

RF Pulse Design

Multi-dimensional Excitation I

M229 Advanced Topics in MRI

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2018.04.10

Class Business

- Office hours
 - Instructors: Fri 10-12pm
TAs: Xinran Zhong and Zhaohuan Zhang (time: TBD)
 - Emails beforehand would be helpful
- Homework 1 will be out on 4/12 (due on 4/26)
- Papers and Slides

Today's Topics

- Recap of adiabatic pulses
- Small tip approximation
- Excitation k-space interpretation
- Design of 2D excitation pulses
 - Spiral pulse design

Recap of Adiabatic Pulses

- A special class of RF pulses that can achieve uniform flip angle
- Flip angle is independent of the applied B1 field

$$\theta \neq \int_0^T B_1(\tau) d\tau$$

- Slice profile of an adiabatic pulse is obtained using Bloch simulations
- Does not follow the small tip approximation

Adiabatic Pulses

$$\theta \neq \int_0^{\tau} \gamma B_1(s) ds$$

- Amplitude and frequency modulation
- Long duration (8-12 ms)
- High B1 amplitude (>12 μT)
- Generally NOT multi-purpose (inversion pulses cannot be used for refocusing, etc.)

Non-adiabatic Pulses

$$\theta = \int_0^{\tau} \gamma B_1(s) ds$$

- Amplitude modulation
- Short duration (0.3-1 ms)
- Low B1 amplitude
- Generally multi-purpose (inversion pulses can be used for refocusing, etc.)

Adiabatic Pulses

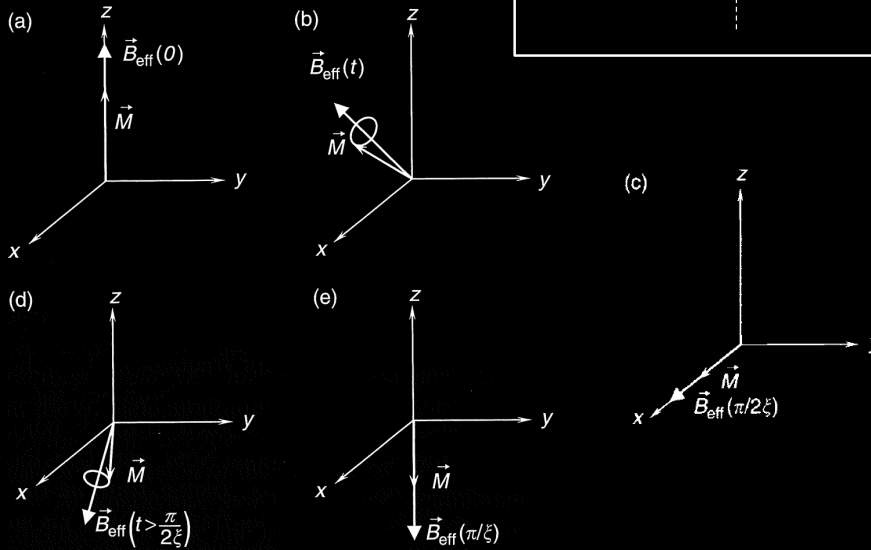
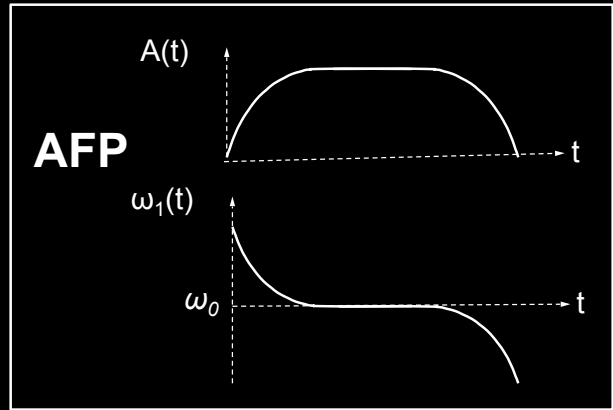
- Frequency modulated pulses:

$$B_1(t) = \underbrace{A(t)}_{\text{envelop}} e^{-i\underbrace{\omega_1(t)}_{\text{frequency sweep}} t}$$

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}_{eff}$$

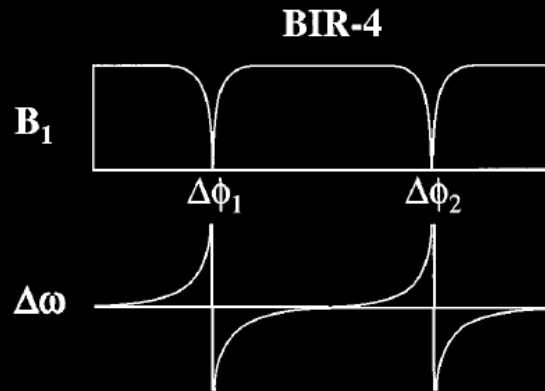
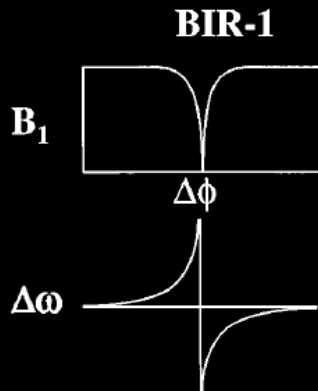
$$\text{where } \vec{B}_{eff} = \begin{pmatrix} A(t) \\ 0 \\ B_0 - \frac{\omega}{\gamma} + \frac{\omega_1(t)}{\gamma} \end{pmatrix}$$

Adiabatic Inversion

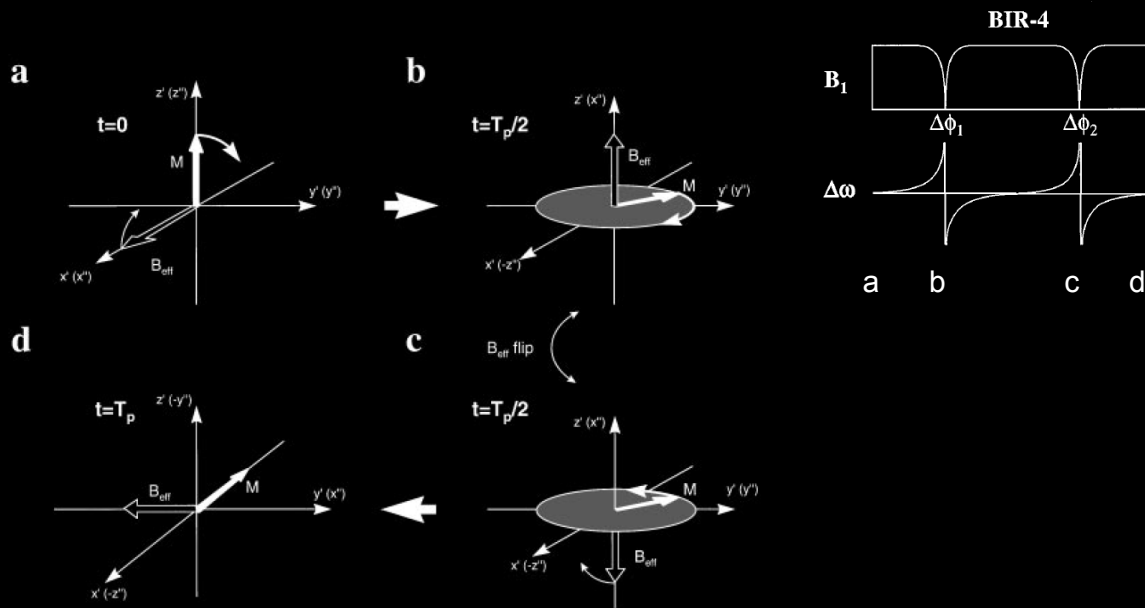


Adiabatic Excitation: BIR Pulses

- BIR: B1 Insensitive Rotation
- Most popular: BIR-4 Pulse



Adiabatic Excitation: BIR4 Pulse



Bloch Simulator

- <http://mrsrl.stanford.edu/~brian/blochsim/>

```
[mx,my,mz] = bloch(b1,gr,tp,t1,t2,df,dp,mode,mx,my,mz)
```

Bloch simulation of rotations due to B_1 , gradient and off-resonance, including relaxation effects. At each time point, the rotation matrix and decay matrix are calculated. Simulation can simulate the steady-state if the sequence is applied repeatedly, or the magnetization starting at m_0 .

INPUT:

```
b1 = (Mx1) RF pulse in G. Can be complex.
gr = (Mx1,2,or 3) 1,2 or 3-dimensional gradient in G/cm.
tp = (Mx1) time duration of each b1 and gr point, in seconds,
      or 1x1 time step if constant for all points
      or monotonically INCREASING endtime of each
      interval..
t1 = T1 relaxation time in seconds.
t2 = T2 relaxation time in seconds.
df = (Nx1) Array of off-resonance frequencies (Hz)
dp = (Px1,2,or 3) Array of spatial positions (cm).
      Width should match width of gr.
mode= Bitmask mode:
      Bit 0: 0-Simulate from start or M0, 1-Steady State
      Bit 1: 1-Record m at time points. 0-just end time.
```

```

%%% User inputs:
mu = 5; % Phase modulation parameter [dimensionless]
beta1 = 672; % Frequency modulation parameter [rad/s]
pulseWidth = 10.24; % RF pulse duration [ms]
A0 = 0.12; % Peak B1 amplitude [Gauss].

%%%%%%

nSamples = 512; % number of samples in the RF pulse
dt = pulseWidth/nSamples/1000; % time step, [seconds]
tim_sech = linspace(-pulseWidth/2,pulseWidth/2,nSamples)./1000';
% time scale to calculate the RF waveforms in seconds.

% Amplitude modulation function B1(t):
B1 = A0.* sech(beta1.*tim_sech);

% Carrier frequency modulation function w(t):
w = -mu.*beta1.*tanh(beta1.*tim_sech)./(2*pi);
% The 2*PI scaling factor at the end converts the unit from rad/s to Hz

% Phase modulation function phi(t):
phi = mu .* log(sech(beta1.*tim_sech));

% Put together complex RF pulse waveform:
rf_pulse = B1 .* exp(1i.*phi);

% Generate a time scale for the Bloch simulation:
tim_bloch = [0:(nSamples-1)]*dt;

%%% The Bloch simulator requires a gradient input. For our simulation,
% gradient will be zero, as we are simulating a non-selective RF pulse.
T1_value = 10000; % [ms]
T2_value = 10000; % [ms]

f_max = 4000; % off-resonance frequency range [Hz]
freq_range = linspace(-f_max,f_max,1000); % off-resonance frequency range [Hz]

grad_pulse = zeros(1,length(rf_pulse));
mod = 0;
[mx1,my1,mz1] = bloch(rf_pulse, grad_pulse, dt, ...
    T1_value/1000, T2_value/1000, freq_range, 0, mod, 0, 0, 0);

% Plotting the longitudinal magnetization to see the inversion profile as a
% function of resonance frequency
figure(2);
plot(freq_range, mz1,'k','LineWidth',LineWidthVal);
title('Inversion Profile'); xlabel('Frequency (Hz)'); ylabel('M_z'); grid on;
v = axis; axis([v(1) v(2) -1.05 1.05]);

```

Small Tip Approximation

Bloch Equation (at on-resonance)

$$\frac{d\vec{M}_{rot}}{dt} = \vec{M}_{rot} \times \gamma \vec{B}_{eff}$$

$$\text{where } \vec{B}_{eff} = \begin{pmatrix} B_1(t) \\ 0 \\ \cancel{B_0} - \frac{\omega}{\gamma} + G_z z \end{pmatrix}$$

When we simplify the cross product,

$$\frac{d\vec{M}}{dt} = \begin{pmatrix} 0 & \omega(z) & 0 \\ -\omega(z) & 0 & \omega_1(t) \\ 0 & -\omega_1(t) & 0 \end{pmatrix} \vec{M}$$

$$\omega(z) = \gamma G_z z \quad \omega_1(t) = \gamma B_1(t)$$

Small Tip Approximation

$$\frac{d\vec{M}}{dt} = \begin{pmatrix} 0 & \omega(z) & 0 \\ -\omega(z) & 0 & \omega_1(t) \\ 0 & -\omega_1(t) & 0 \end{pmatrix} \vec{M}$$

$M_z \approx M_0$ small tip-angle approximation

$$\left. \begin{array}{l} \sin \theta \approx \theta \\ \cos \theta \approx 1 \\ M_z \approx M_0 \rightarrow \text{constant} \end{array} \right\} \frac{dM_z}{dt} = 0$$

$$\frac{dM_{xy}}{dt} = -i\gamma G_z z M_{xy} + i\gamma B_1(t) M_0$$

$$M_{xy} = M_x + iM_y$$

First order linear differential equation. Easily solved.

$$\frac{dM_{xy}}{dt} = -i\gamma G_z z M_{xy} + i\gamma B_1(t) M_0$$

Solving a first order linear differential equation:

$$M_{xy}(t, z) = i\gamma M_0 \int_0^t B_1(s) e^{-i\gamma G_z z \cdot (t-s)} ds$$

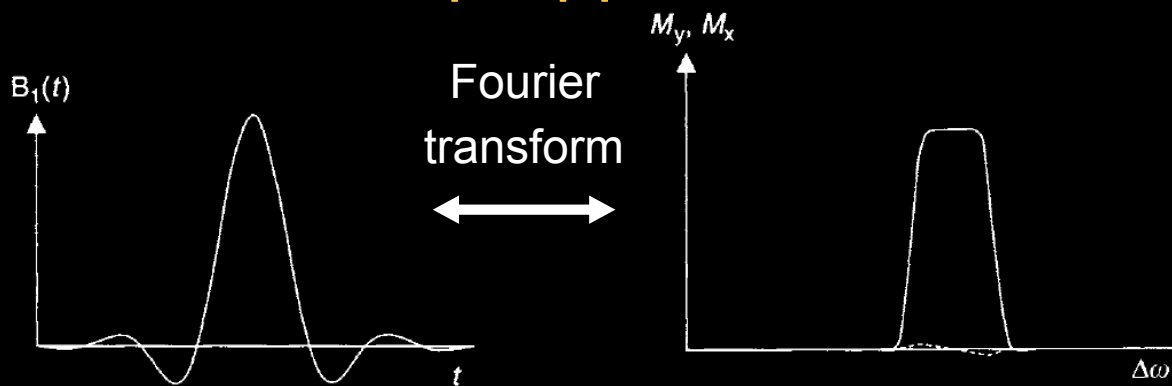


$$M_r(\tau, z) = iM_0 e^{-i\omega(z)\tau/2} \cdot \mathcal{FT}_{1D}\{\omega_1(t + \frac{\tau}{2})\} |_{f=-(\gamma/2\pi)G_z z}$$

(See the note for complete derivation)

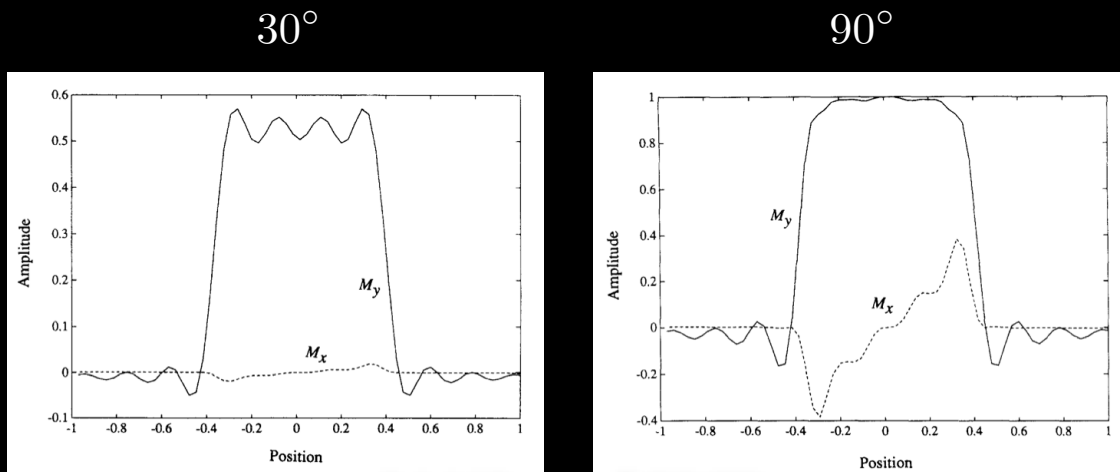
To the board ...

Small Tip Approximation



- For small tip angles, “the slice or frequency profile is well approximated by the Fourier transform of $B_1(t)$ ”
- The approximation works surprisingly well even for flip angles up to 90°

Shaped Pulses



Pauly, J. J. *Magn. Reson.* **81** 43-56 (1989)

small-angle approximation still works reasonably well for flip angles that aren't necessarily “small”

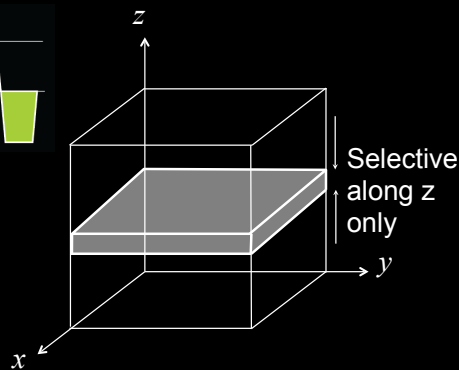
Multi-Dimensional Excitation RF Pulses

- 1D vs. N-D RF pulses
- Small tip angle approximation revisited
- Excitation k-space interpretation
- 1D examples in excitation k-space
- Excitation k-space integrals
- 2D excitation pulse design steps
- 2D spiral pulse design example
- EPI pulse design, spectral-spatial pulses (next lecture)

What is Multi-Dimensional Excitation?

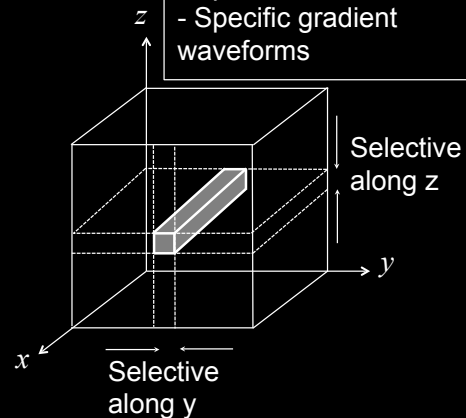
Multi-dimensional excitation occurs when using multi-dimensional RF pulses in MRI/NMR, i.e. 2D or 3D RF pulses

1D vs. N-D RF Pulses



2D/N-D Pulse Design Requires:

- Specific B1 waveform
- Specific gradient waveforms



- 1D pulses are selective along 1 dimension, typically the slice select dimension
- 2D pulses are selective along 2 dimensions
 - So, a 2D pulse would select a long cylinder instead of a slice
 - The shape of the cross section depends on the 2D RF pulse

Excitation k-space Interpretation

Small Tip Approximation

$$M_{xy}(t, z) = i\gamma M_0 \int_0^t B_1(s) e^{-i\omega(z)(t-s)} ds$$

$$\omega(z) = \gamma G_z z \quad \longrightarrow \quad \omega(\vec{r}, t) = \gamma \vec{G}(t) \vec{r}$$



$$M_{xy}(t, \vec{r}) = i\gamma M_0 \int_0^t B_1(s) e^{-i\gamma \int_s^t \vec{G}(\tau) d\tau \cdot \vec{r}} ds$$

Small Tip Approximation

$$M_{xy}(t, \vec{r}) = i\gamma M_0 \int_0^t B_1(s) e^{-i\gamma \int_s^t \vec{G}(\tau) d\tau \cdot \vec{r}} ds$$

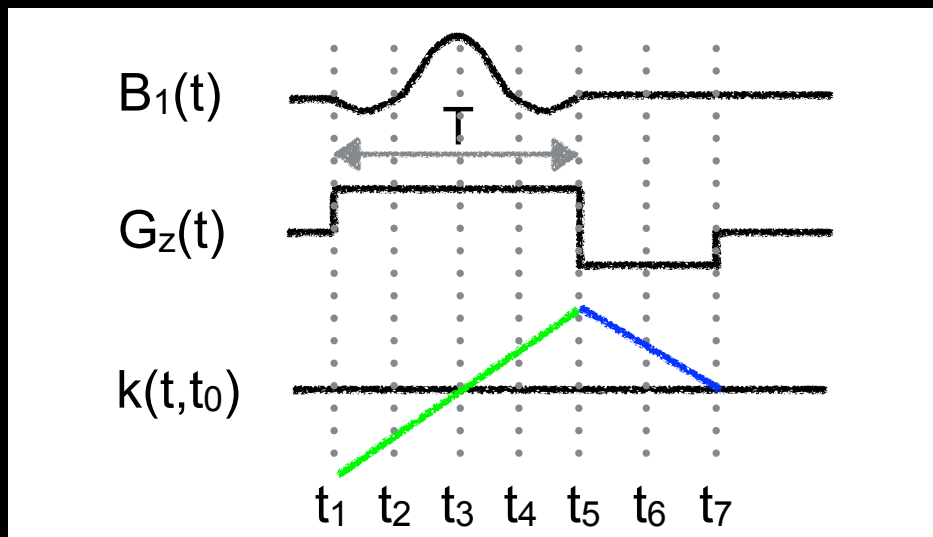
Let us define: $\vec{k}(s, t) = -\frac{\gamma}{2\pi} \int_s^t \vec{G}(\tau) d\tau$



$$M_{xy}(t, \vec{r}) = i\gamma M_0 \int_0^t B_1(s) e^{i2\pi \vec{k}(s, t) \cdot \vec{r}} ds$$

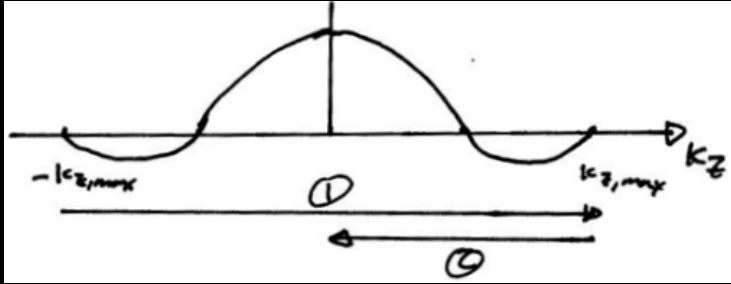
One-Dimensional Example

$$\vec{k}(s, t) = -\frac{\gamma}{2\pi} \int_s^t \vec{G}(\tau) d\tau$$



Consider the value of k at $s = t_1, t_2, \dots, t_7$

One-Dimensional Example



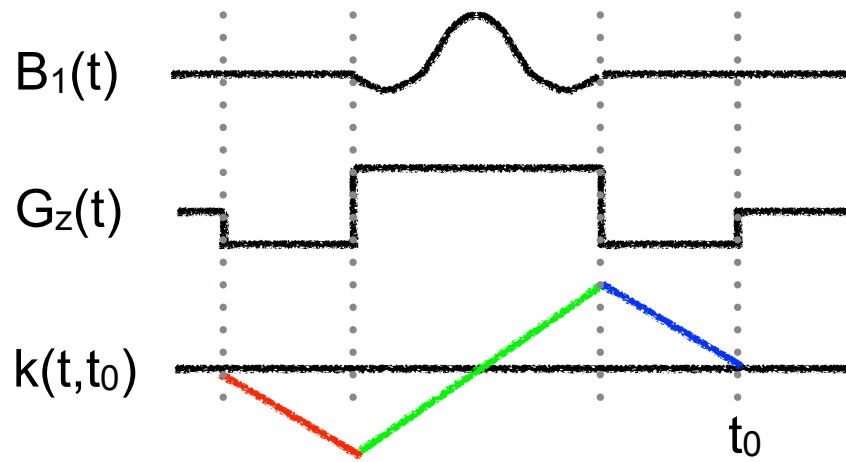
$$k_{z,max} = \frac{T}{2} \frac{\gamma}{2\pi} G_z$$

- This gives magnetization at $t = t_0$, the end of the pulse
- Looks like you scan across k-space, then return to origin

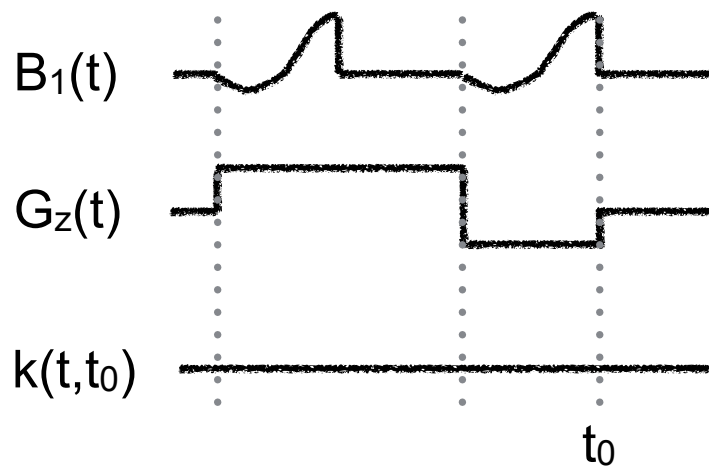
Evolution of Magnetization During Pulse

- RF pulse goes in at DC ($k_z = 0$)
- Gradients move previously applied weighting around
- Think of the RF as “writing” an analog waveform in k-space
- Same idea applies to reception

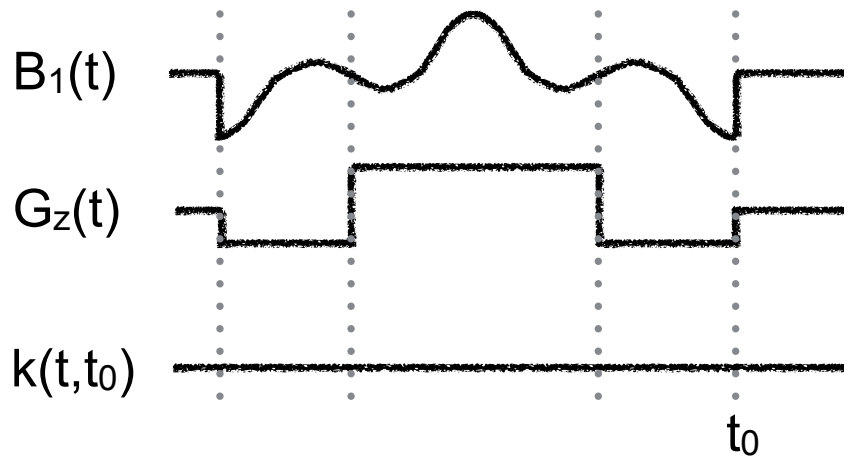
Other 1D Examples



Other 1D Examples



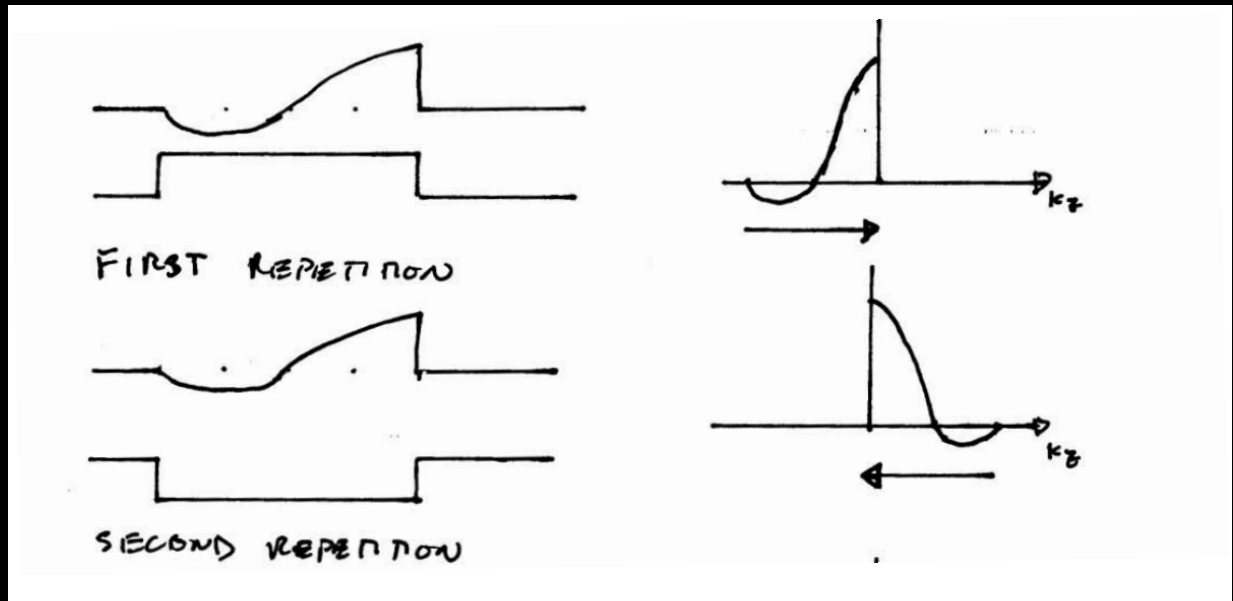
Other 1D Examples



Multiple Excitations

- Most acquisition methods require several repetitions to make an image
 - e.g., 128 phase encodes
- Data is combined to reconstruct an image
- Same idea works for excitation!

Simple 1D Example



Sum the data from two acquisitions

Same profile as slice selective pulse, but zero echo time

Small Tip Approximation Solution as k-space Integral

$$M_{xy}(t, \vec{r}) = i\gamma M_0 \int_0^t B_1(s) e^{i2\pi \vec{k}(s,t) \cdot \vec{r}} ds$$

$$e^{i2\pi \vec{k}(s,t) \cdot \vec{r}} = \int_{\vec{k}} \delta(\vec{k}(s,t) - \vec{k}) e^{i2\pi \vec{k} \cdot \vec{r}} d\vec{k}$$

Substituting and changing the order of integration:

$$M_{xy}(t, \vec{r}) = iM_0 \int_{\vec{k}} \left[\int_{-\infty}^t \gamma B_1(s) \delta(\vec{k}(s,t) - \vec{k}) ds \right] e^{i2\pi \vec{k} \cdot \vec{r}} d\vec{k}$$

$$p(\vec{k})$$

$$M_{xy}(t, \vec{r}) = iM_0 \int_{\vec{k}} \left[\int_{-\infty}^t \gamma B_1(s)^3 \delta(\vec{k}(s, t) - \vec{k}) ds \right] e^{i2\pi \vec{k} \cdot \vec{r}} d\vec{k}$$

$$M_{xy}(t, \vec{r}) = iM_0 \int_{\vec{k}} p(\vec{k}) e^{i2\pi \vec{k} \cdot \vec{r}} d\vec{k}$$

where $p(\vec{k}) = \int_{-\infty}^t \gamma B_1(s)^3 \delta(\vec{k}(s, t) - \vec{k}) ds$

- The magnetization is the inverse transform of $p(k)$
- We want this to be a unit delta, multiplied by a weighting function

Small Tip Approximation Solution as k-space Integral

Multiply and divide by $|k'(s, t)|$:

$$p(\vec{k}) = \int_{-\infty}^t \frac{\gamma B_1(s)}{|k'(s, t)|} \delta(\vec{k}(s, t) - \vec{k}) |k'(s, t)| ds$$

Unit Delta

$W(k(s, t))$

If we assume $W(k)$ is single-valued

$$p(\vec{k}) = W(\vec{k}) \int_{-\infty}^t \delta(\vec{k}(s, t) - \vec{k}) |k'(s, t)| ds$$

$$p(\vec{k}) = W(\vec{k}) S(\vec{k})$$

Small Tip Approximation Solution as k-space Integral

$$M_{xy}(t, \vec{r}) = iM_0 \int_{\vec{k}} p(\vec{k}) e^{i2\pi\vec{k}\cdot\vec{r}} d\vec{k}$$

$$p(\vec{k}) = W(\vec{k})S(\vec{k})$$

$$W(\vec{k}) = \frac{\gamma B_1(s)}{|k'(s, t)|} \quad \textit{k-space weighting}$$

$$S(\vec{k}) = \int_{-\infty}^t \delta(\vec{k}(s, t) - \vec{k}) |k'(s, t)| ds$$

k-space sampling

Small Tip Approximation Solution as k-space Integral

$$M_{xy}(t, \vec{r}) = iM_0 \int_{\vec{k}} W(\vec{k})S(\vec{k}) e^{i2\pi\vec{k}\cdot\vec{r}} d\vec{k}$$

So, the inverse Fourier transform of the k-space weighting will give us the excitation profile!

$$W(\vec{k}) = \frac{\gamma B_1(s)}{|k'(s, t)|} \quad \textit{k-space weighting}$$

Design of 2D Excitation Pulses

2D Pulse Design

1. Choose a k-space trajectory

$$\vec{k}(s, t) = -\frac{\gamma}{2\pi} \int_s^t \vec{G}(\tau) d\tau$$

2. Choose a weighting function

$$W(\vec{k})$$

3. Design the RF pulse

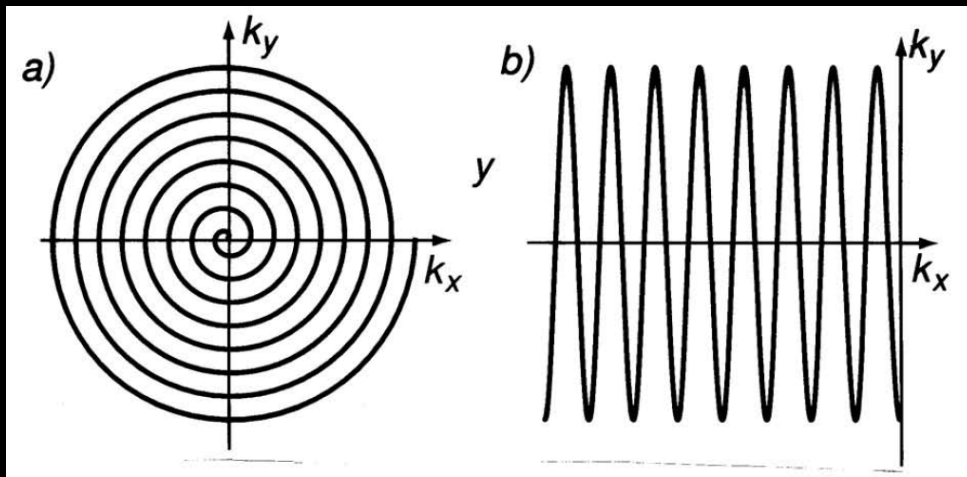
$$B_1(s) = \frac{1}{\gamma} W(\vec{k}) \cdot |k'(s, t)|$$

1. Choose a k-space trajectory

- Select a k-space trajectory that uniformly covers k-space
 - k-space extent ($-k_{\max}, k_{\max}$) \Rightarrow spatial resolution
 - sampling density (Δk) \Rightarrow spatial FOV

1. Choose a k-space trajectory

- Two most common choices:



- Spiral is common for pencil beams
- EPI is common for spectral-spatial pulses

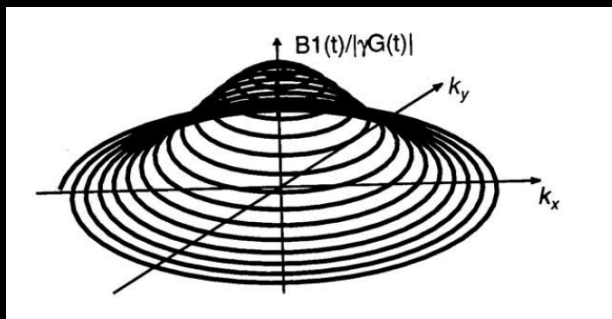
2. Choose a weighting function

$$M_{xy}(t, \vec{r}) = iM_0 \int_{\vec{k}} W(\vec{k}) S(\vec{k}) e^{i2\pi\vec{k}\cdot\vec{r}} d\vec{k}$$

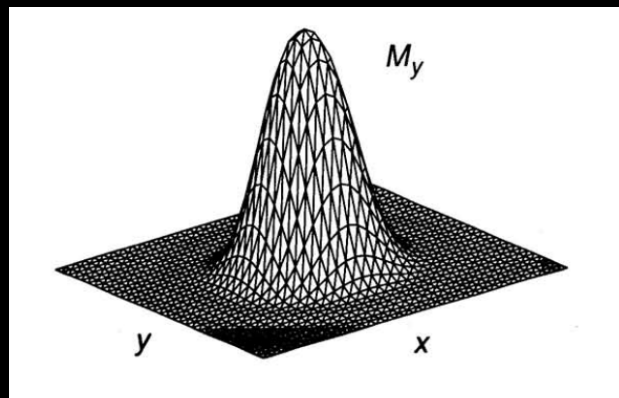
- An excitation profile is the inverse Fourier transform of the weighting function
- If you know what excitation profile you want, its Fourier transform will be the weighting function
- Localized excitation \Rightarrow low-pass k-space weighting

2. Choose a weighting function

k-space weighting



Excitation profile



3. Design the RF pulse

$$\vec{k}(s, t) = -\frac{\gamma}{2\pi} \int_s^t \vec{G}(\tau) d\tau$$

$$k'(s, t) = -\frac{\gamma}{2\pi} \vec{G}(s)$$

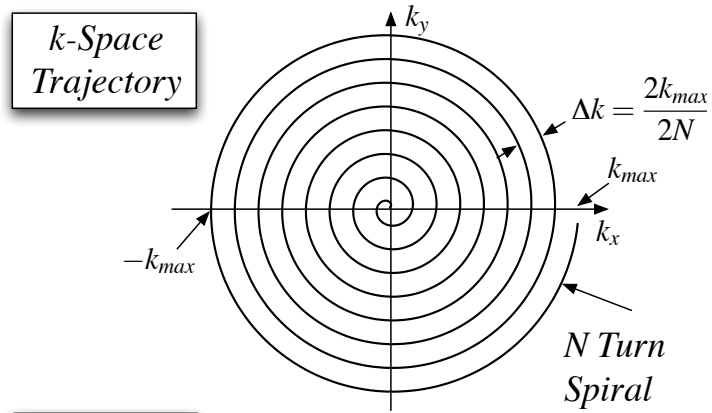
$$B_1(s) = \frac{1}{2\pi} |\vec{G}(s)| W(\vec{k})$$

B_1 needs to be scaled for flip angle

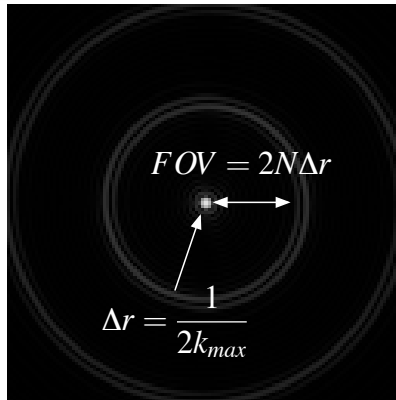
2D Spiral Pulse Design

- Two major choices:
 - Resolution Δr $\Delta r = \frac{1}{2k_{max}}$
 - Smallest volume / minimum transition width
 - Field-of-View (FOV)
 - Distance to center of first sidelobe

$$FOV = \frac{1}{\Delta k} = \frac{2N}{2k_{max}}$$



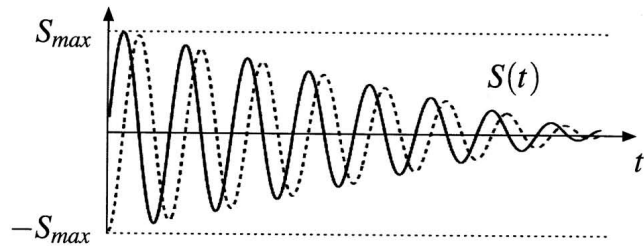
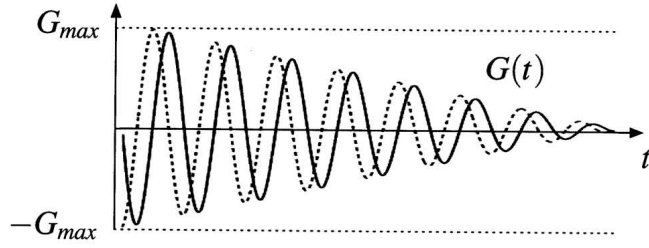
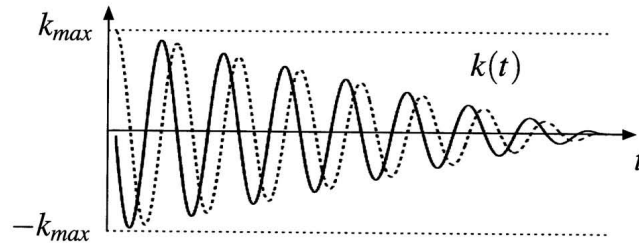
Impulse Response



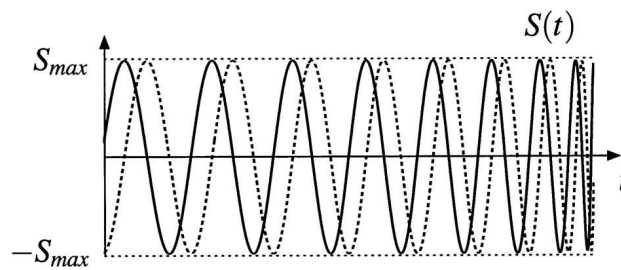
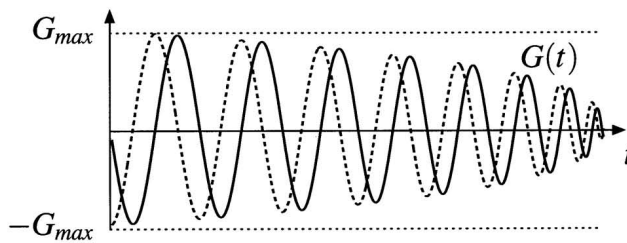
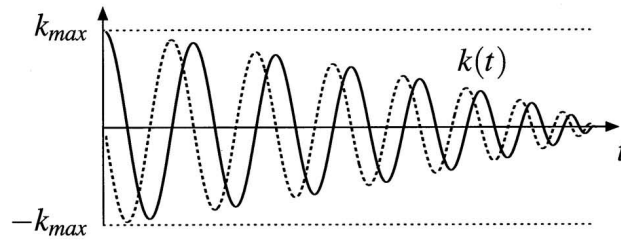
2D Spiral Pulse Design

- Spiral Gradient Design
 - Constant angular rate spiral
 - Constant slew rate spiral

Constant Angular Rate Spiral



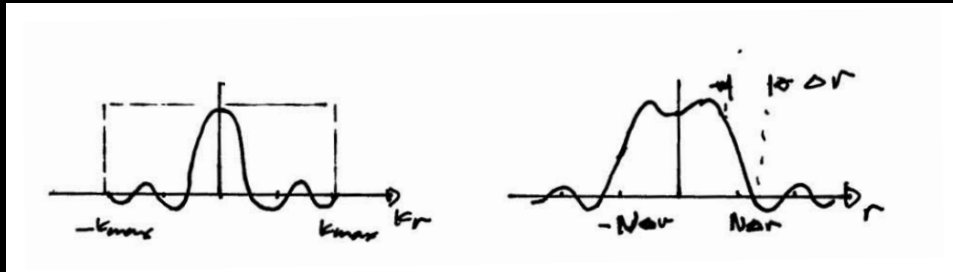
Constant Slew Rate Spiral



2D Spiral Pulse Design

- Truncated Jinc Weighting

$$W(\vec{k}) = \text{jinc}\left(N \frac{k_r}{k_{max}}\right) \cdot \text{rect}\left(\frac{k_r}{2k_{max}}\right)$$



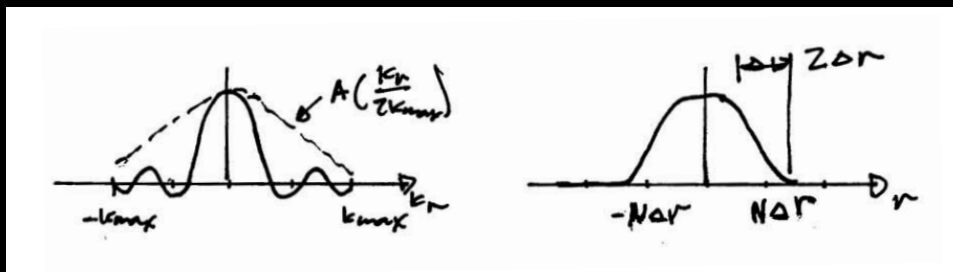
*Minimum transition width,
but residual ripples*

2D Spiral Pulse Design

- Windowed Jinc Weighting

$$W(\vec{k}) = \text{jinc}\left(N \frac{k_r}{k_{max}}\right) \cdot A\left(\frac{k_r}{2k_{max}}\right)$$

Window Function



*Doubled transition width,
but smoother response*

2D Spiral Pulse Design

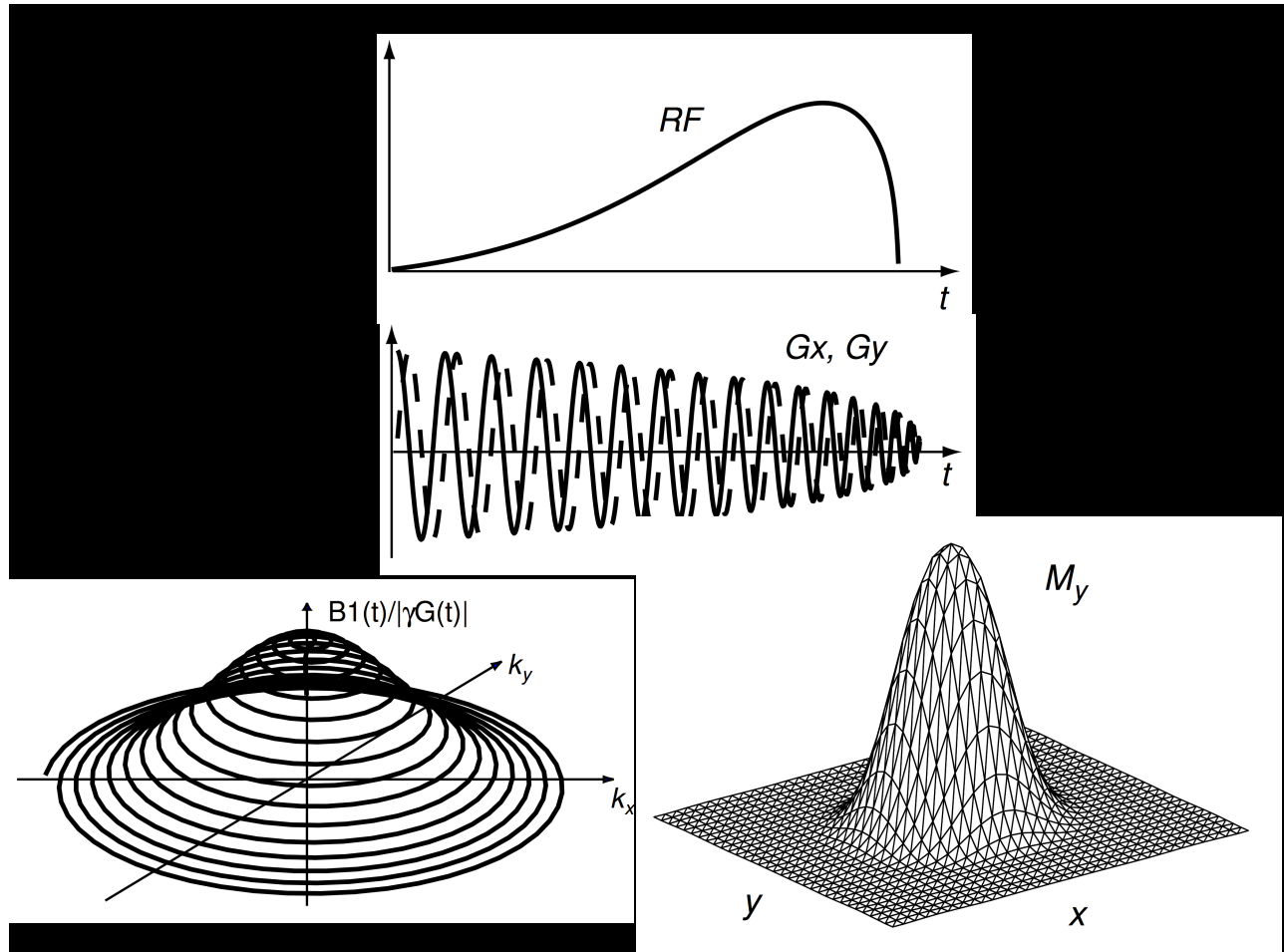
- Calculation of the RF pulse

- given $W(\vec{k})$ and $k(s,t)$

$$W(\vec{k}) = \frac{\gamma B_1(s)}{|k'(s,t)|}$$

$$B_1(s) = \frac{1}{2\pi} |\vec{G}(s)| W(\vec{k})$$

- needs to be scaled for flip angle
- $|k'(s,t)|$ is an estimate of the density compensation function $d(t)$



Conclusions

- N-D RF pulses are selective in N-dimensions
- The small tip approximation can be extended to describe the excitation k-space
- The small tip approximation solution can be used to show that the excitation profile of an N-D pulse is given by the inverse Fourier transform of the excitation k-space weighting

Conclusions

- An N-D RF pulse can be designed by:
 - Choosing a k-space trajectory
 - Choosing a k-space weighting function
 - Then calculating the $B_1(t)$ and $G(t)$ functions

Next Class

- N-D pulses with EPI trajectory
- Spatial-spectral pulses
- Matlab demo of N-D pulses

Thank You!

- Further reading
 - Read “Spatial-Spectral Pulses” p.153-163
- Acknowledgments
 - John Pauly’s EE469b (RF Pulse Design for MRI)
 - Shams Rashid, Ph.D.

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