

①

* Magnetic fields

- B_0 large static field
- B_1 radio frequency field
- $G_{x,y,z}$ gradient fields

$\boxed{B_0}$ without $B_0 \rightarrow$ spin oriented randomly

$$\sum \vec{M} = 0 = \vec{M}$$

↑

"net or bulk"
magnetization

With $B_0 \rightarrow$ 2 things happen

a) Polarization

$$\sum \vec{M} \neq 0 = \vec{M} \text{ alignment of spins}$$

$$= M_z \hat{k}$$

↑ along \hat{z} direction, "longitudinal"

In the presence of B_0 , 2 energy states

n_+ , parallel

n_- , anti-parallel

* Boltzmann distribution $\frac{n_-}{n_+} = e^{-\Delta E/kT}$

(2)

b) Resonance

at equilibrium, $\vec{M} \parallel \vec{B}$ If $\vec{M} \neq \vec{B}$, precession will occur.

From classical mechanics,

torque experienced by \vec{M}

$$= \vec{M} \times \vec{B} = \frac{d}{dt} (\text{angular momentum}) = \frac{d}{dt} (\gamma \vec{I})$$

$$\vec{M} = \gamma \hbar \vec{I}$$

$$\Rightarrow \frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

↓
collection of spins

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}, \quad \vec{B} = \vec{B}_0 = B_0 \hat{k}$$

$\Rightarrow \vec{M}$ will precess about the axis of \vec{B}
at an angular frequency of $\gamma |B|$.

* frequency of precession

$$f = \frac{\gamma}{2\pi} B \text{ Hz; Larmor frequency}$$

$$\text{For } {}^1\text{H}, \frac{\gamma}{2\pi} = \gamma = 42.575 \frac{\text{MHz}}{\text{T}}$$

(3)

$$\frac{d\vec{M}}{dt} = \vec{M} \times \gamma \vec{B}$$

$$\text{let } \vec{B} = B_0 \cdot \hat{k}$$

$$\frac{d\vec{M}}{dt} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ M_x & M_y & M_z \\ 0 & 0 & \gamma B_0 \end{vmatrix}$$

$$\frac{dM_x}{dt} = M_y \cdot \gamma B_0, \quad \frac{dM_y}{dt} = -M_x \cdot \gamma B_0, \quad \frac{dM_z}{dt} = 0$$

$$\frac{dM_x^2}{dt^2} = \frac{dM_y}{dt} \cdot \gamma B_0, \quad \frac{dM_y^2}{dt^2} = -\frac{dM_x}{dt} \cdot \gamma B_0$$

$$= -(\gamma B_0)^2 \cdot M_x \quad = -(\gamma B_0)^2 M_y$$

$$\text{Assume, } M_x(t) = A \cos(\gamma B_0 t) + B \sin(\gamma B_0 t)$$

$$\vec{M}^o = \begin{bmatrix} M_x^o \\ M_y^o \\ M_z^o \end{bmatrix}$$

$$M_x(t=0) = A = M_x^o$$

$$\frac{dM_x}{dt} = -A \gamma B_0 \sin(\gamma B_0 t) + B \gamma B_0 \cos(\gamma B_0 t)$$

$$= M_y \cdot \gamma B_0$$

$$M_y(t=0) = B = M_y^o$$

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Finally,

$$M_x(t) = M_x^0 \cos(\gamma B_0 t) + M_y^0 \sin(\gamma B_0 t)$$

$$M_y(t) = -M_x^0 \sin(\gamma B_0 t) + M_y^0 \cos(\gamma B_0 t)$$

$$M_z(t) = M_z^0$$

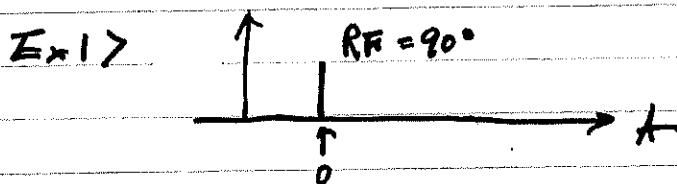
or,

$$\begin{bmatrix} M_x(t) \\ M_y(t) \\ M_z(t) \end{bmatrix} = \begin{bmatrix} \cos(\gamma B_0 t) & \sin(\gamma B_0 t) & 0 \\ -\sin(\gamma B_0 t) & \cos(\gamma B_0 t) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} M_x^0 \\ M_y^0 \\ M_z^0 \end{bmatrix}$$

$\underbrace{\hspace{10em}}$
 $R_z(\gamma B_0 t)$

$$\omega = \gamma B_0$$

$$\vec{\omega} = \gamma \vec{B}_0 = \gamma B_0 \hat{k}$$



$$\vec{M}(0_-) = \begin{bmatrix} 0 \\ 0 \\ M_z^0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ M_0 \end{bmatrix}$$

$$\vec{M}(0_+) = \begin{bmatrix} M_0 \\ 0 \\ 0 \end{bmatrix} \leftarrow \text{Immediately after a } 90^\circ \text{ RF pulse}$$

$$\vec{M}(t) = R_z(\gamma B_0 t) \begin{bmatrix} M_0 \\ 0 \\ 0 \end{bmatrix} \leftarrow \vec{M}(t) \text{ after the } 90^\circ \text{ RF pulse}$$

$$M_x(t) = M_0 \cos(\gamma B_0 t)$$

$$M_y(t) = -M_0 \sin(\gamma B_0 t) \quad] \leftarrow \text{free precession}$$

$$M_z(t) = 0$$