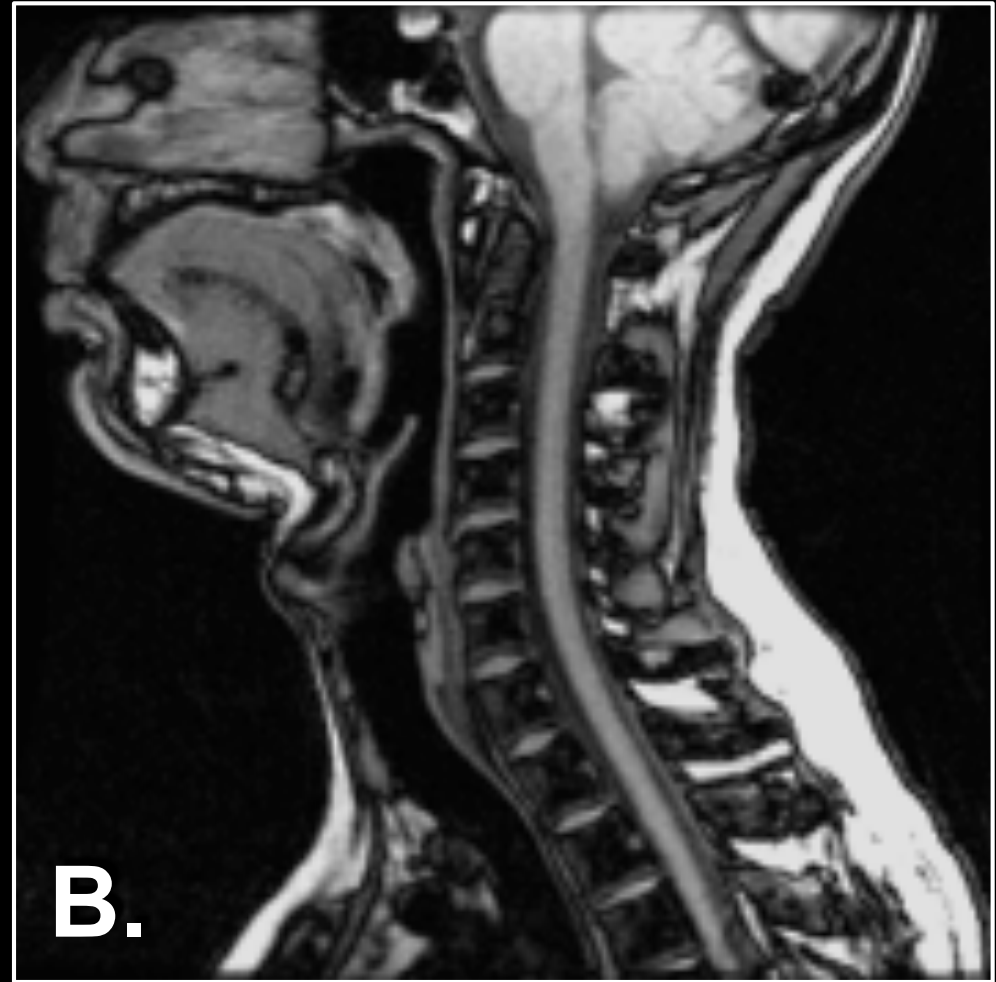
In-Phase



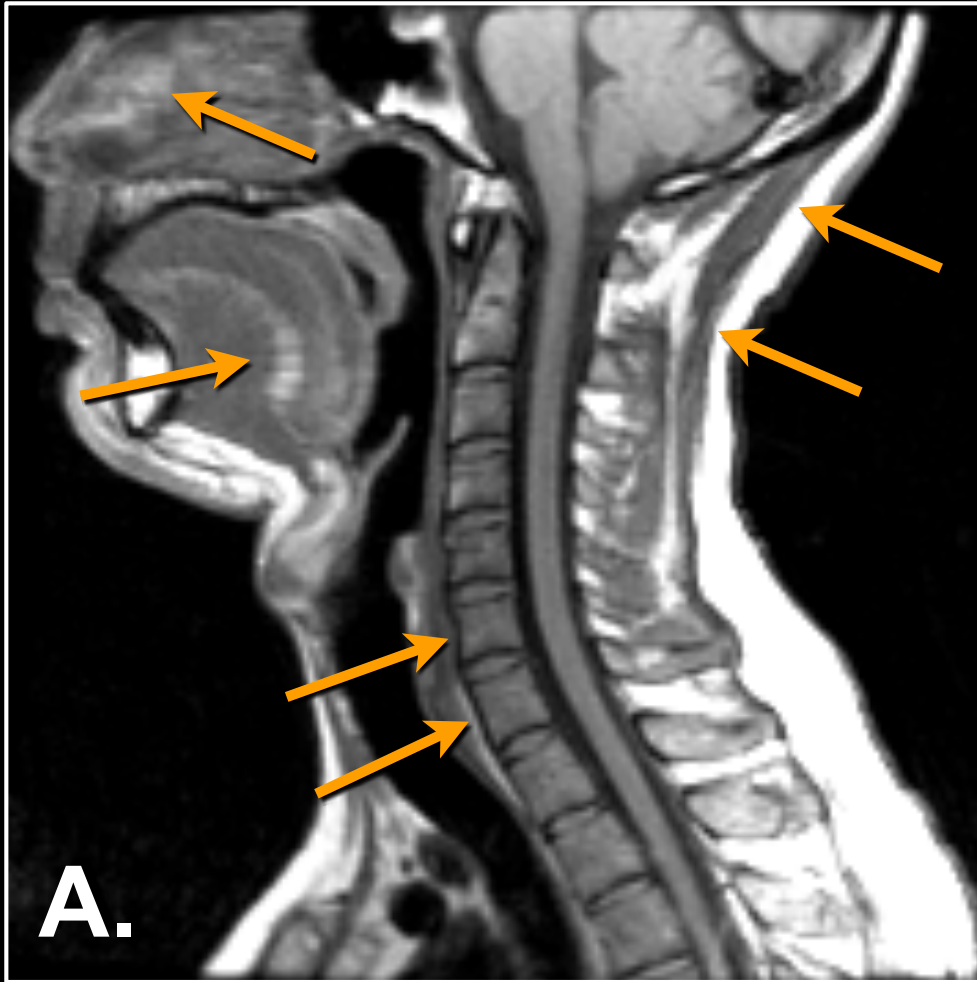
Opposed-Phase



Which image is the in-phase image?

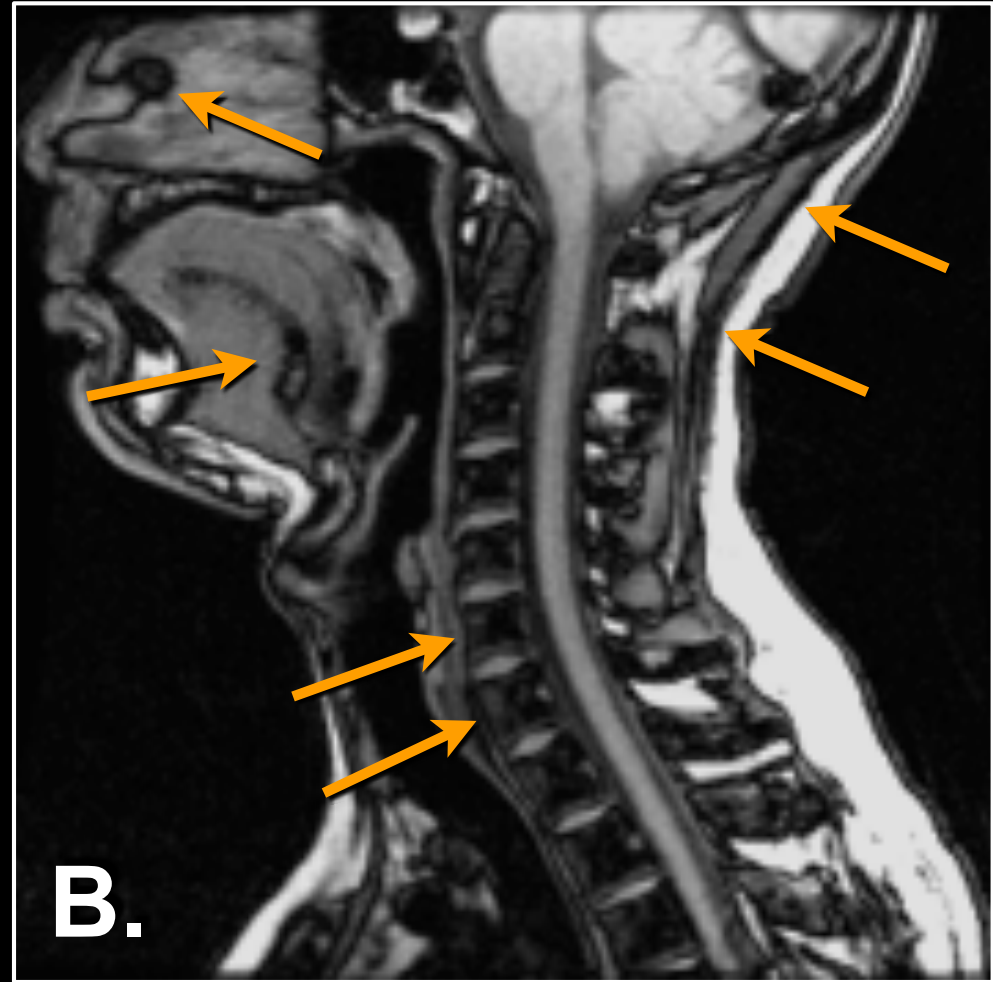


Which image is the in-phase image?



A.

In-Phase



B.

Opposed-Phase

Gradient Echoes & Fat Suppression

- **Why is fat suppression/separation important?**
 - Fat is bright on most pulse sequences.
 - But so are many other things...
 - CSF & edema
 - Flowing blood
 - Contrast enhanced tissues
- **Fat obscures underlying pathology**
 - Edema, neoplasm, inflammation
- **How can fat be eliminated in GRE images?**
 - Fat saturation pulses
 - Multi-echo acquisitions
 - Dixon/IDEAL

Fat Suppression

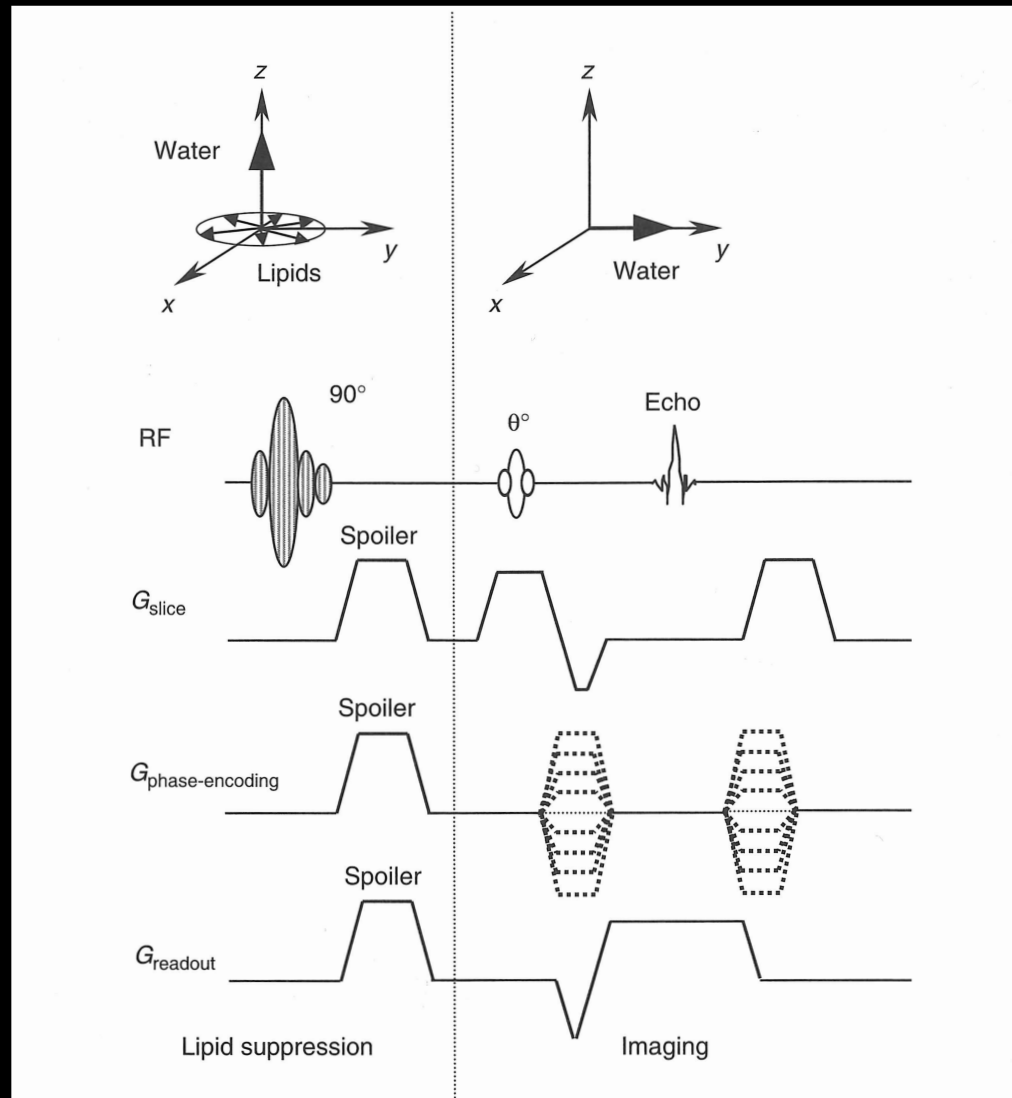
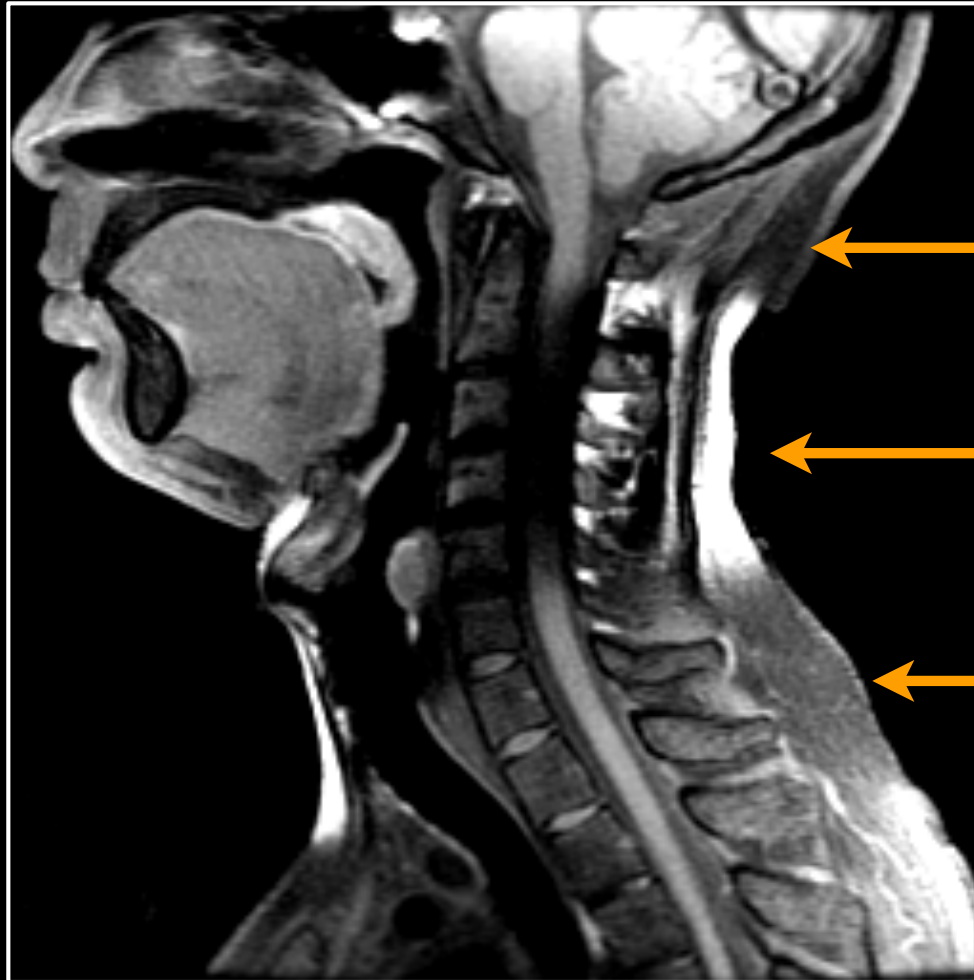


FIGURE 4.15 An example of using a spectrally selective pulse to suppress lipid signals in an imaging sequence. The 90° spectrally selective pulse (shaded area to denote the frequency offset), usually with maximal phase dispersion, is applied ~ 217 Hz off-resonance with respect to the water resonant frequency to excite lipids at 1.5 T. The lipid signals are dephased by one or more spoiler gradients. After lipid suppression (portion to the left of the dotted vertical line), an imaging sequence is executed to excite water signals and form a water image (portion to the right of the dotted vertical line).

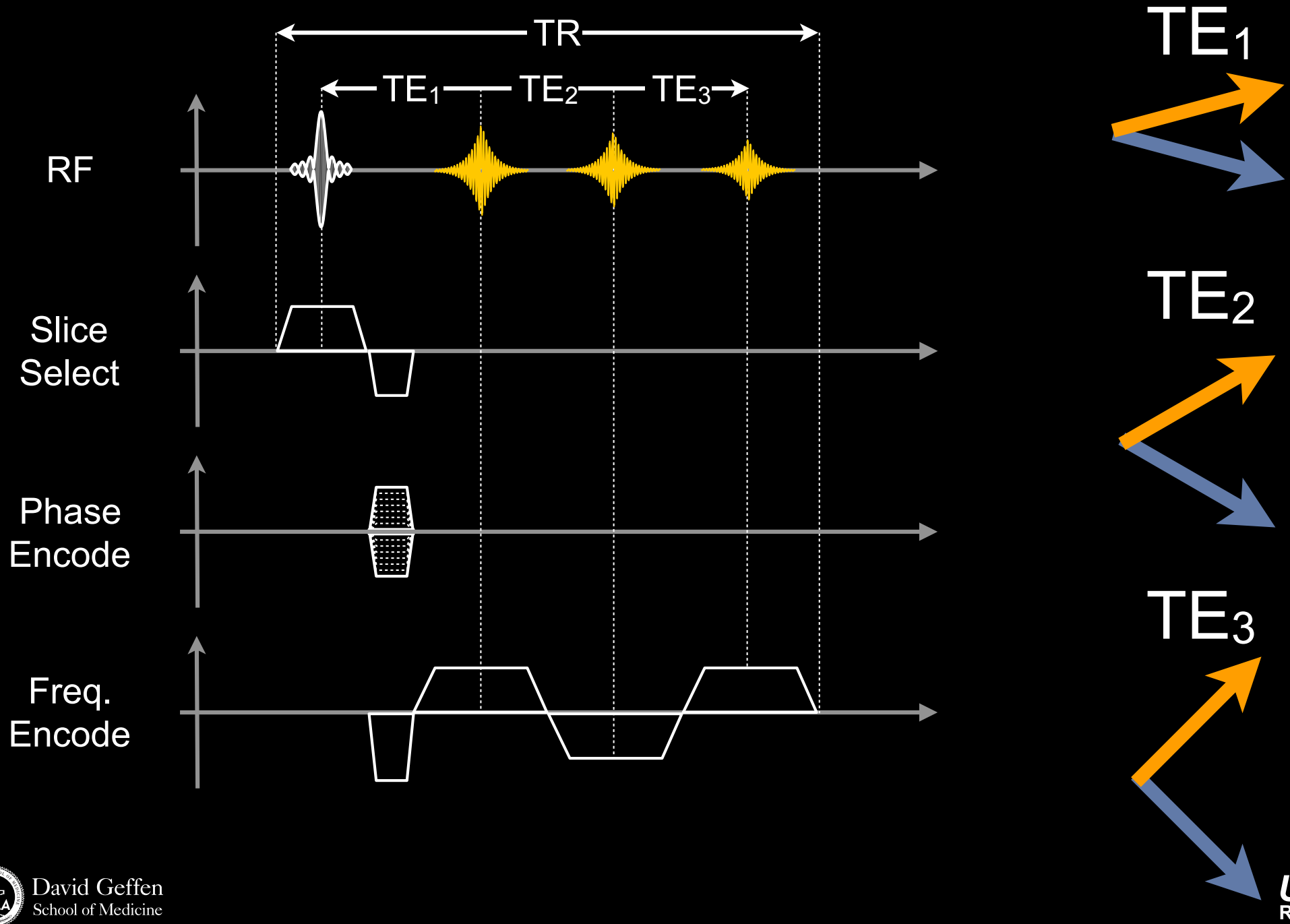
Fat Suppression



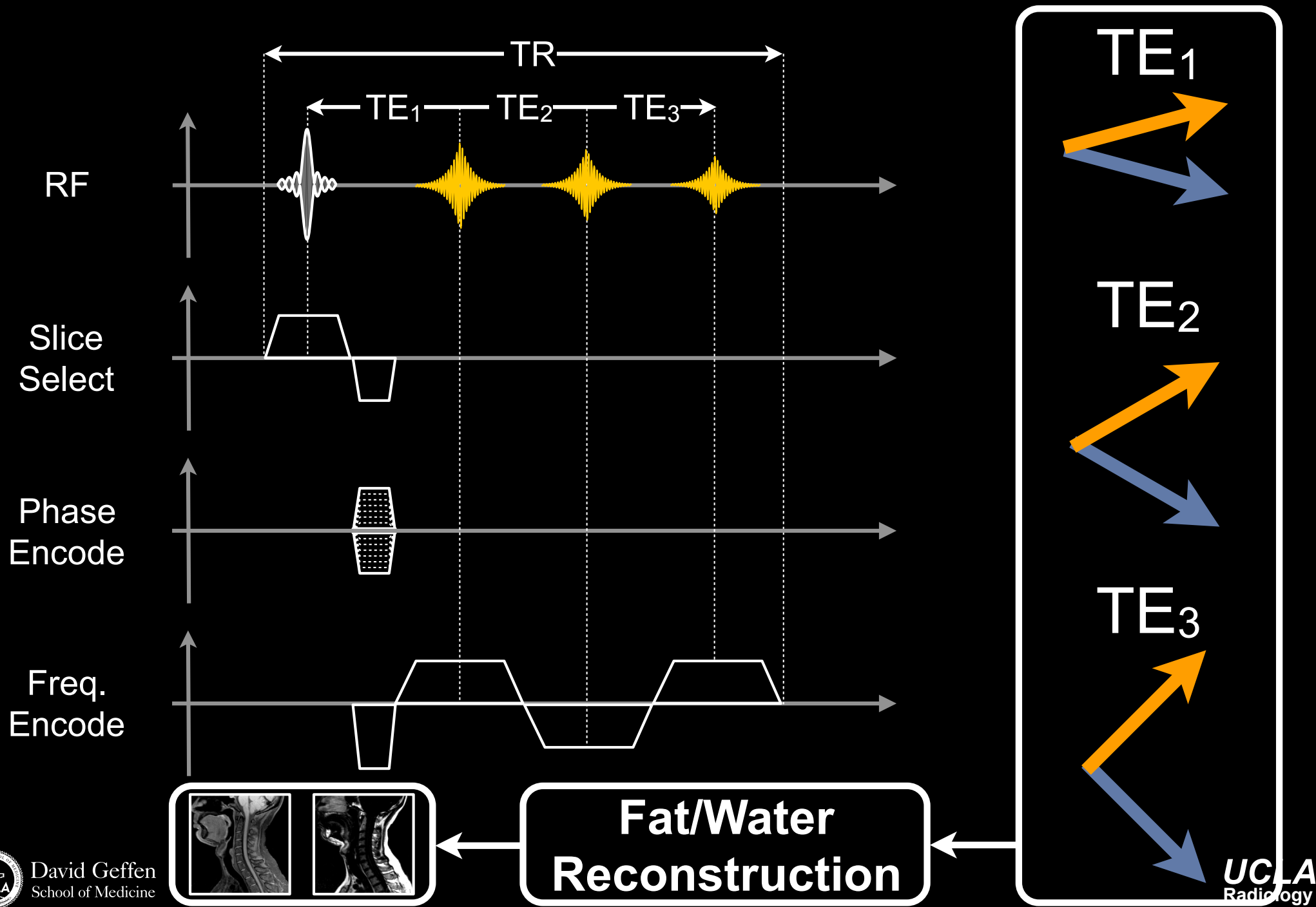
**Fat-Sat Can
Be Spatially
Non-Uniform**

Fat-Sat Image

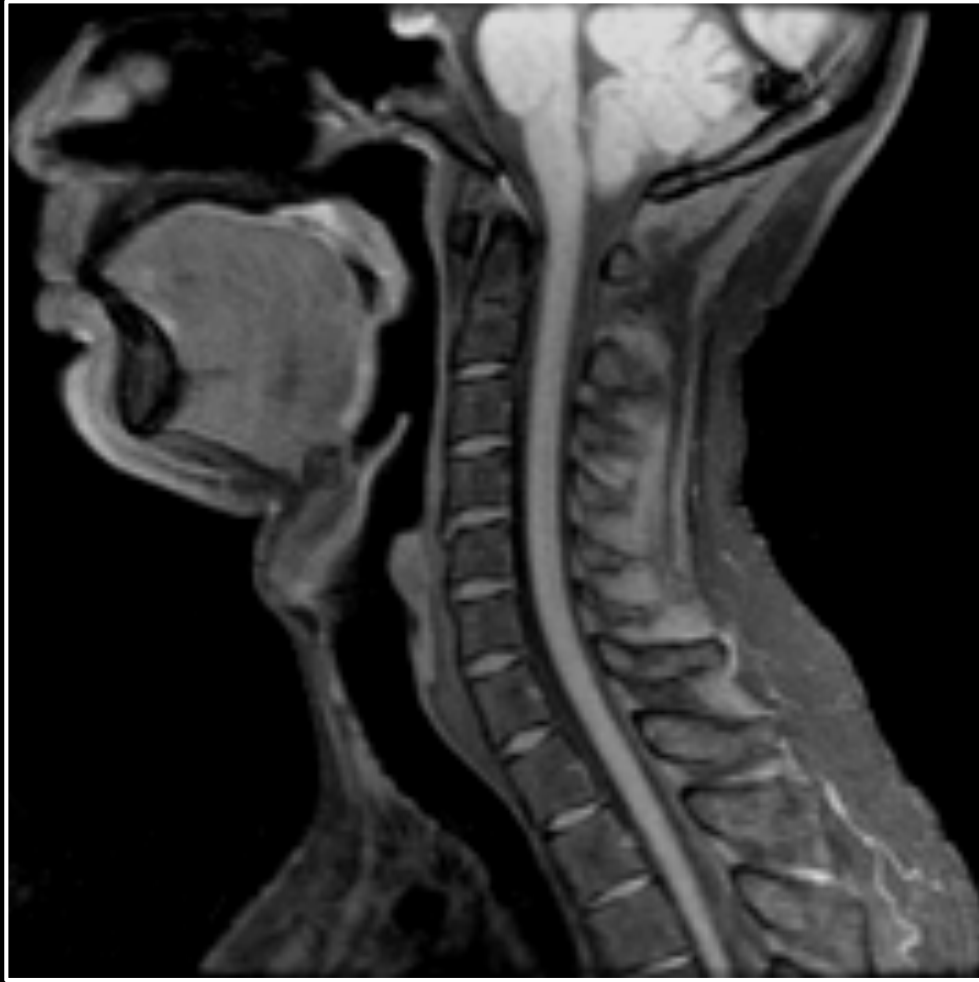
GRE & Fat/Water Separation - How?



GRE & Fat/Water Separation - How?



Gradient Echoes & Fat/Water Separation



Water Image



Fat Image

Gradient Echoes & Fat/Water Separation



Imperfect Fat Sat



Water Image



Fat Image



In-Phase



Opposed-Phase

Thanks



DANIEL B. ENNIS, PH.D.
ENNIS@UCLA.EDU
310.206.0713 (OFFICE)
[HTTP://ENNIS.BOL.UCLA.EDU](http://ennis.bol.ucla.edu)

PETER V. UEBERROTH
BLDG.
SUITE 1417, ROOM C
10945 LE CONTE AVENUE