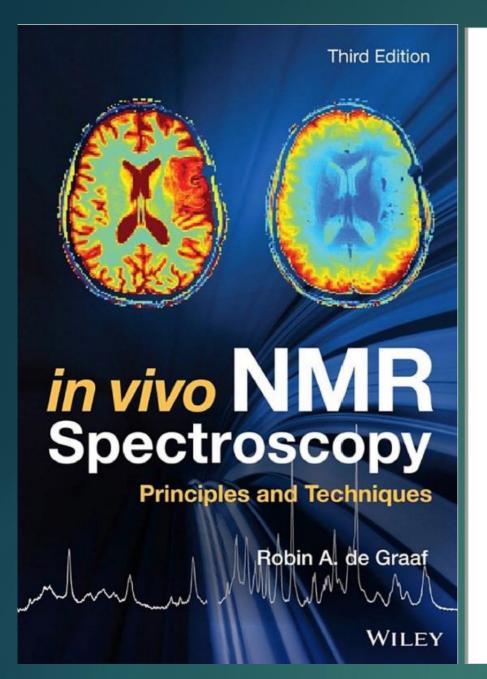
MR Spectroscopic Imaging

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MR Spectroscopic Imaging

- MRI- Basics and k-Space Encoding
- Single Voxel Spectroscopy
- Multi-voxel Spectroscopy/Spectroscopic Imaging
- Acceleration Techniques: Phase-encoding, parallel Imaging, Echo-planar Imaging, Concentric Rings, Radial Imaging and more
- Multi-dimensional MR Spectroscopic Imaging (2D spectral+3D spatial)
- Conclusions



Static High Field (B₀) Creates or polarizes signal 1000 Gauss to 110,000 Gauss (Earth's field is 0.5 G)

(Earth's field is 0.5 G)

Gradient Fields
1-4 G/cm
Used to image: determine spatial position of MR Magnetic signal

Radiofrequency Field (B₁)
Excites or perturbs signal into a measurable form
On the order of O.1 G but in resonance with MR signal

signal
RF coils also measure MR signal
Excited or perturbed signal returns to
equilibrium
Important contrast mechanism

Bore (55-60 cm)

Magnetic field (B₀)

Body RF (transmit/receive)

MRI Uses

Gradients

Shim

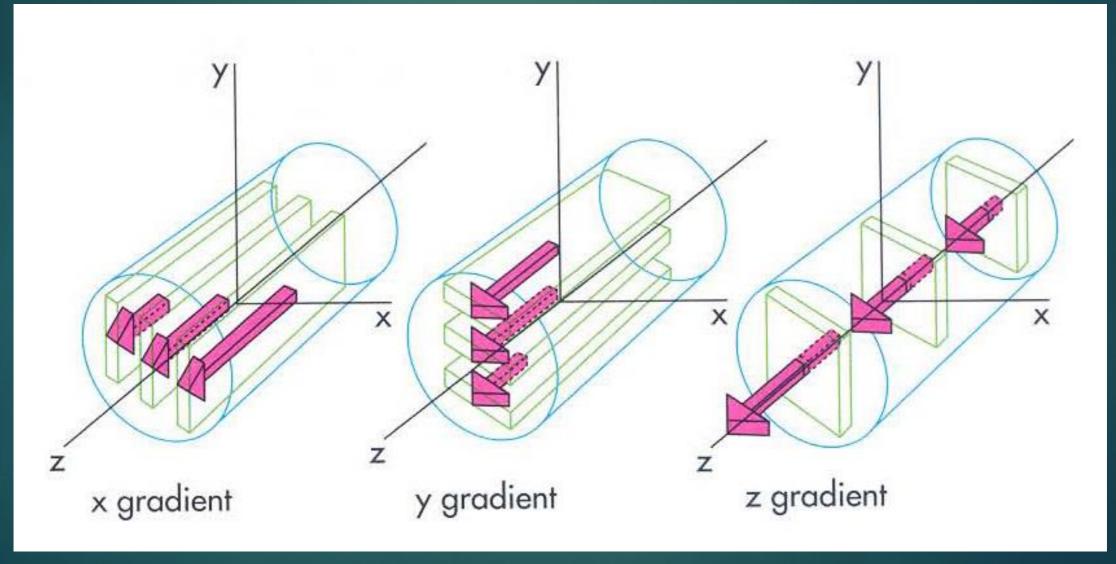
 $(B_0 uniformity)$

Lauterbur 1973 KWE 1975



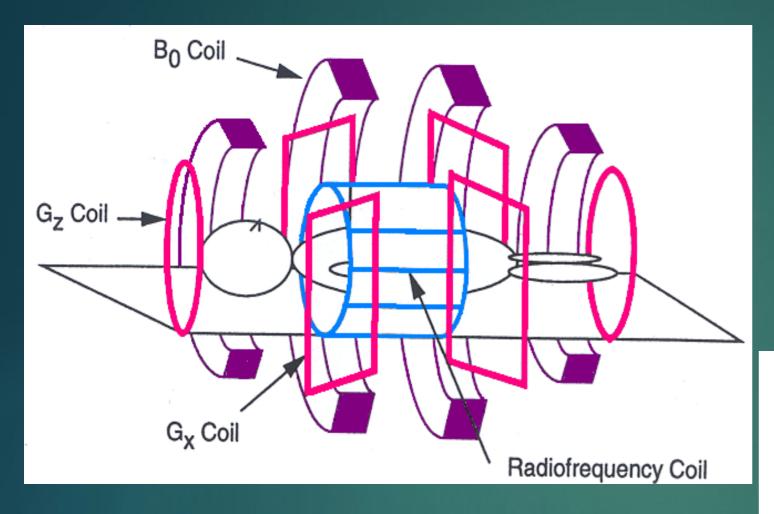
Effect of pulsed field gradients (X, Y, Z)- Spatial Localization

Every imaging system will have three gradient coils that can modify the static field strength (Bo) in X, Y,Z directions. Thus you have the control over changing the Larmor frequencies of nuclear spins in X,Y,Z directions



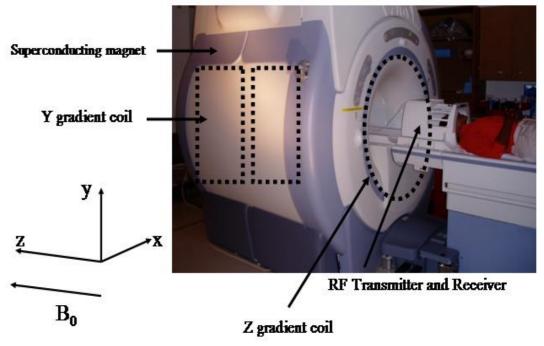


Gradient Coils



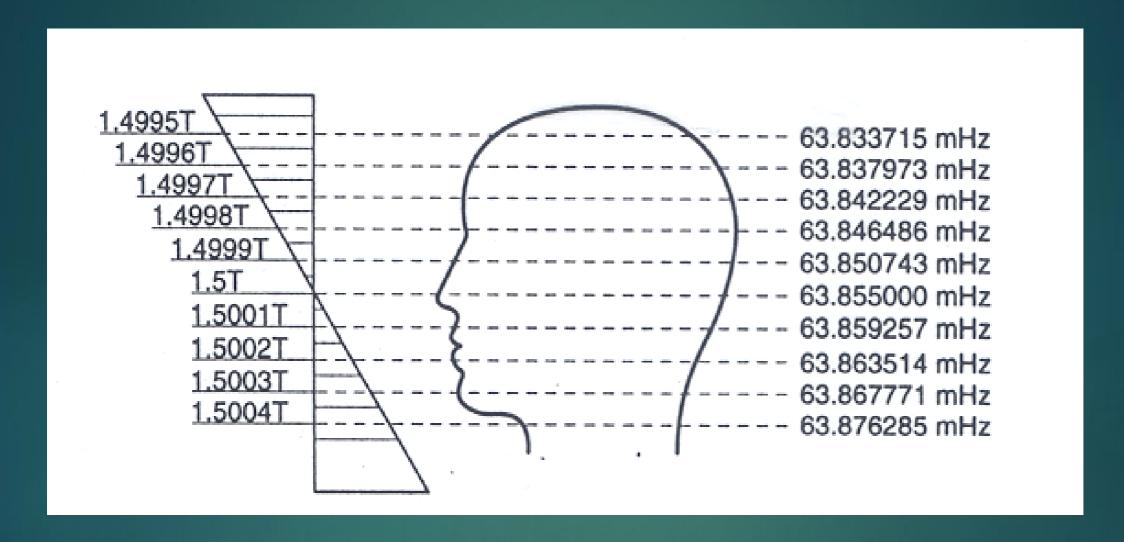
Nishimura, MRI Principles







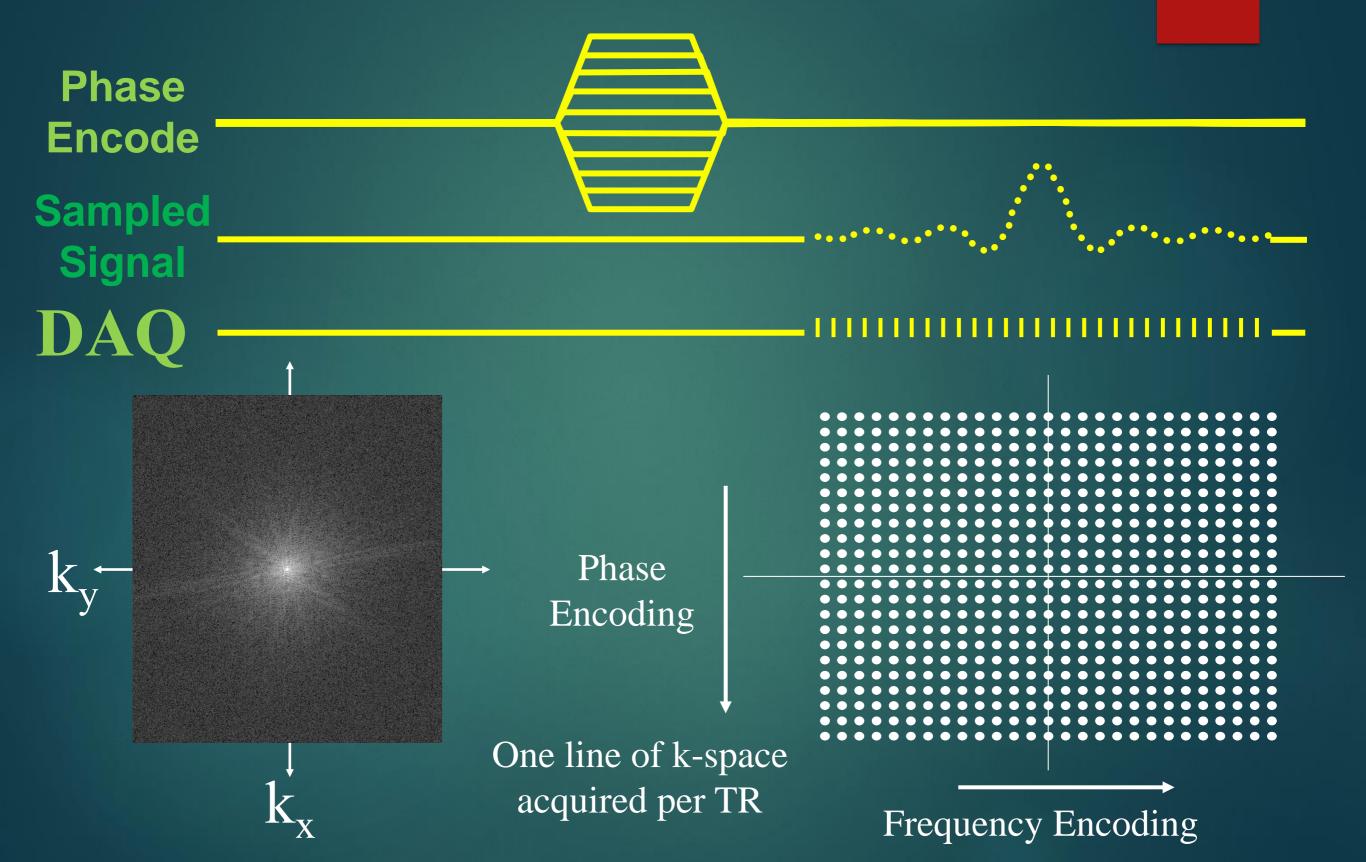
Spatial Encoding/Slice Selection



➤ The effects of the main magnetic field and the applied slice gradient. In this example, the local magnetic field changes in one-Gauss increments accompanied by a change in the precessional frequency from chin to the top of the head.

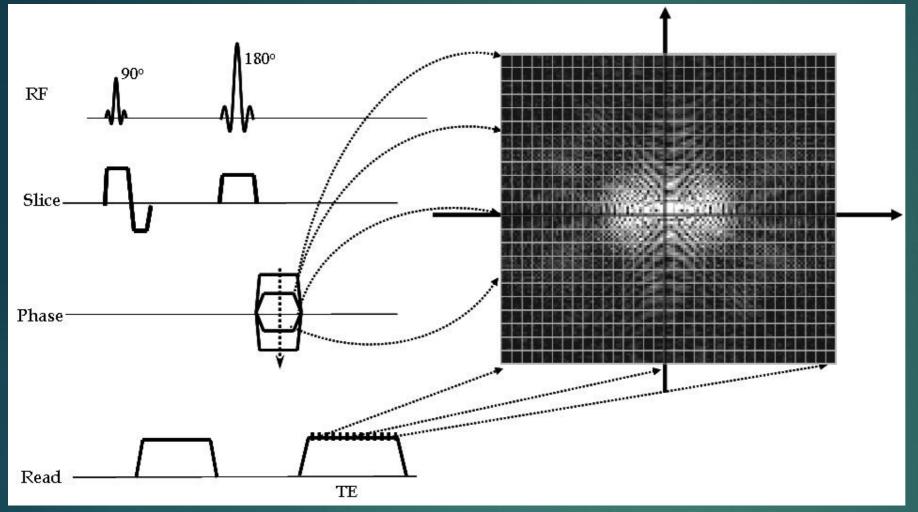
k-Space Acquisition





Kumar Welti Ernst JMR 18;69-83 1975; Edelstein et al. Spin Warp Imaging. PBM 1980

Fourier Zeugmatography/Spin-Warp Imaging



Gradient applied along the yaxis will cause the spins to precess at a frequency determined by their y position, and is called phase encoding. Next a gradient is applied along the x-axis and the spinecho is collected. The frequency components of the echo gives information of the x-position and the phase values give information of the y-position.

$$S(t_x, t_y) = \iint A(x, y) \exp \left[i \left[y(G_x x t_x + G_y y t_y) \right] dx dy \right]$$

$$k_i = \int_{t_i}^{t_i} \operatorname{ad} k_j = \int_{t_i}^{t_i} \left[\int_{t_i}^{t_i} dx dy \right] dx$$

$$S(k_x, k_y) = \iint \mathcal{A}(x, y) \exp \left[i(k_x x + k_y y)\right] dx dy$$

$$\mathcal{A}(x,y) = \iint S(k_x,k_y) \exp\left[-i(k_x x + k_y y)\right] dx dy$$

Kumar Welti Ernst JMR 18;69-83 1975; Edelstein et al. Spin Warp Imaging. PBM 1980





K-Space

For a given data point in k-space, say (kx, ky), its signal S(kx, ky) is the sum of all the little signal from each voxel I(x,y) in the physical space, under the gradient field at that particular moment

$$S(k_x, k_y) = \int \int I(x, y)e^{-i2\pi(k_x x + k_y y)} dxdy$$

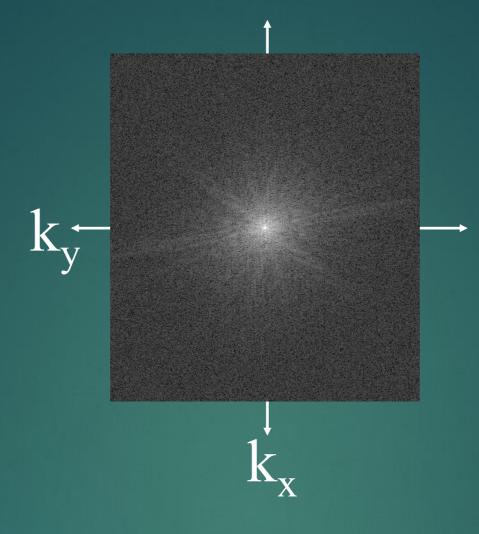
From this equation, it can be seen that the acquired MR signal, which is also in a 2-D space (with kx, ky coordinates), is the Fourier Transform of the imaged object.

$$Kx = \gamma/2\pi \int_0^t Gx(t) dt$$

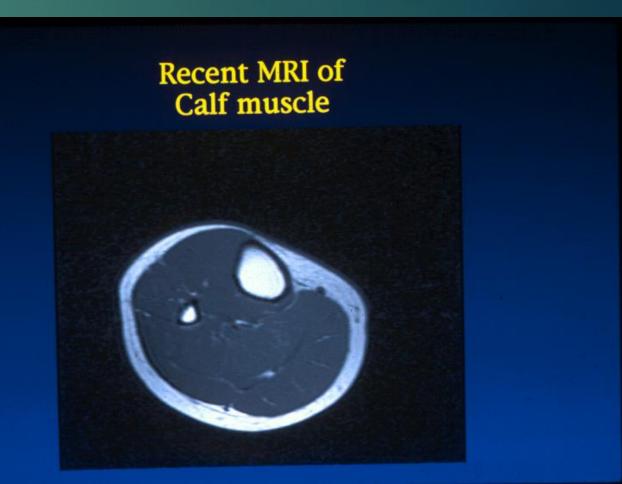
$$Ky = \gamma/2\pi \int_0^t Gy(t) dt$$

The frequency and phase encoding gradients control the imaging trajectory in k-space





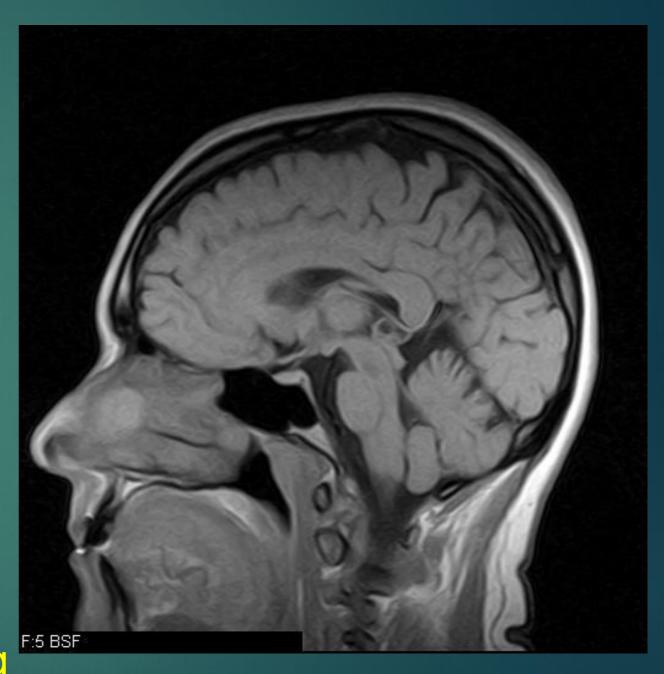




Magnetic Resonance Imaging (MRI)



- MRI exploits Nuclear Magnetic Resonance (NMR) to produce water-based images
 - Signal from ¹H in water
 - Gray scale caused by T1/T2 relaxation and ¹H density within a voxel
- MRI resolution
 - 512x512 voxels in a slice
 - Sub-millimeter voxel volume
- Structural differences cause T1/T2 relaxation variation among voxels

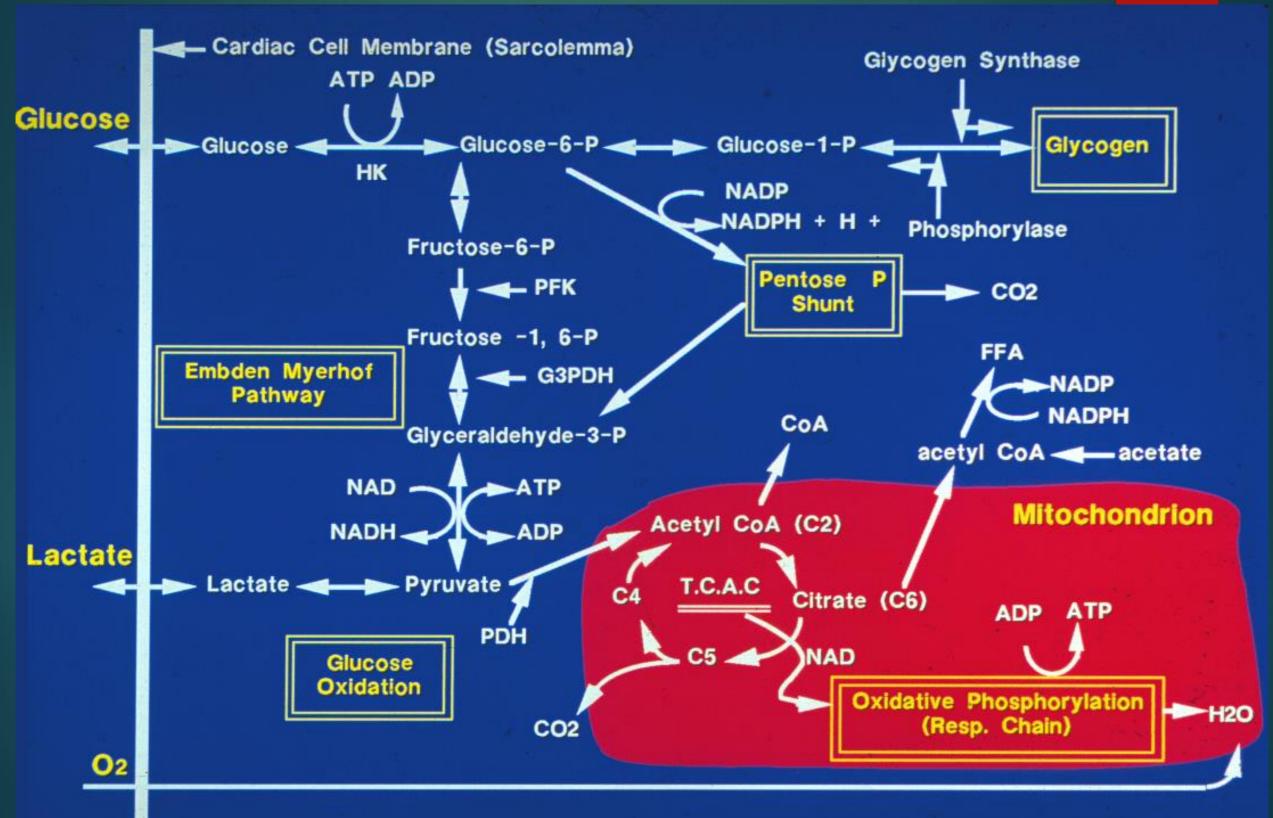


Problems with Anatomical Imaging



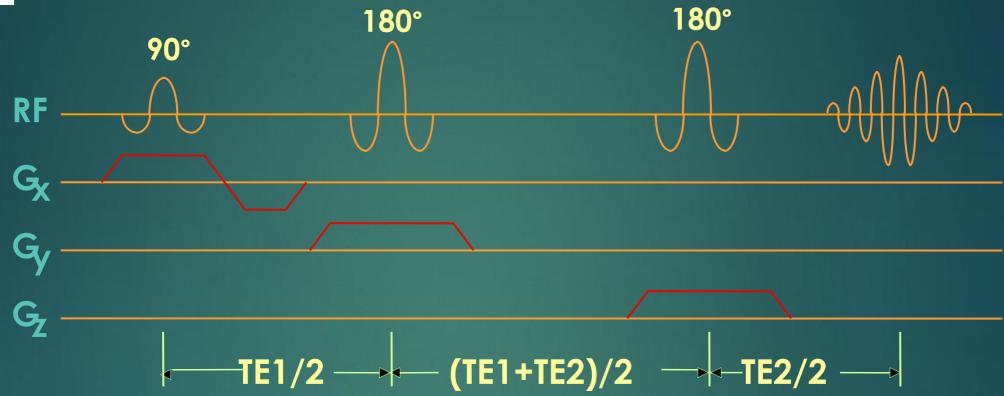
- Despite its superb soft tissue contrast and multiplanar capability, anatomical MRI is largely limited to depicting morphological abnormality.
- Anatomical MRI suffers from nonspecificity. Different disease processes can appear similar upon anatomic imaging, and in turn a single disease entity may have varied imaging findings.
- ► The underlying metabolic or functional integrity of brain cannot be adequately evaluated based on anatomical MRI alone.
- ► To that end, several physiology-based MRI methods have been developed to improve tumor characterization.
- Diffusion Weighted (DW) MRI/Diffusion Tensor Imaging (DTI): In addition to early diagnosis of cerebral ischemia, DW MRI is extremely sensitive in detecting other intracranial disease processes, including cerebral abscess, traumatic shearing injury, etc.
- Perfusion Imaging: Dynamic susceptibility-weighted contrast-enhanced (DSC) perfusion MRI of the brain provides hemodynamic information.
- MR Spectroscopy for biochemical characterization, Improving Specificity of cancer and more







Point Resolved Spectroscopy, PRESS



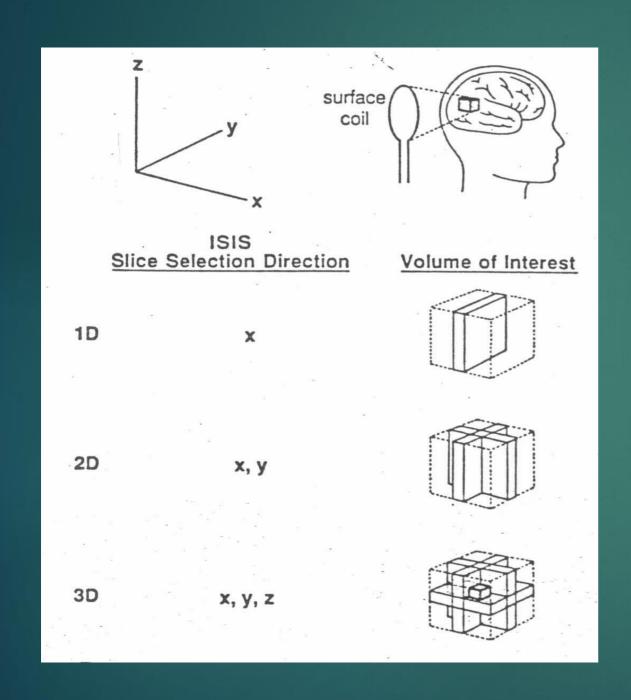
- A slice-selective 90° pulse is followed by two sliceselective 180° refocusing pulses
 - > Achieves localization within a single acquisition
 - \triangleright Suitable for signals with long $T_2 {}^1H$ MRS

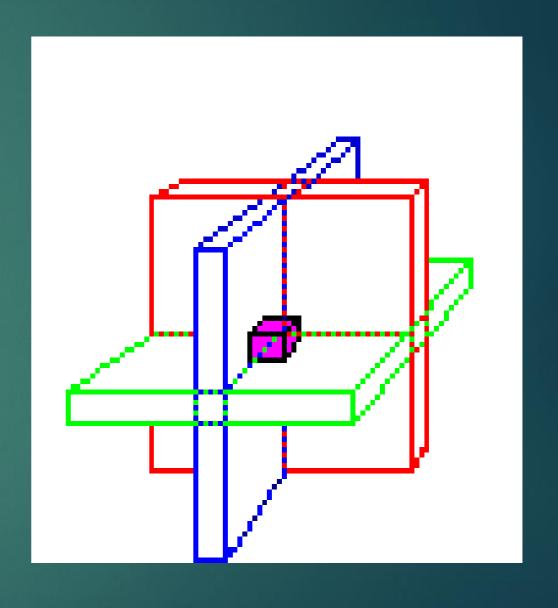
Bottomley PA. Annal NY Acad Sci 1987; 508: 333-348.

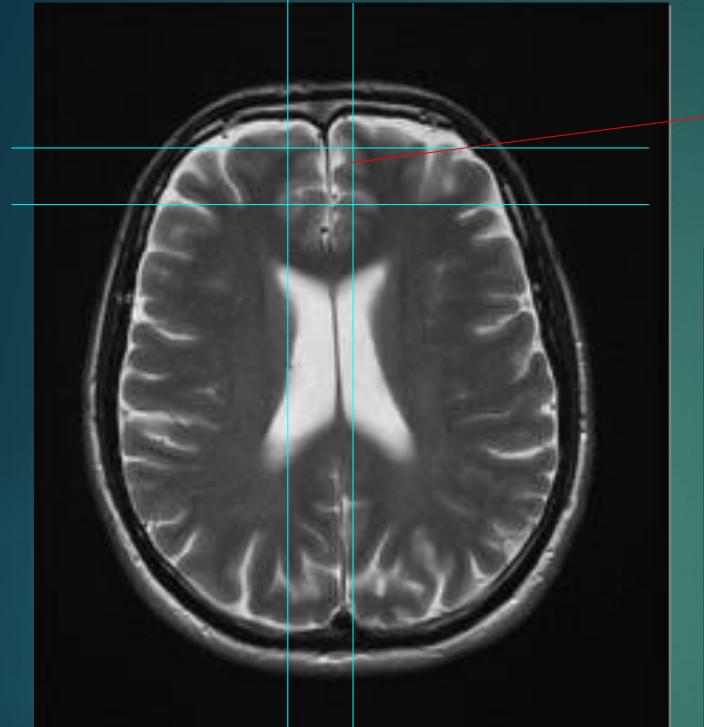
STEAM: Frahm MRM 1989

Localization





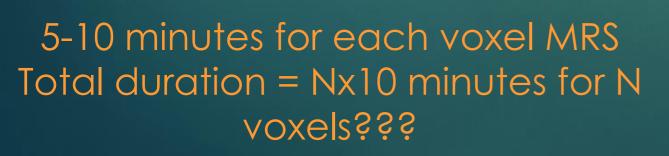


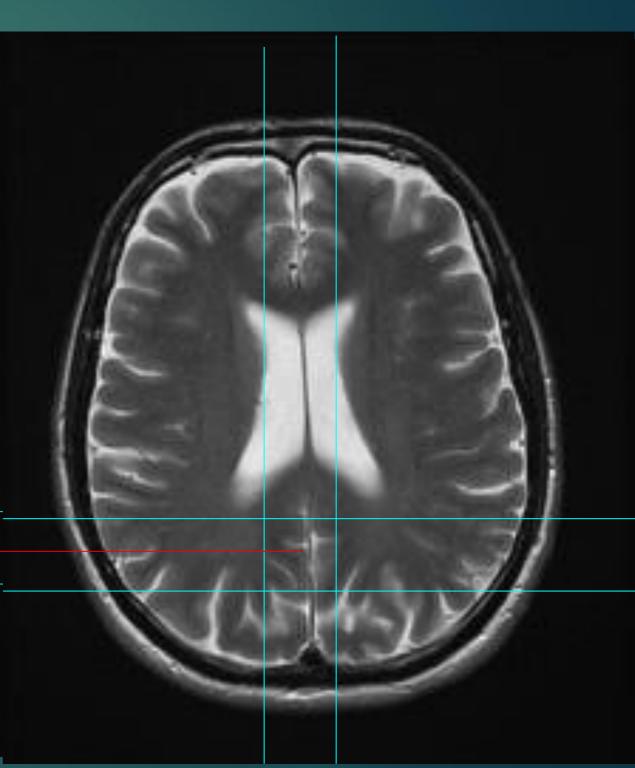


Frontal Gray



Occipital Gray -





Single Voxel Spectroscopy



disadvantages

- requires large sample volume (2x2x2 cm³ or more)
- requires many averages for adequate SNR
- limited coverage
- can only cover a small region in one experiment



Multi-Voxel Spectroscopy

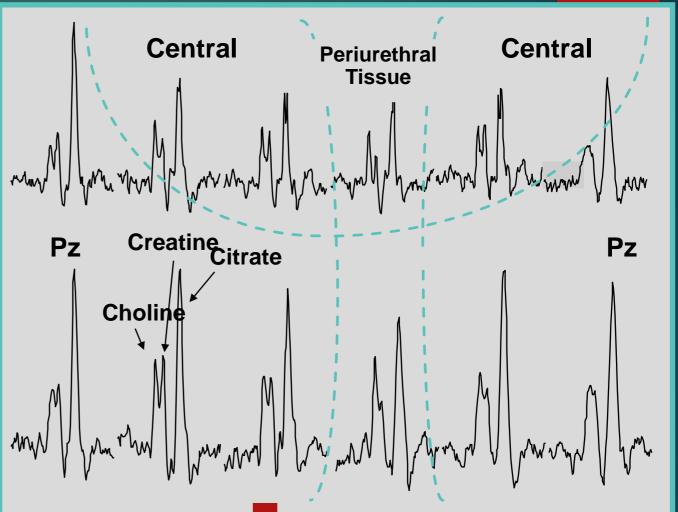
the problem of limited coverage can be fixed by taking conducting multiple experiments from different locations

this is problematic as the total experimental time will scale with the number of different voxels you wish to measure

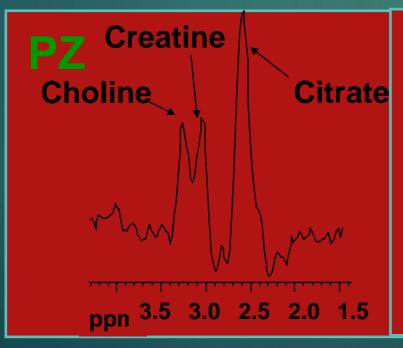
Spectral Characteristics from different zones Healthy (<40 years) Volunteer

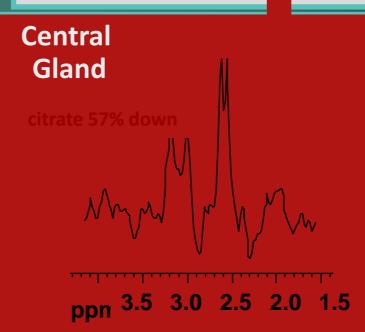


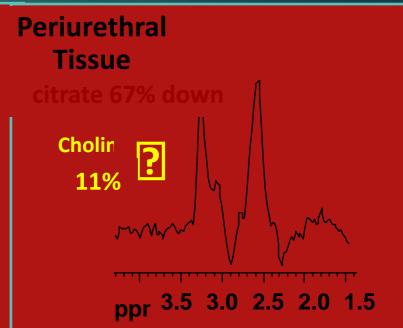




Three
Distinctive
Metabolic
Patterns







Proc. Natl. Acad. Sci. USA Vol. 79, pp. 3523–3526, June 1982 Biophysics

NMR chemical shift imaging in three dimensions

(in vivo biochemistry/31P imaging/metabolite mapping)

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*Bell Laboratories, Murray Hill, New Jersey 07974; and †Department of Biochemistry, Columbia University, New York, New York 10032

Communicated by John J. Hopfield, March 10, 1982

ABSTRACT A method for obtaining the three-dimensional distribution of chemical shifts in a spatially inhomogeneous sample using Fourier transform NMR is presented. The method uses a sequence of pulsed field gradients to measure the Fourier transform of the desired distribution on a rectangular grid in (k,t) space. Simple Fourier inversion then recovers the original distribution. An estimated signal/noise ratio of 20 in 10 min is obtained for an "image" of the distribution of a 10 mM phosphorylated metabolite in the human head at a field of 20 kG with 2-cm resolution.

the resonant frequency of the spins) varying linear gradient, $[G(t)^*x]\hat{z}$, as shown in Fig. 1, how will this affect the FID? Under these conditions, the phase of each spin at time t after a rf pulse will depend on both x and δ as its instantaneous frequency is now given by $\frac{d\phi}{dt} = \gamma H_T(t)$, where γ is the gyromagnetic ratio for the species under observation and $H_T(t) = [H_o + G(t)^*x](1$

 $+ \varepsilon$). Here we have just augmented the externally applied field, $H_{-} + G(t) \cdot x$, by $(1 + \varepsilon)$ to take into account the electronic shield-

MRSI/csi



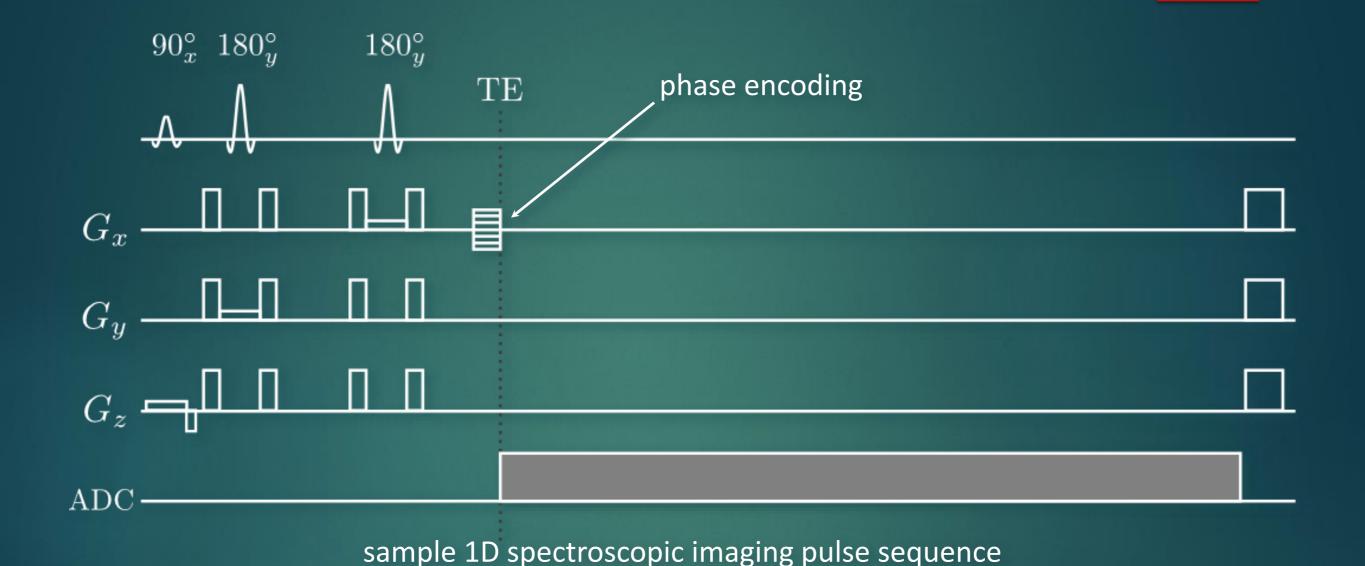
greater coverage can be obtained by spatially encoding time signals with phase-encoding gradients

phase-encoded data is encoded in k-space

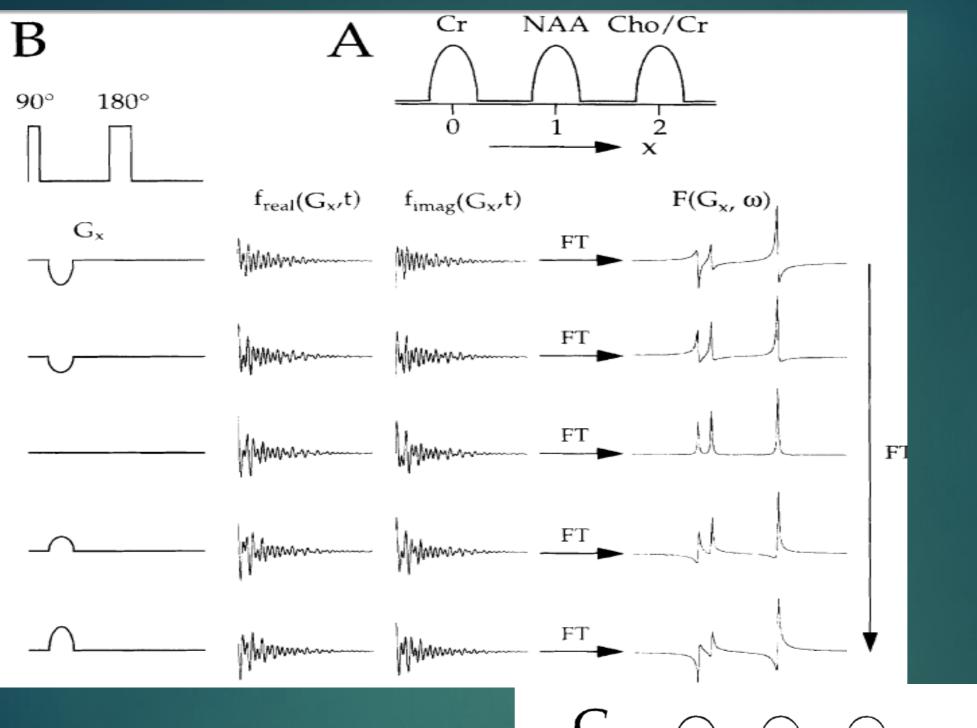
this allows for more voxels to be collected in a single experiment as well as smaller voxels

1D Spatial Encoding



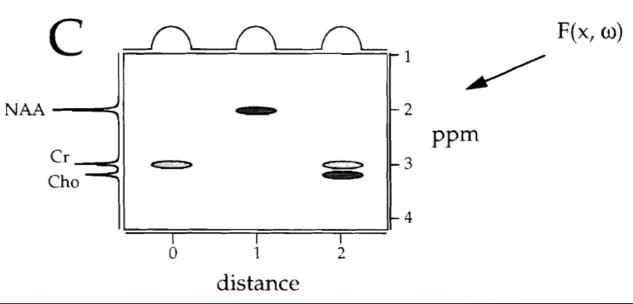


each FID is phase encoded along one dimension





Resulting SI data set After FFT along x and t we get



2D Spectroscopic Imaging



how do we fill out 2D k-t-space?



same as before except phase encoding happens in two different dimensions now

Spatial Encoding

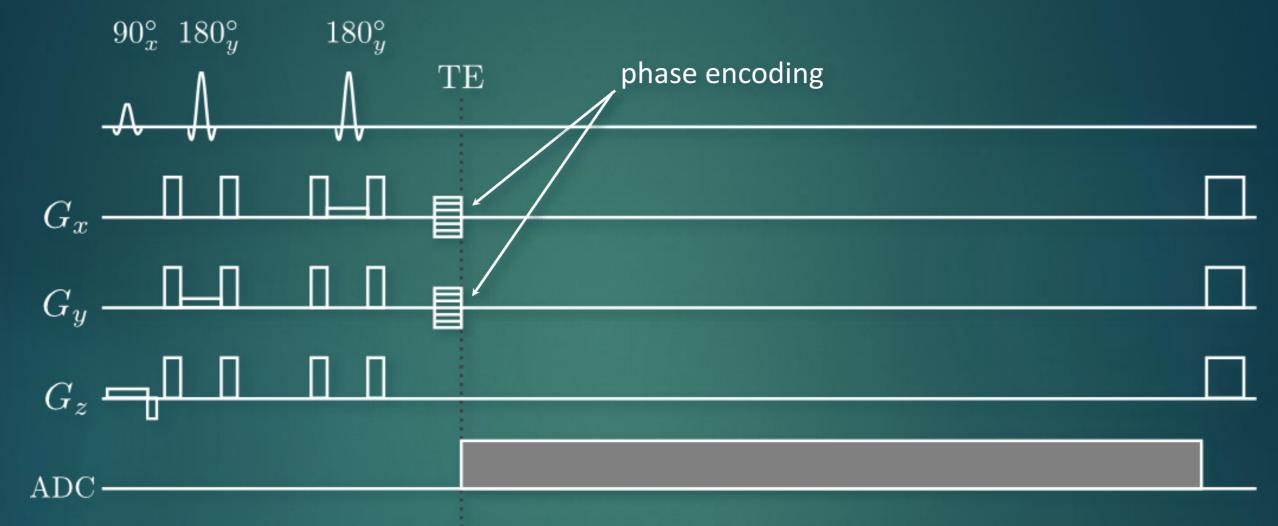
how do we use gradients to move around k-space?

$$\vec{k}(t) = \frac{\gamma}{2\pi} \int_0^t \vec{G}(\tau) d\tau$$

we can move anywhere in k-space so long as we program our gradients correctly

2D Spatial Encoding



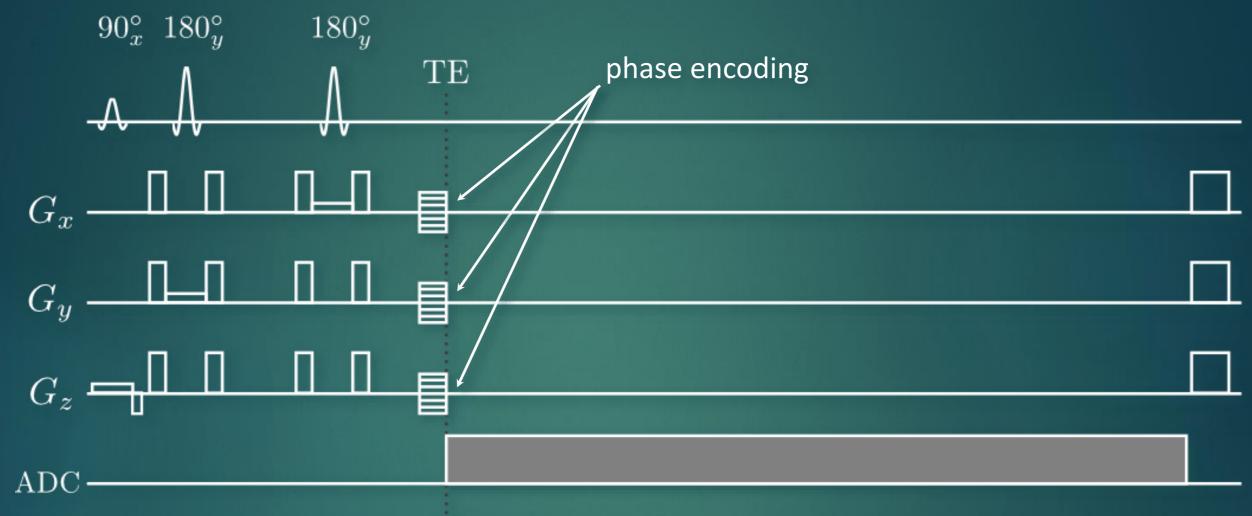


sample 2D spectroscopic imaging pulse sequence

each FID is phase encoded along one dimension

3D Spatial Encoding





sample 3D spectroscopic imaging pulse sequence

each FID is phase encoded along one dimension

Brown 1982 Maudsley 1984

Sampling Considerations



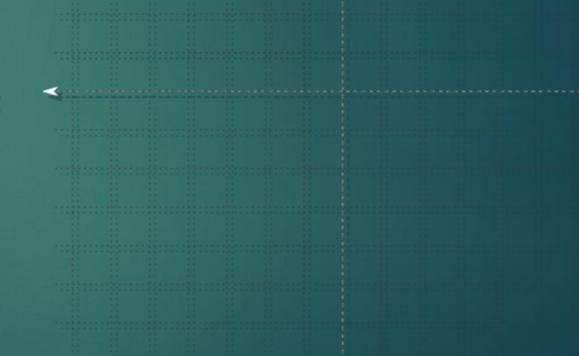
constant time, vary amplitude

$$\Delta k_x = \frac{1}{\text{FOV}_x} \quad \Delta k_y = \frac{1}{\text{FOV}_y}$$

$$k_x = n\Delta k_x = \frac{n_x}{\text{FOV}_x} = \gamma G_x t$$

$$k_y = n\Delta k_y = \frac{n_x}{\text{FOV}_y} = \gamma G_y t$$

$$G_x = \frac{n_x}{\gamma FOV_x t} G_t = \frac{n_t}{\gamma FOV_y t}$$



MRSI

Each k-space point is individually collected on a cartesian grid

Image data is obtained by applying 2D FFT along spatial dimensions

Total acquisition time is thus $N_x \times N_y \times \mathrm{TR} \times \mathrm{NEX}$

$$lack k_y$$
 $lack x imes x$

3D Spatial Encoding

the amount of time for a CSI scan is thus $N_x \times N_y \times N_z \times \text{TR} \times \text{NEX}$

for a 32x32x1 scan (2D) with a TR = 1s and 1 average, the scan time is 17 minutes

for a 32x32x16x1 scan (3D) with a TR = 1s and 1 average, the scan time is 4.5 hours

without acceleration techniques, CSI is very slow and inefficient (and low res)

CHESS (global)

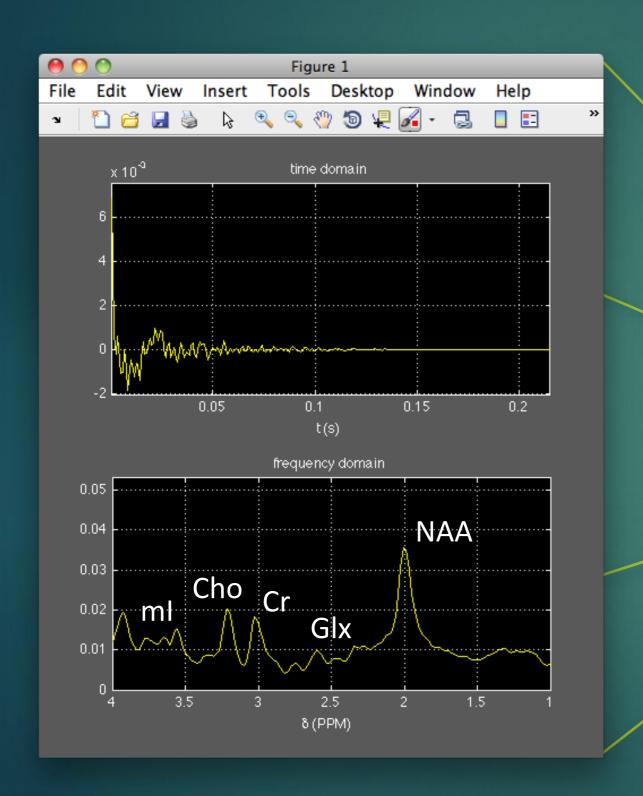
OVS(slice localized)

3D STEAMCSI PRESSCSI Data
Acquisition
(N*\Deltat)

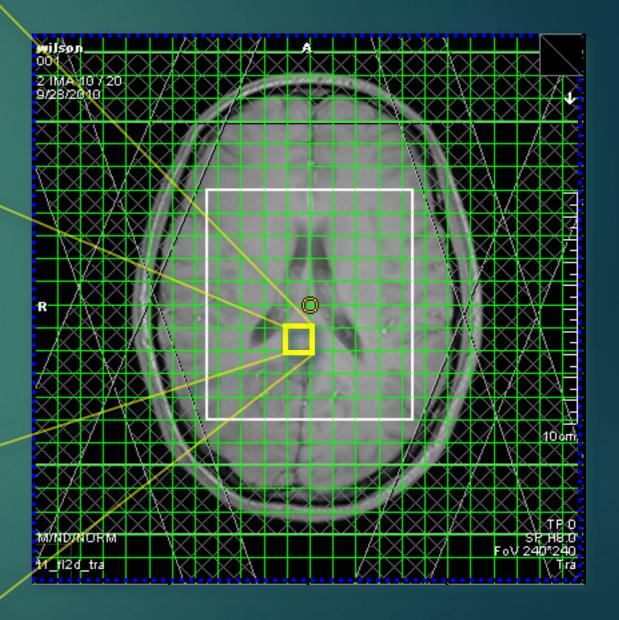
Recovery
Time
(TR)

MR Spectroscopic Imaging (2-3 Phase Encoded)





localized spectra



MR Spectroscopic Imaging (Co

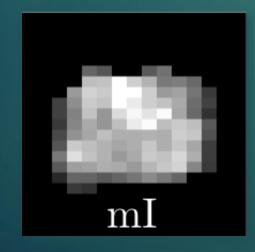




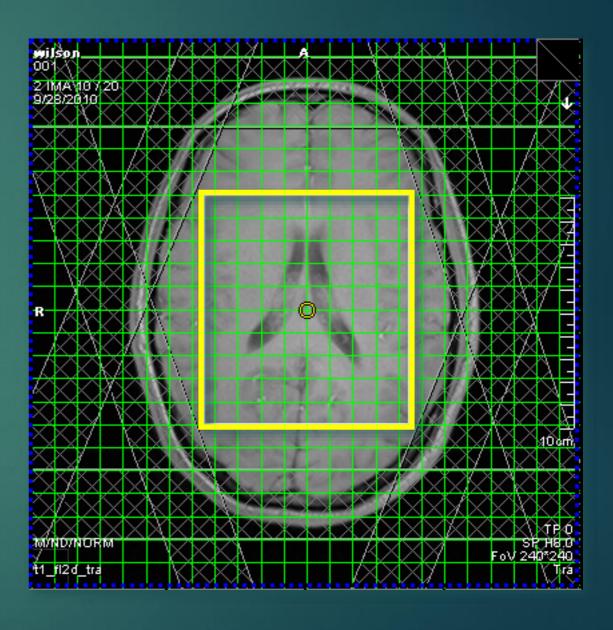




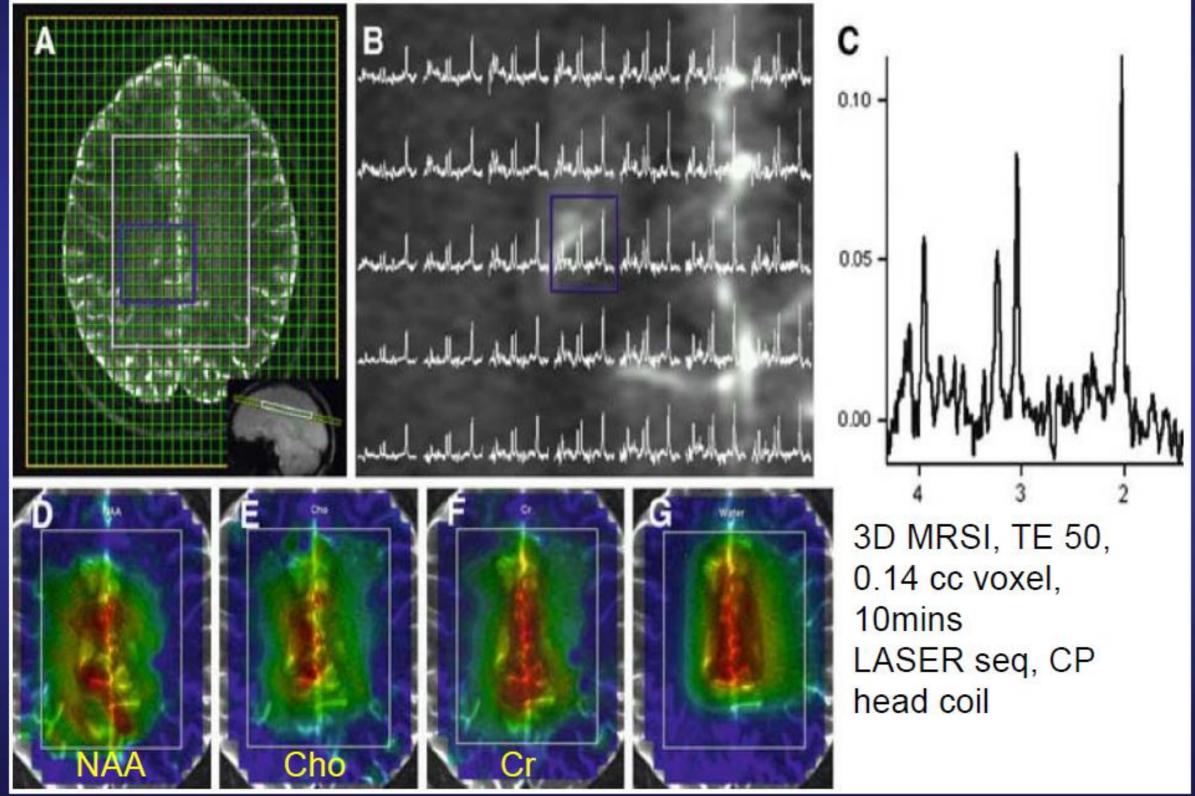




metabolite maps



High resolution metabolite maps





Metabolic mapping quality – 3T vs 7T

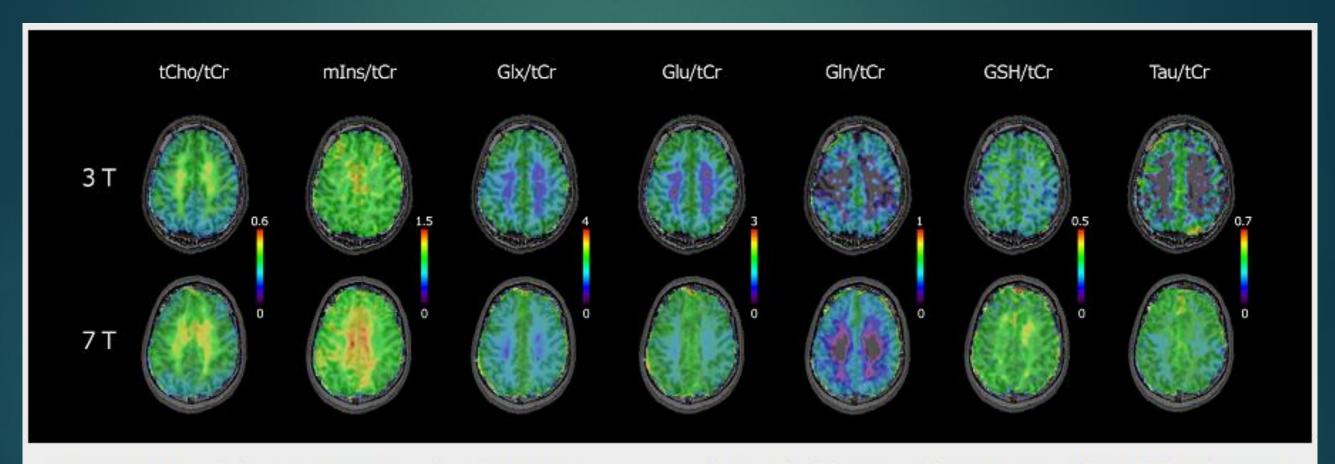


Figure 4. Metabolic maps acquired with FID-MRSI at 3T and 7T. Reliable quantification over the whole slice was possible for Glu/tCr, Gln/tCr, GSH/tCr and Tau/tCr at 7T but not at 3T. Values are displayed in a.u.

Heckova et al. ISMRM 2016



How long does it take to perform a multi- voxel 2D/3D MRSI?

2D MRSI (2 spatial+1spectral): Total duration = TR*NEX*Nx*Ny =1s*1*32*32= 17 minutes

3D MRSI (3 spatial+1spectral):
Total duration = TR*NEX*Nx*Ny*Nz
=1s*1*32*32*16= 4.53 hours
=1s*1*16*16*8= 34 minutes

Acceleration Techniques



The goal

- to reduce the number of excitations in order to reduce the total scan time (1-10 minutes)
- The strategies
- Selective Averaging
- Parallel Imaging
- Turbo Spin Echo (TSE) techniques
- Echo-Planar (EP) techniques
- Concentric Ring Trajectories (SI-CONCEPT)
- Radial (Golden Angle View Ordering) and TV regularizer

Fast MRSI

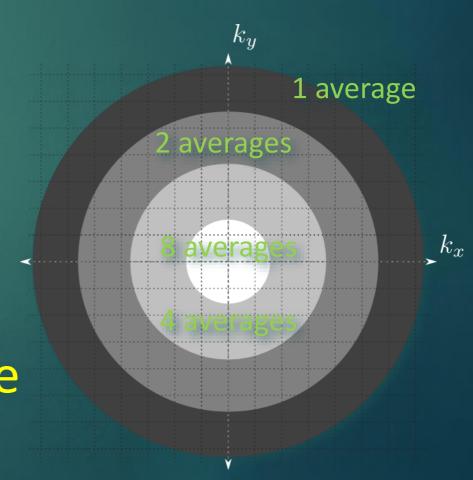


- Elliptical weighting
 - Reduced spatial sampling of k-space with only the central ellipsoid being acquired (reduction factor typically = 2)
- Parallel Imaging Reconstruction
 - Reduced acquisitions of k-space by increasing the spacing between k-space samples. Additional spatial information from multiple receiver coils is then used to increase the spatial FOV to the original size.

Selective Averaging

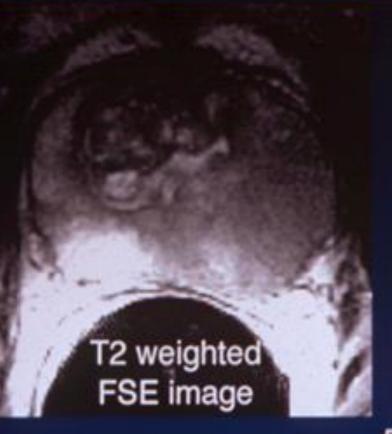
Average the parts of kspace with greater intensity

Significantly reduces total scan time

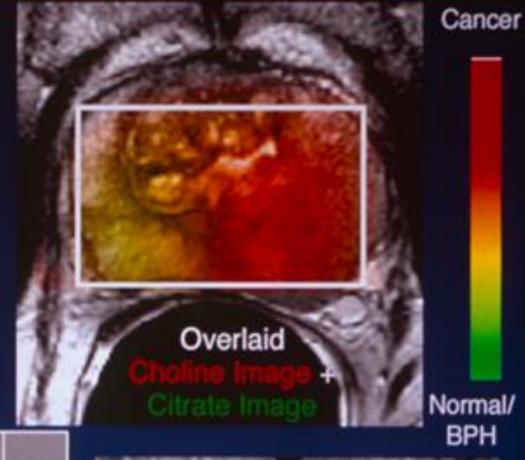


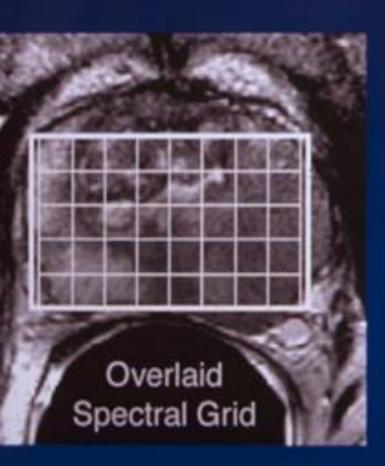
MRI/MRSI Data Display

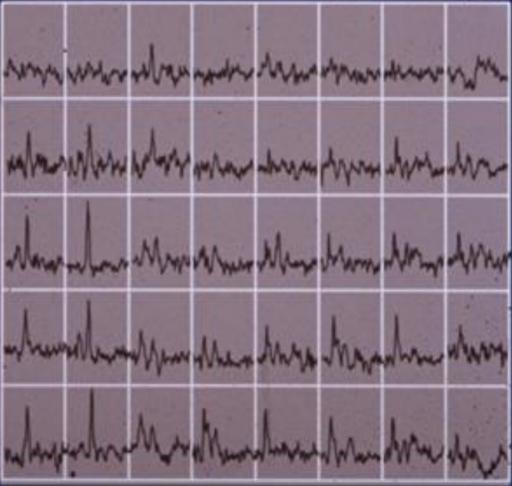


















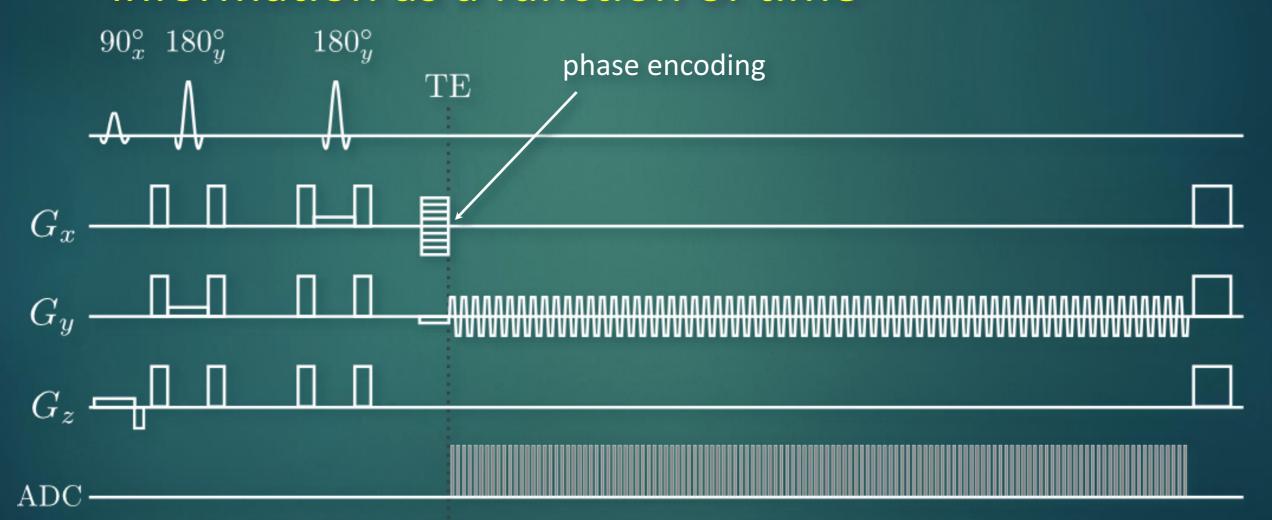
Multi-coil reconstruction (SENSE/GRAPPA)

advantages

- reduced scan timedisadvantages
- reduced SNR from reduced number of excitations

Echo-Planar Spectroscopic Imaging (EPSI)

echo-planar spectroscopic imaging uses a repeated time-varying readout gradient to collect the same spatially encoded information as a function of time



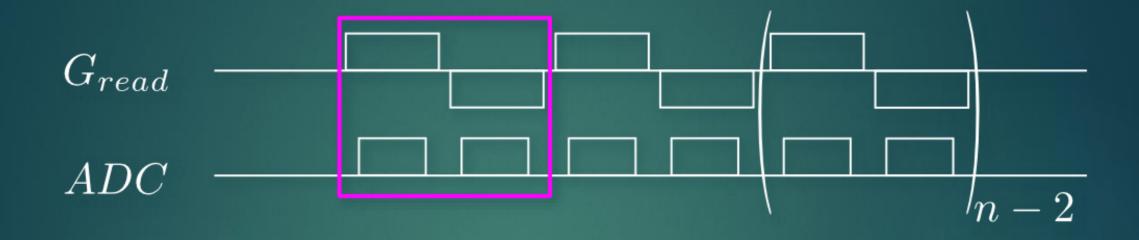
what is the effect of the repeated bipolar gradient readout?

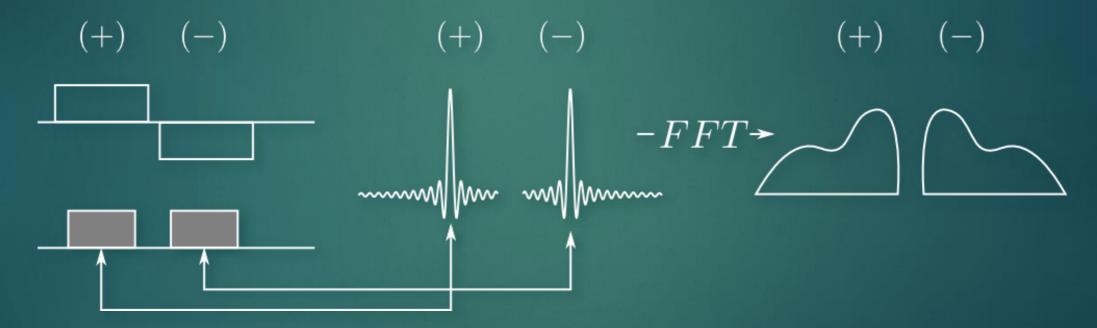
Mansfield 1984, Posse 1994, Lipnick 2008



Echo-Planar SI



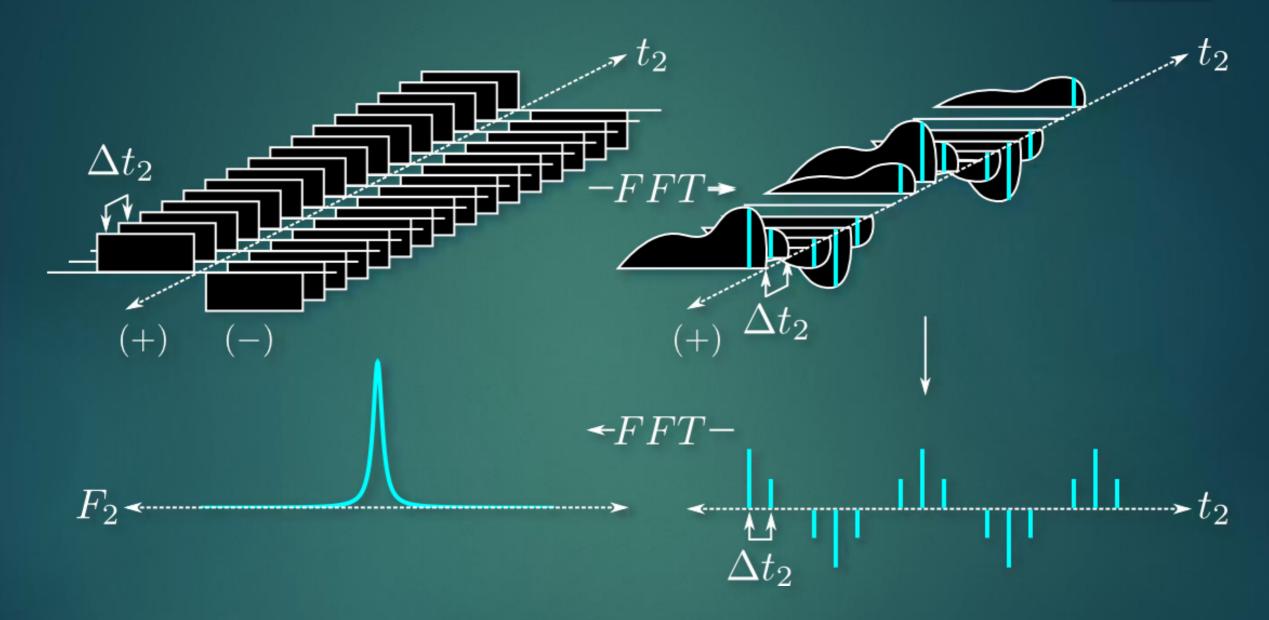




two sets of echoes (odd and even) form which are mirror images of each other

Echo-Planar SI





the repeated nature of the readout gradients spatially encodes as a function of time

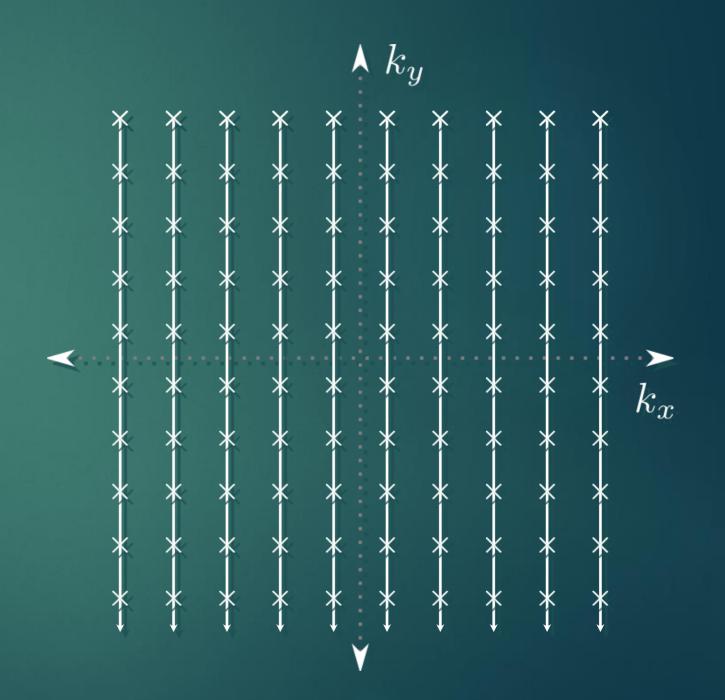
EPSI



A single line in k-space is collected in a single excitation

Image data is obtained by applying 2D FFT along spatial dimensions

Total acquisition time is thus $N_x imes \mathrm{TR} imes \mathrm{NEX}$



Echo-Planar SI



the amount of time for a MRSI scan is thus $N_x imes N_z imes {
m TR} imes {
m NEX}$

for a 32x32x16 scan (3D) with a TR = 1s and 1 average, the scan time is 8.5 minutes

Using all 3 phase-encoding, 3D MRSI (3 spatial+1spectral): Total duration = TR*NEX*Nx*Ny*Nz =1s*32*32*16= 4.5 hours

significant reduction in scan time!

Echo-Planar SI

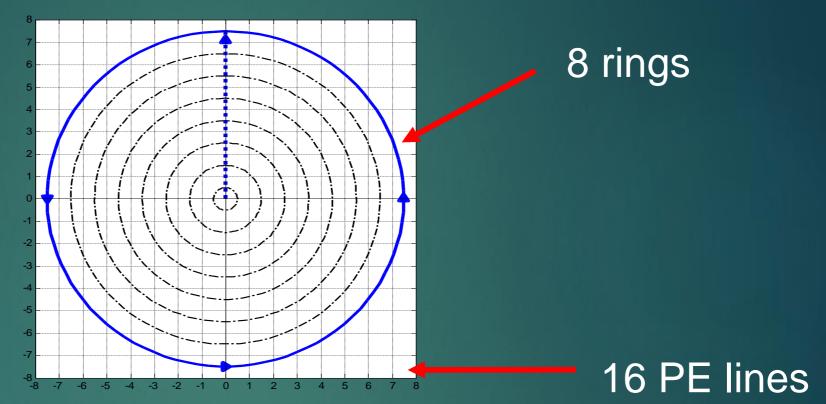


advantages

- significantly reduced scan timedisadvantages
- echo-planar readout creates undesired eddy currents which can distort spectra
- reduced SNR from reduced number of excitations
- very demanding on the hardware (reduced spectral bandwidth)



Why Concentric Circular sampling?



- ► More efficient k-space sampling due to symmetry of concentric circles → half the number of excitations required for similar k-space coverage
- Outer corners of k-space contain little signal and are usually filtered away anyway



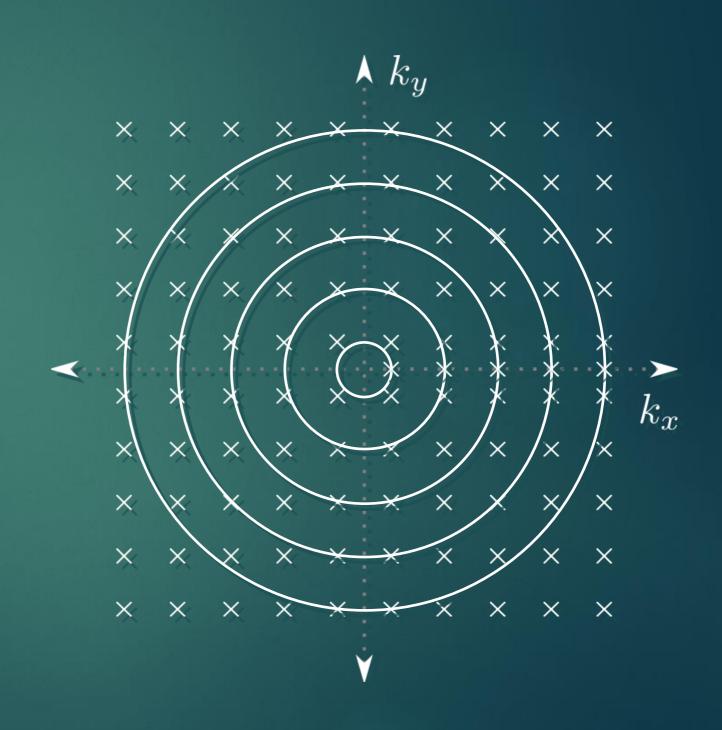
Concentric Circles (SI-CONCEPT)

A single ring in k-space is collected in a single excitation

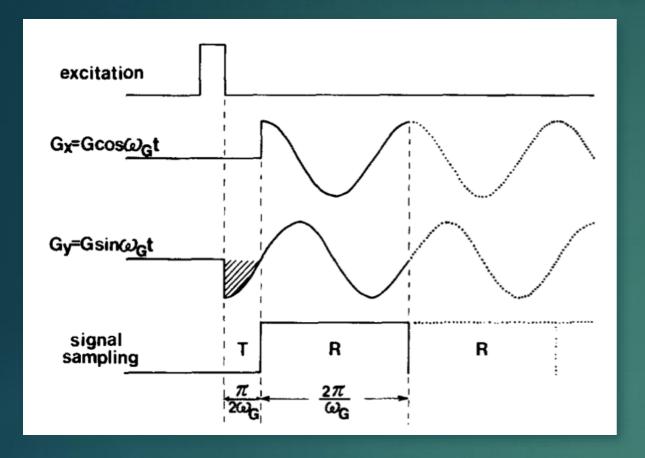
Image data cannot be processed by 2D FFT since it is not cartesian

Total acquisition time is thus

$$\frac{1}{2}N_x \times \text{TR} \times \text{NEX}$$



What is Concentric Circular?



Circular k-space trajectory defined

$$k_x(t) = -k_n \sin(\frac{2\pi}{T}(t - TE))$$

$$k_{y}(t) = + k_{n} \cos(\frac{2\pi}{T}(t - TE))$$

where k_n is the radius of the nth ring and T is the spectral dwell time in the direct dimension

Gradient waveforms are thus given by

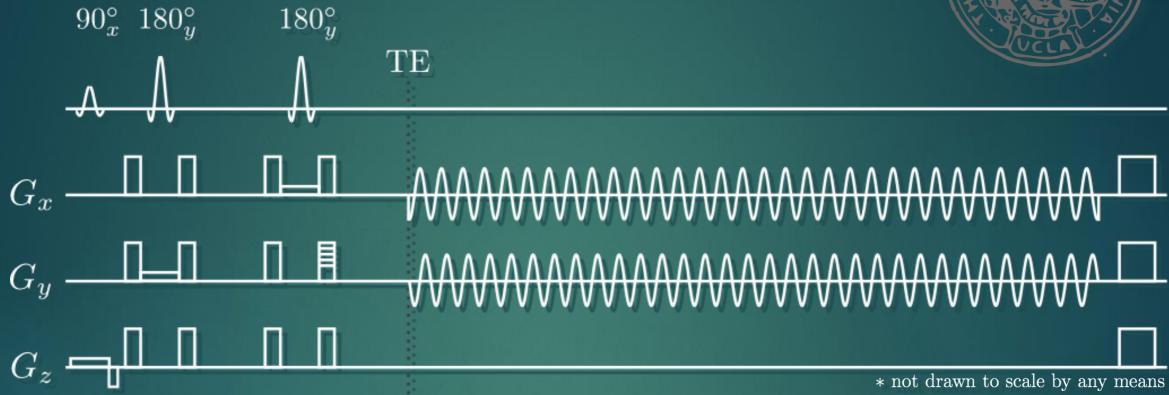
$$G_x(t) = -\frac{4\pi^2 k_n}{\forall T} \cos(\frac{2\pi}{T}(t - TE))$$

$$G_{y}(t) = -\frac{4\pi^{2}k_{n}}{\sqrt{T}}\sin(\frac{2\pi}{T}(t-TE))$$

JK Furuyama, NE Wislon, MA Thomas MRM 2012

SI-CONCEPT Pulse Sequence





The use of a concentric k-space trajectory is readily applied to ordinary CSI sequences

Repeatedly tracing the same circle in k-space encodes both spatial and spectral information

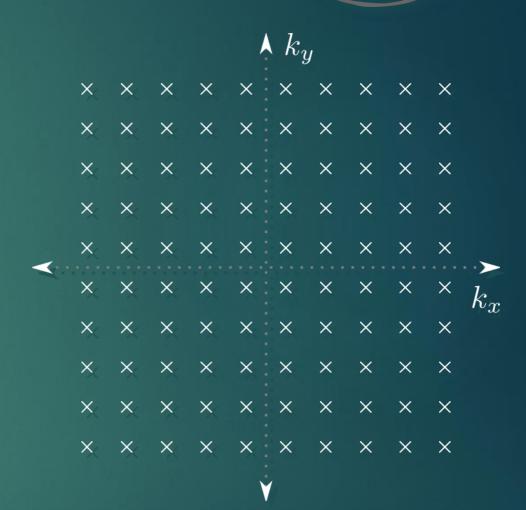
Concentric Circles

Convert polar data to cartesian?



how?

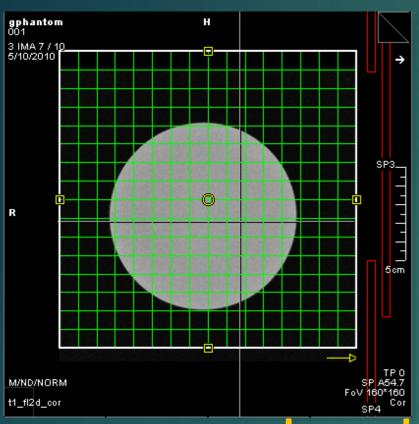
Gridding takes any arbitrary k-space trajectory and convolves it onto a cartesian grid

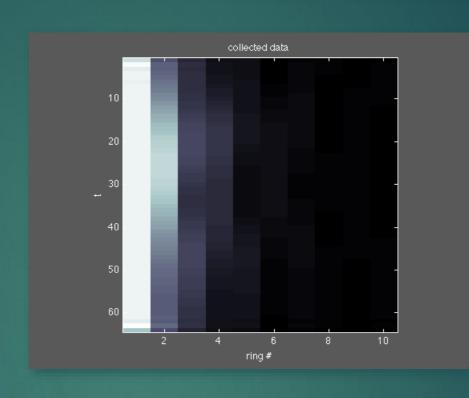


Jackson 1991 Adalsteinsson 1998 Furuyama, 2012

Concentric Circular Imaging - Polar Data

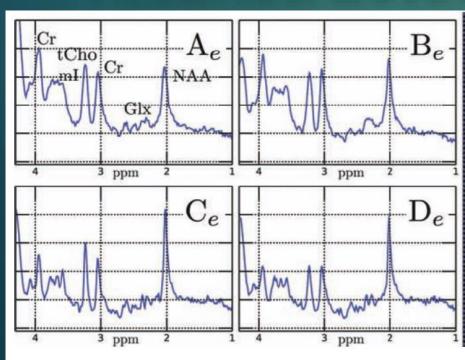


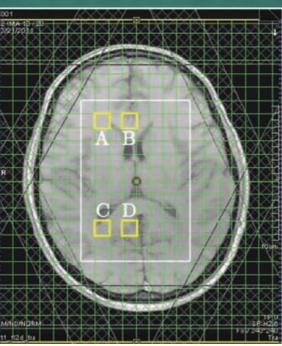


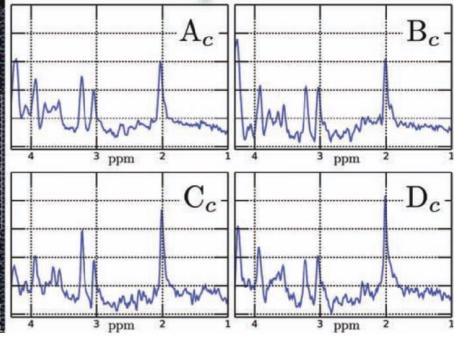


JK Furuyama, NE Wislon, MA Thomas MRM 2012

- reconstructed Human Brain Spectra







MRSI vs. EPSI vs. SI-CONCEPT

$$N_x \times N_y \times \mathrm{TR} \times \mathrm{NEX}$$
 -MRSI



-EPSI

$$\frac{1}{2}N_x \times \text{TR} \times \text{NEX}$$

-SI-CONCEPT

Faster!



Hingerl et al. Inv Rad. 2020
....Brain coverage among all
measured matrix sizes ranging
from a 32 × 32 × 31 matrix with
6.9 × 6.9 × 4.2 mm nominal voxel
size acquired in ~3 minutes to an
80 × 80 × 47 matrix with 2.7 ×
2.7 × 2.7 mm nominal voxel size
in ~15 minutes for different
brain regions.

Emir and coworkers, MRM 2020
"A density-weighted concentric-ring trajectory metabolite-cycling MRSI technique was implemented to collect data with a nominal resolution of 0.25 mL within 3 minutes and 16 seconds."

Advantages of Concentric Circular Trajectories

- Less demanding on gradient hardware → higher spectral BW achievable (required at higher field strengths to prevent spectral aliasing)
- Eddy currents not as severe especially for inner k-space data
- Continuous readout during acquisition (EP-COSI without ramp sampling only samples during ~75% readout)
- Inherently less sensitive to motion artifacts
- Lower maximum slew rates for equal resolutions and spectral BW
 - (> 50% less for actual scan parameters used)

Drawbacks

- Sampling during time-varying readout gradients leads to increased noise variance¹
 - SNR gains from averaging compensate so that sensitivity per time in both sequences is similar
 - More complicated post-processing
 - Data must be regridded in order to apply FFT
 - Alternatively, projection-reconstruction (PR) algorithms can be applied using inverse radon transform

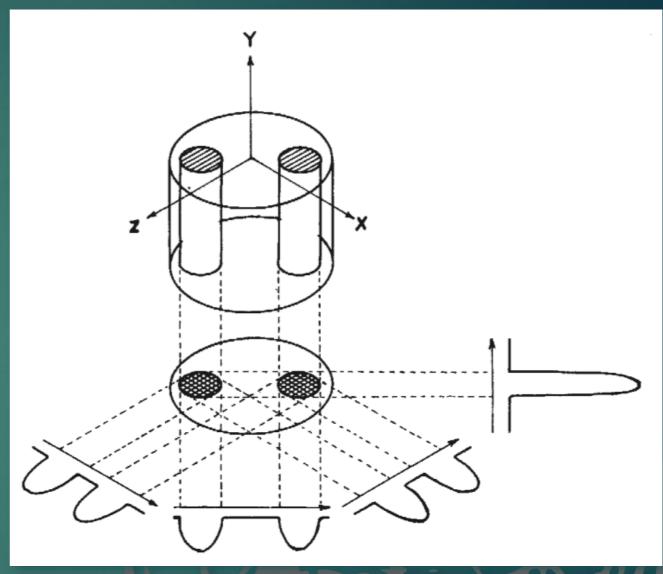


Emir 2017; Chew 2018; Steel 2018;; Kodibagkar 2019; Hingerl 2020

Further Acceleration??? Projection Reconstruction/Radial

Original MRI Sequence

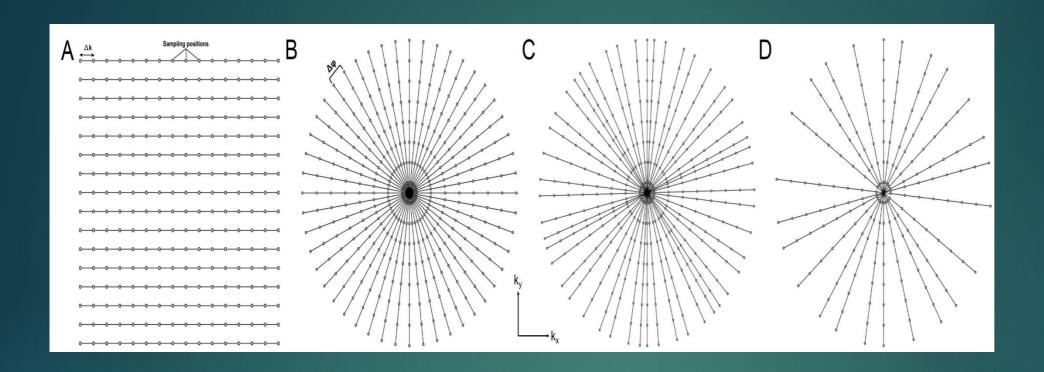




Lauterber P, Nature 242, 190-191 (1973)

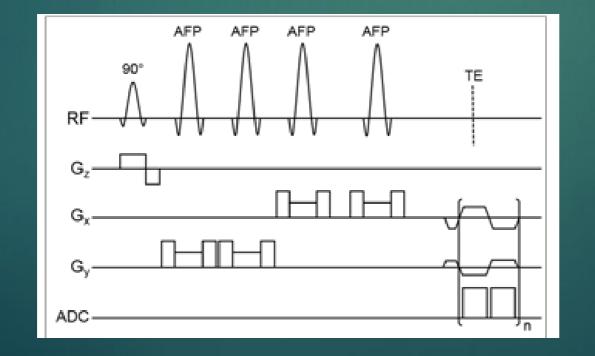
Series of projections taken at different angles

Radial Spectroscopic Imaging



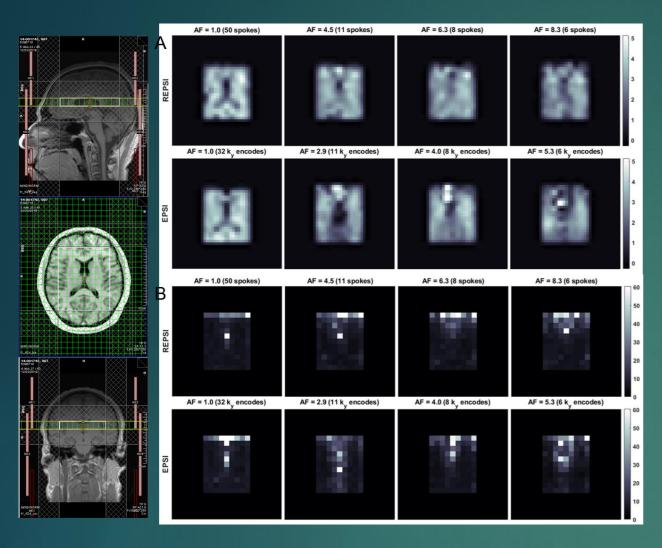


Sampling schemes using (**A**) Cartesian encoding; (**B**) radial encoding; (**C**) Golden angle radial projections successively incremented by 111.25°, Δ k=FOV. No of spokes, n_s =(π /2)*n, where n = base resolution, distance between spokes < Δ k. (D) Undersampled radial acquisition (2X) compared to (C).



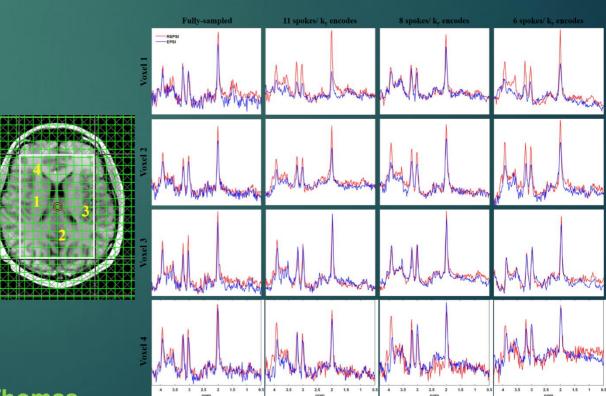
Saucedo, M. Sarma, MA Thomas ISMRM 2020 MRM 2021

Radial Spectroscopic Imaging



(Left) VOI localization in a 33 year-old healthy male volunteer. (A) tNAA maps from fully-sampled (AF = 1.0) REPSI and EPSI brain data (leftmost column), and tNAA maps from CS reconstructions of prospectively undersampled brain data acquired with 11, 8, and 6 radial spokes or k_y -lines. These maps are interpolated by a factor of two. (B) CRLB maps for the tNAA maps shown in (A).

Representative and CS reconstructions of prospectively undersampled *in vivo* brain data from a 32 year-old healthy male volunteer. Spectra extracted: 1 - right putamen to corona radiata, 2 - occipital gray matter, 3 - left posterior insular cortex, and 4 - frontal white matter. Both the REPSI and EPSI data were prospectively undersampled with 11, 8, and 6 acquired radial spokes or k_y -lines, respectively.



A. Saucedo, M. Sarma, MA Thomas MRM 2021

Rosette-Trajectories-based Spectroscopic Imaging (ROSE-SI)



A single petal in k-space is collected in a single excitation

Rosette trajectory is defined as

$$k(t) = k_{max} \sin(\omega_1 t) e^{i\omega_2 t}$$

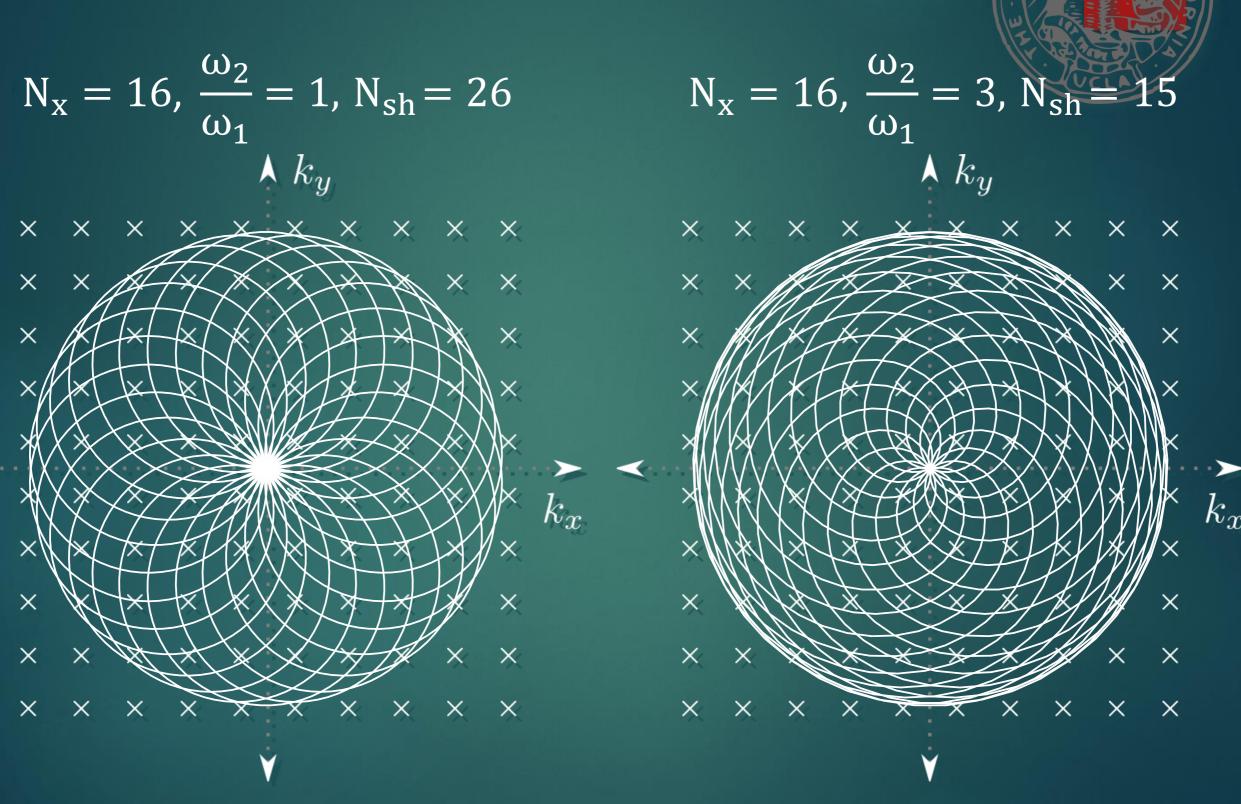
Total acquisition time depends on the radial oscillation frequency (ω_1) and the rotational frequency (ω_2)

$$k_x$$

$$\frac{\omega_2}{\omega_1} \le 1$$
, $N_{sh} \cong \frac{\pi \times N_x}{\sqrt{1 + 3 \times (\omega_2/\omega_1)^2}}$

$$\frac{\omega_2}{\omega_1} > 1$$
, $N_{sh} \cong \frac{\pi \times N_x}{\sqrt{3 + (\omega_2/\omega_1)^2}}$

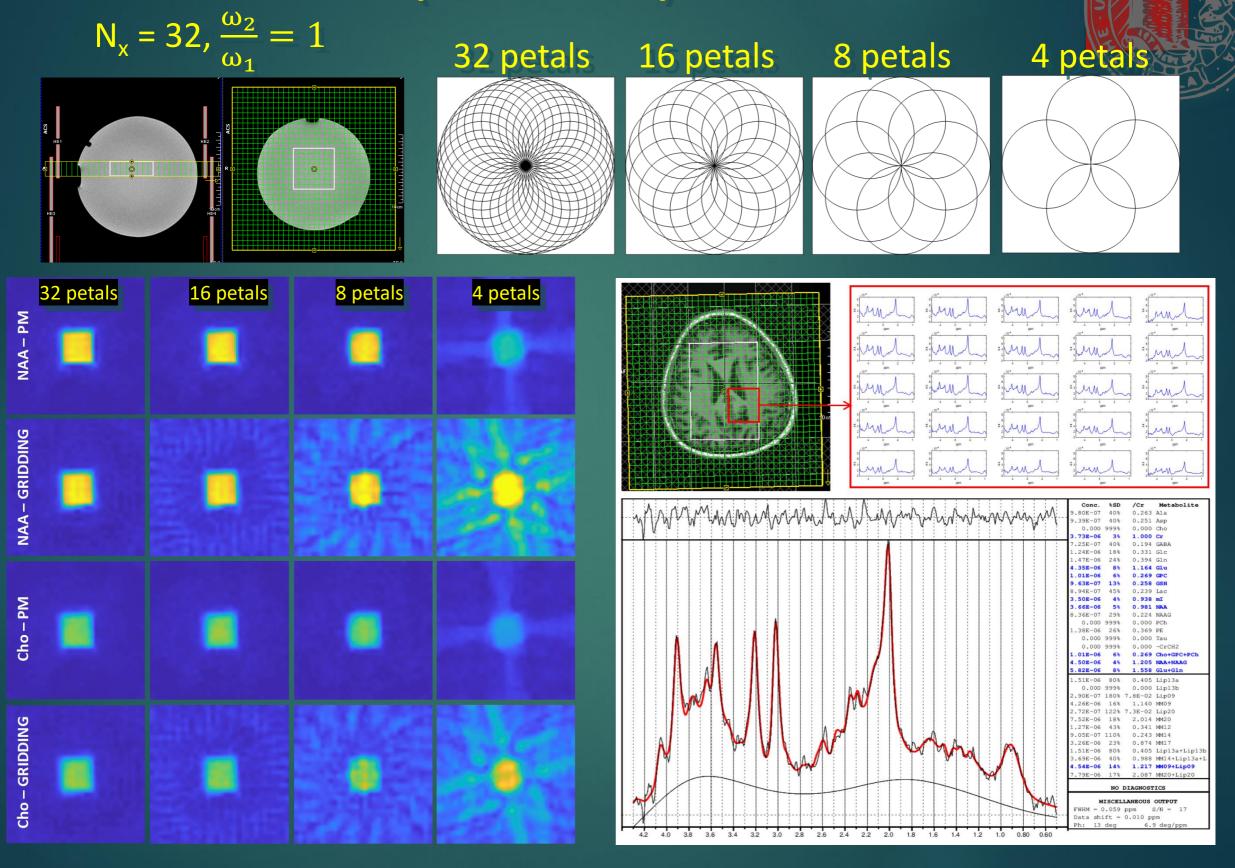
Rosette Petals (ROSE-SI)



Needs 26 petals for $N_x = 16$

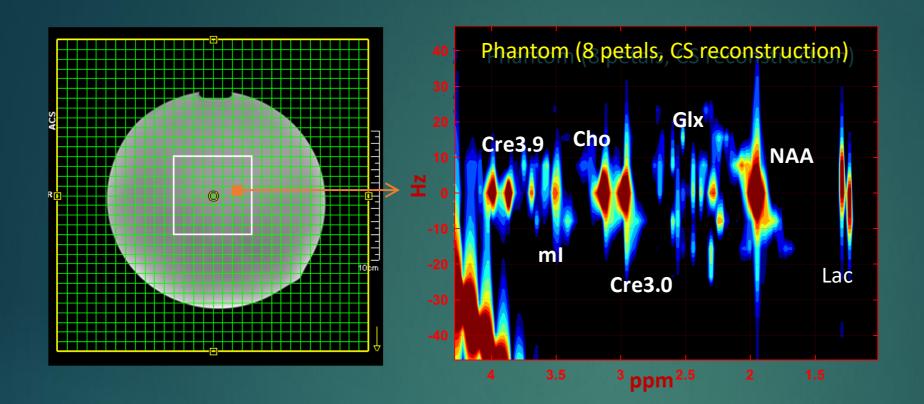
Needs only 15 petals for $N_x=16$

Rosette Petals (ROSE-SI)



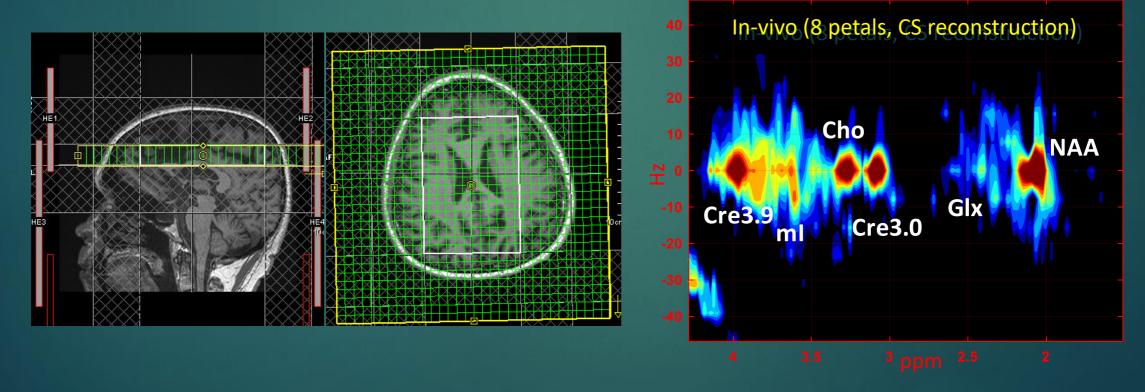
A Joy, U Emir, PM Macey, MA Thomas, ISMRM 2023

Rosette Petals (ROSE-SI)





$$N_x = 32, \frac{\omega_2}{\omega_1} = 1$$



Advantages of Rosette Trajectories

- Continuous readout during acquisition (EP-COSI without ramp sampling only samples during ~75% readout)
- Inherently less sensitive to motion artifacts (due to oversampling of center of k-space)
- Less demanding on gradient hardware (especially for lower rotational frequencies)
- Higher sensitivity than the standard CSI acquisition with square k-space support.
- Freedom in trajectory design to optimize for the available hardware by adjusting ω_2/ω_1
- Encoding speed of rosette can be used to accelerate the data acquisition process.
- Higher sampling density in central and peripheral k-space allows undersampling by reduced number of petals for accelerated acquisition and CS reconstruction

Drawbacks

- Regular patterns of phase accrual in k-space can cause artifacts
 - More complicated post-processing
 - Data must be regridded in order to apply FFT
 - Alternatively, non-uniform fast Fourier transform (NUFFT) can be used



Noll, TMI 1997; Schirda et al., JMRI 2009; Shen et al., MRM 2018; Joy et al., ISMRM 2023

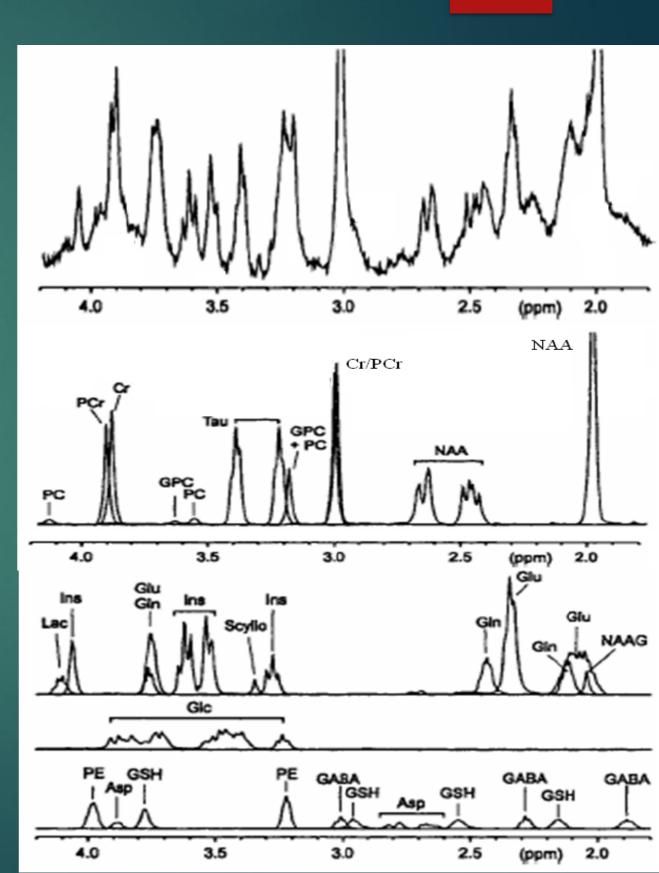


Single-voxel localized 2D MRS: L-COSY and JPRESS

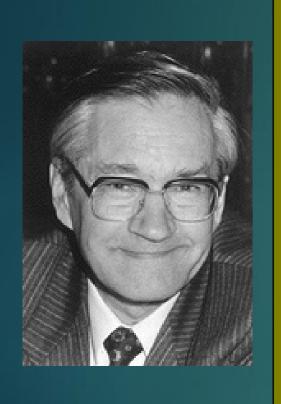
1D MRS Quantitation

- LC-Model for 1D MRS quantitation.
- Works in frequency domain using prior knowledge

Provencher (2001)

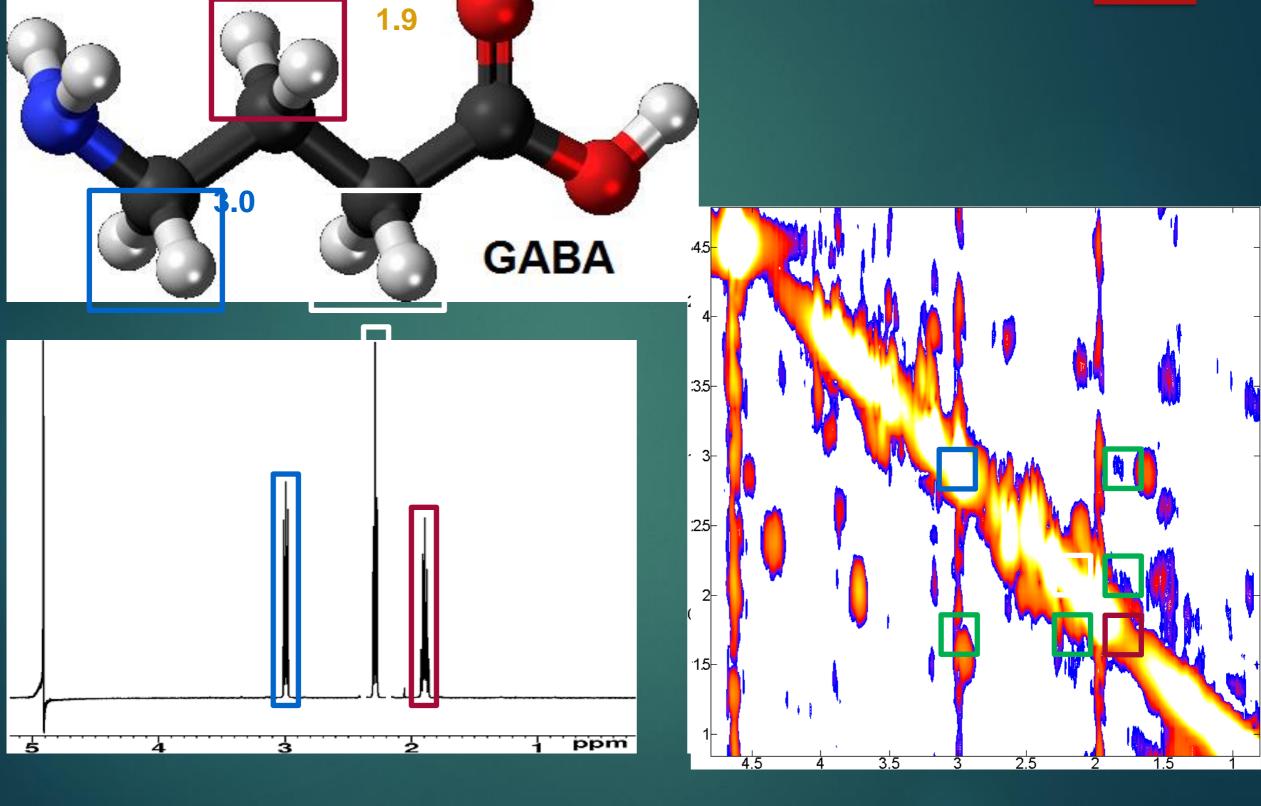


A quote from 1991 Nobel laureate Richard Ernst

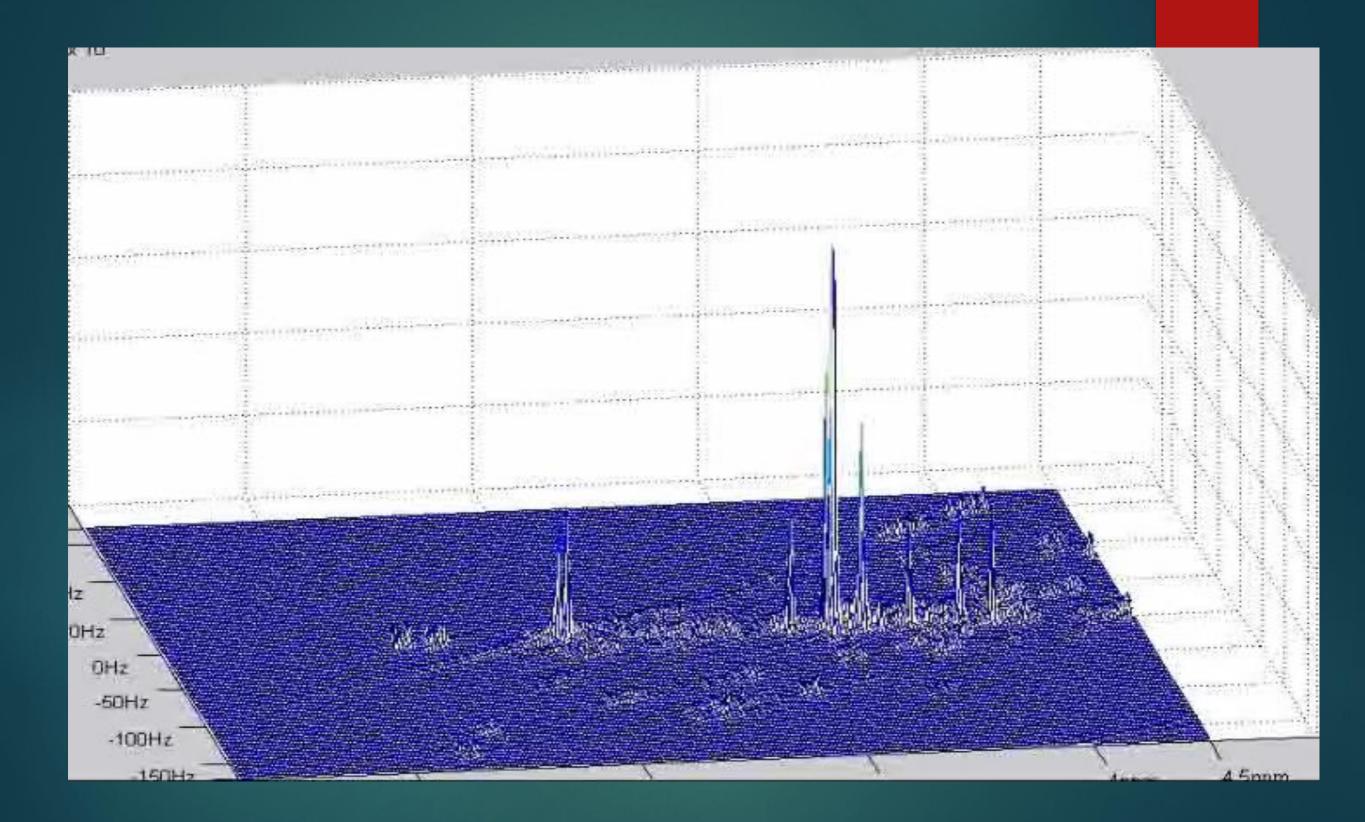


"One-dimensional spectra that are rendered inscrutable because of severe overlap may be unravelled by separating interactions of different physical origins, e.g. chemical shift and couplings, thus making it possible to spread the signals in a second frequency dimension much like opening a Venetian

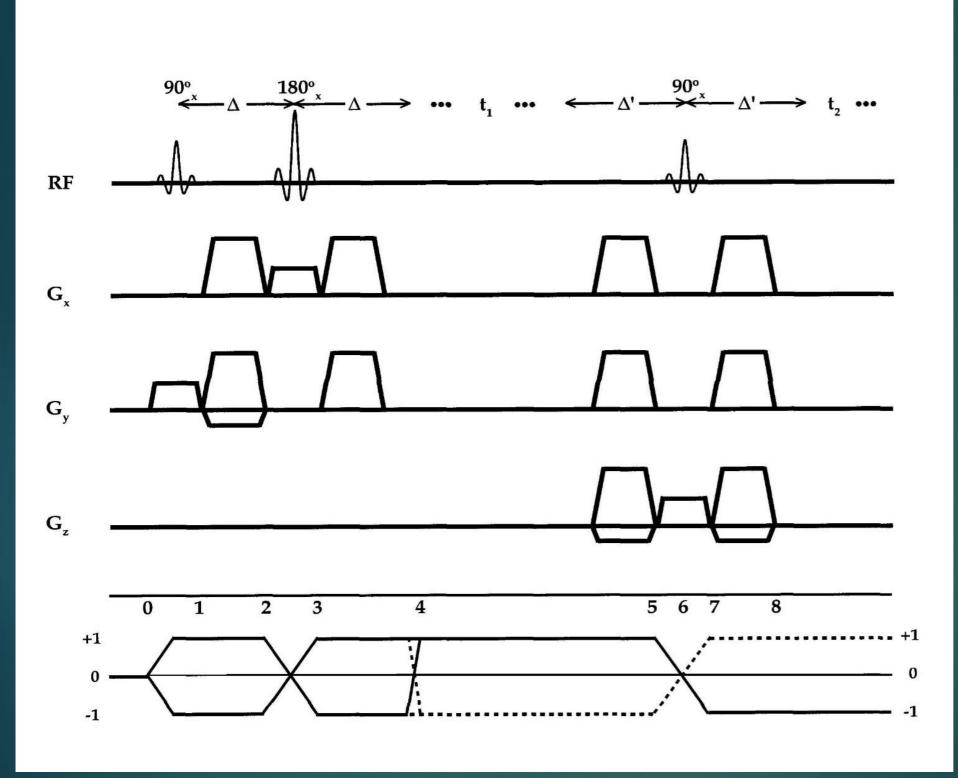
Why 2D Spectroscopy?



Verma et al. ISMRM 2014

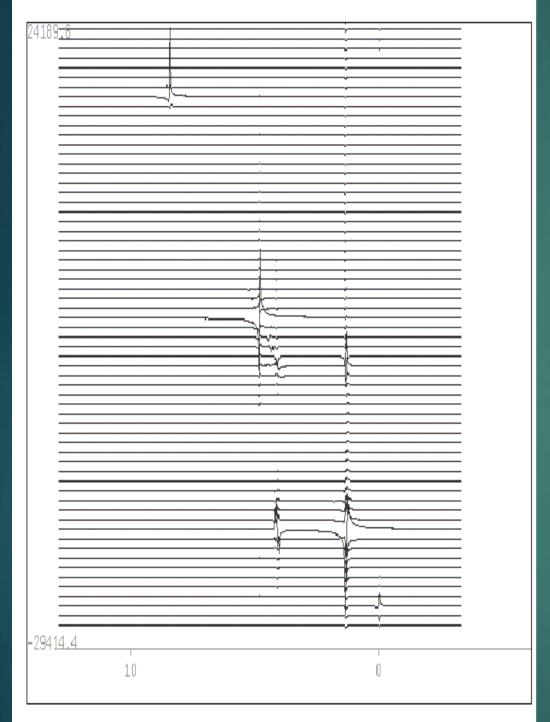


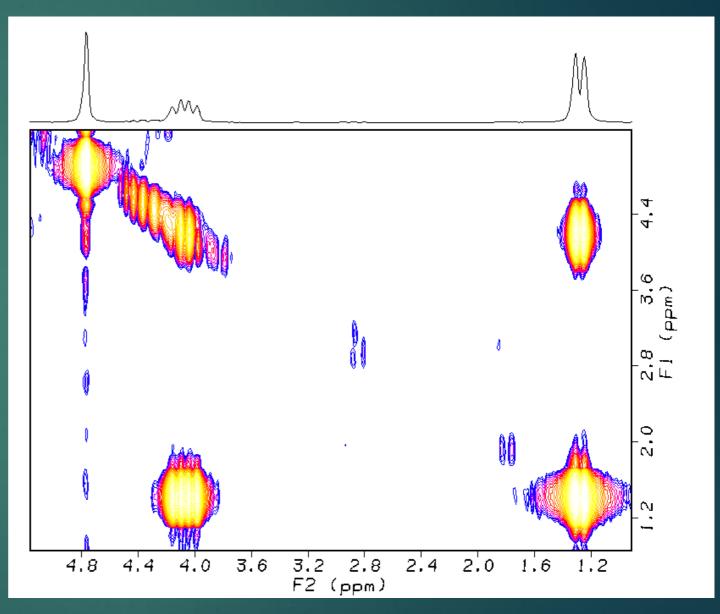
Localized 2D Correlated Spectroscopy (L- COSY)



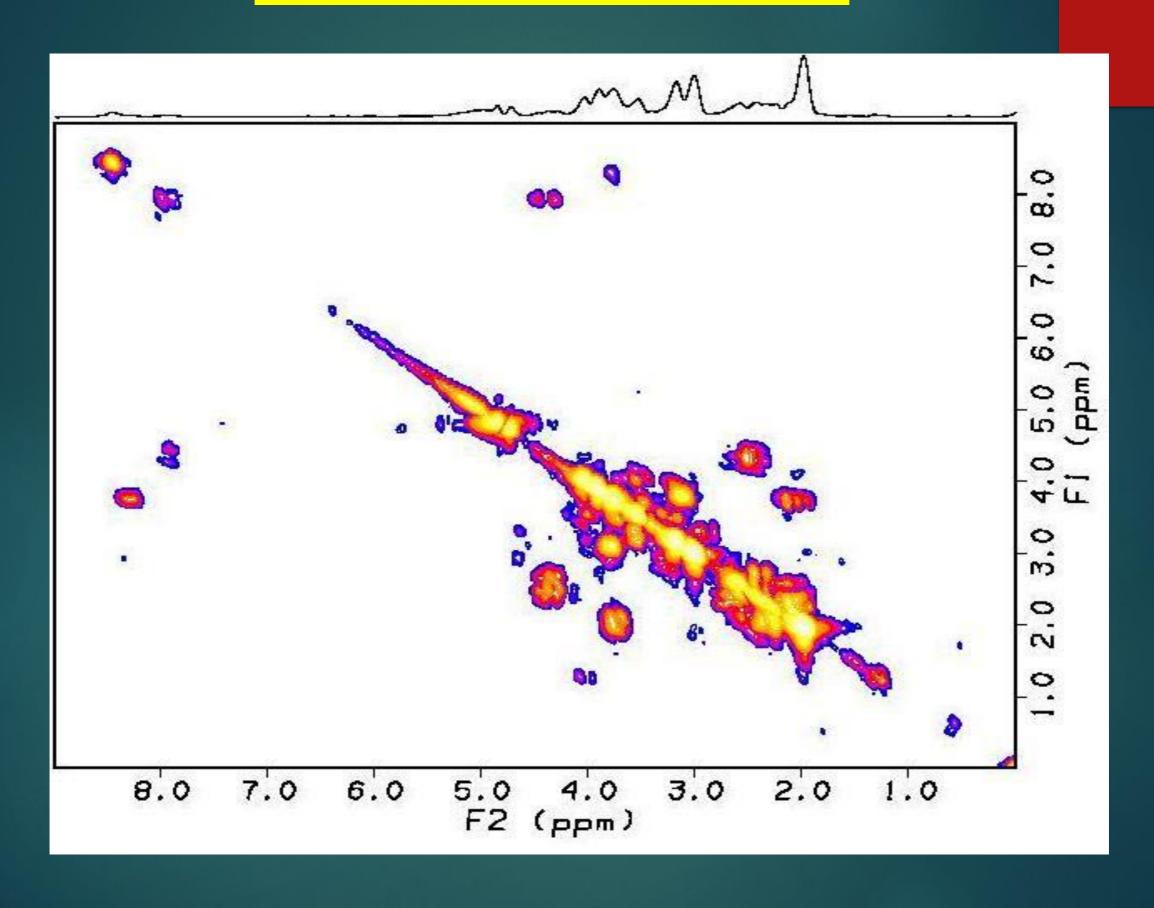
- Based on a spin-echo and a coherence-transfer-echo Hahn (1952) / Maudsley, Wokaun and Ernst (1978)

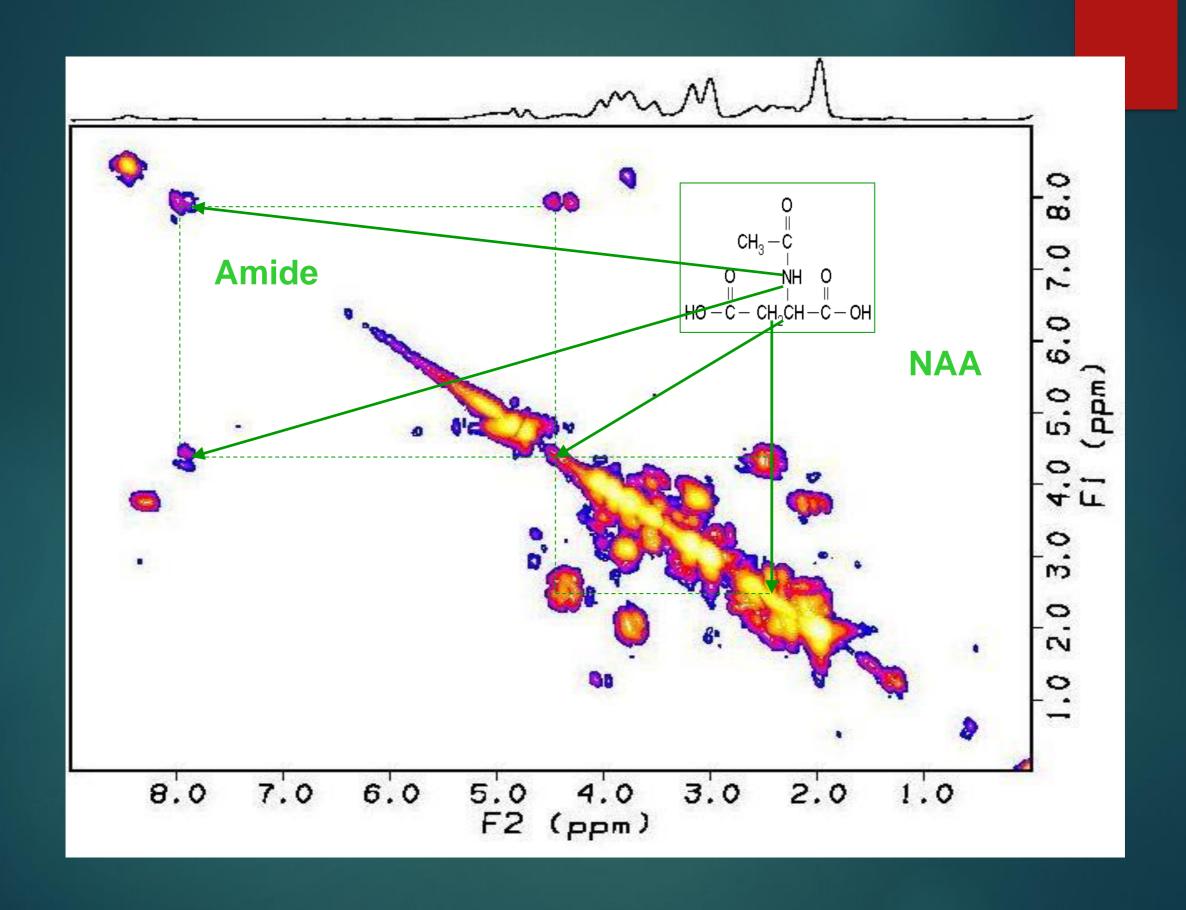


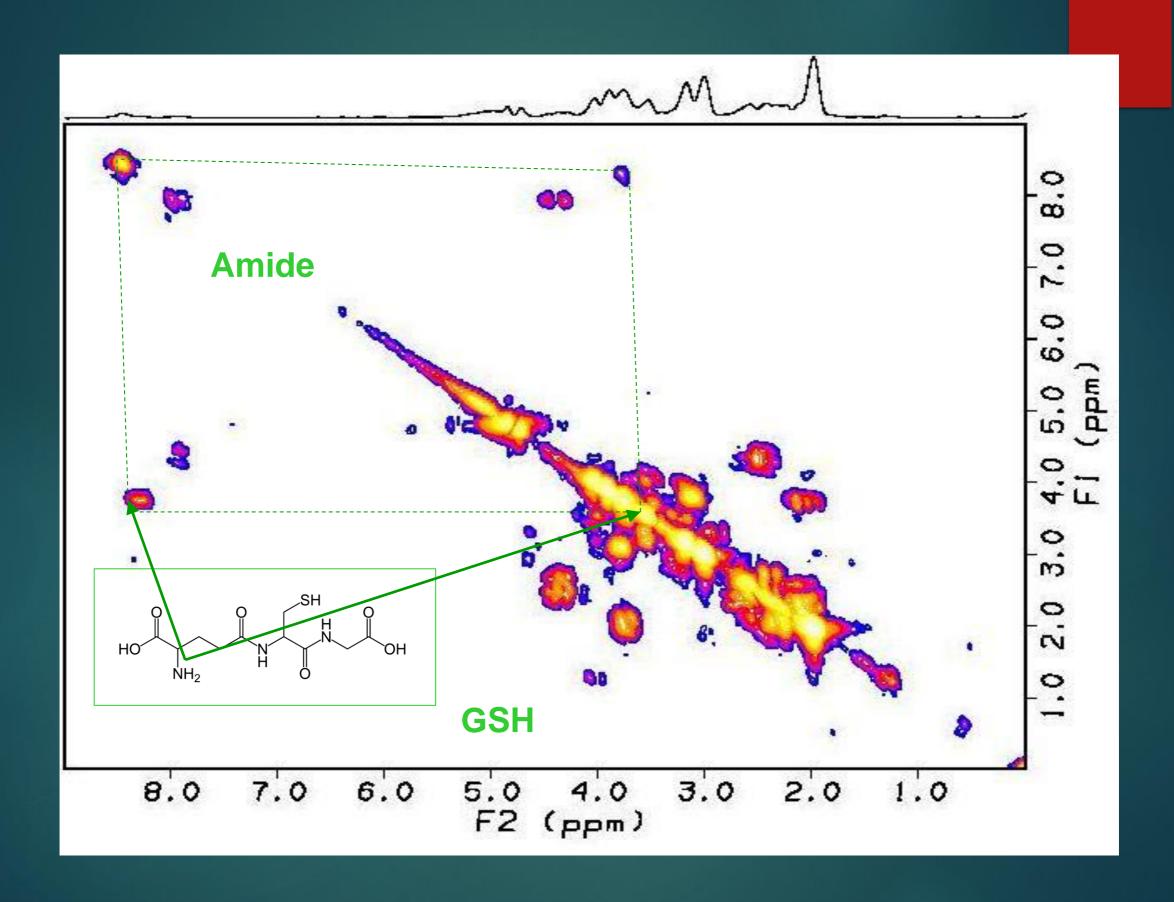


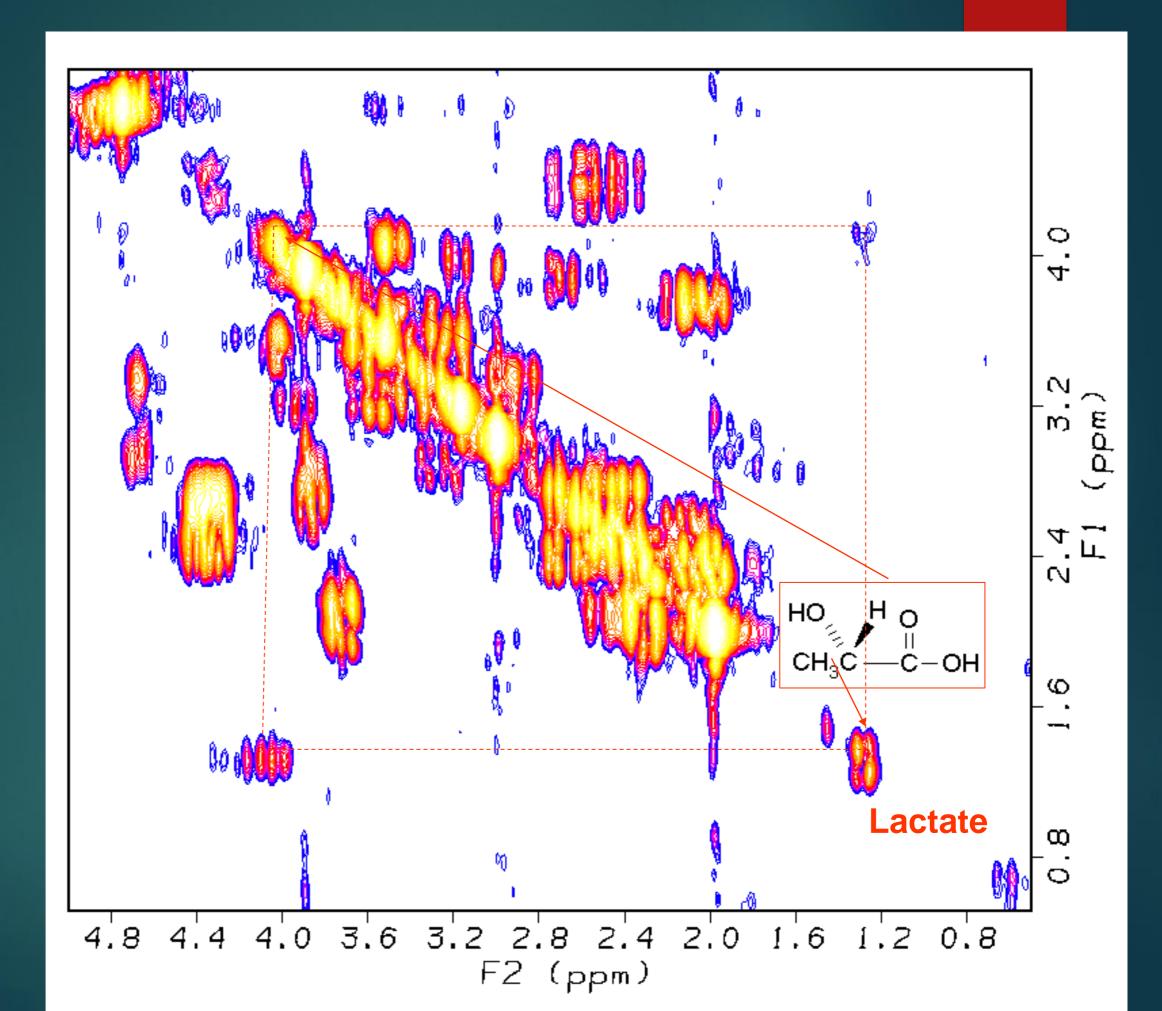


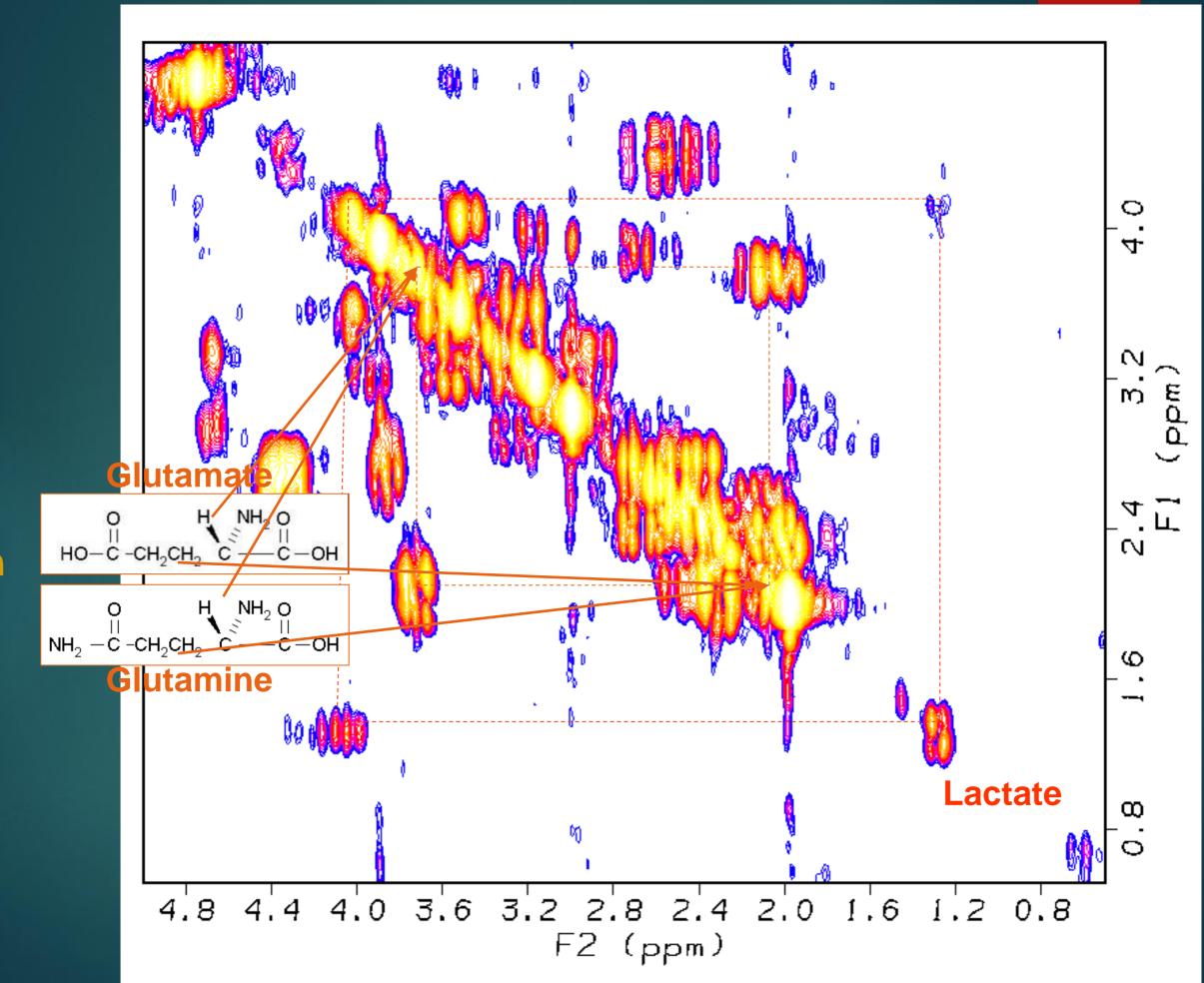
Brain Phantom 3T MRI/MRS Scanner



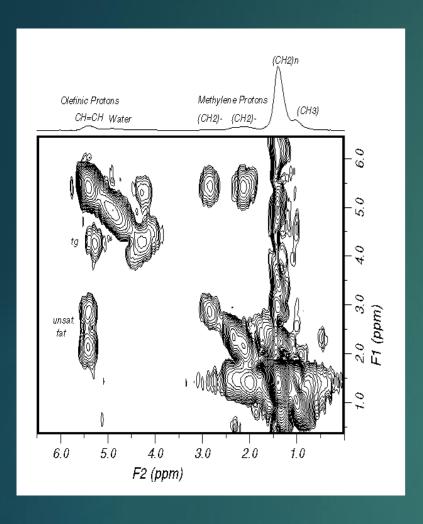


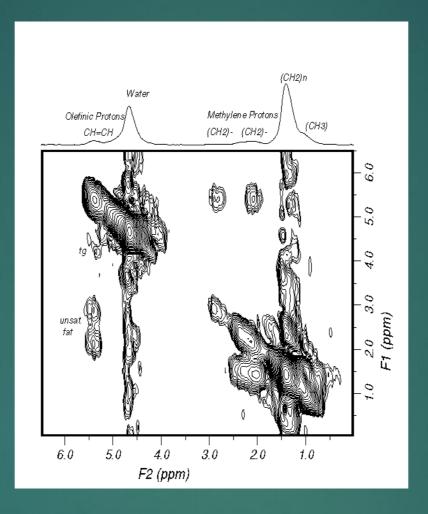


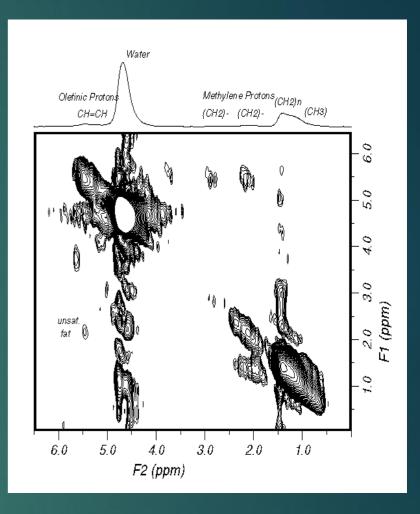




Localized 2D COSY Spectra of a 27yo healthy breast

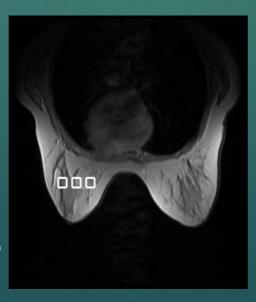






- -1x1x1 cm³
- 40 t₁ incr.
- $8NEX/\Delta t_1$

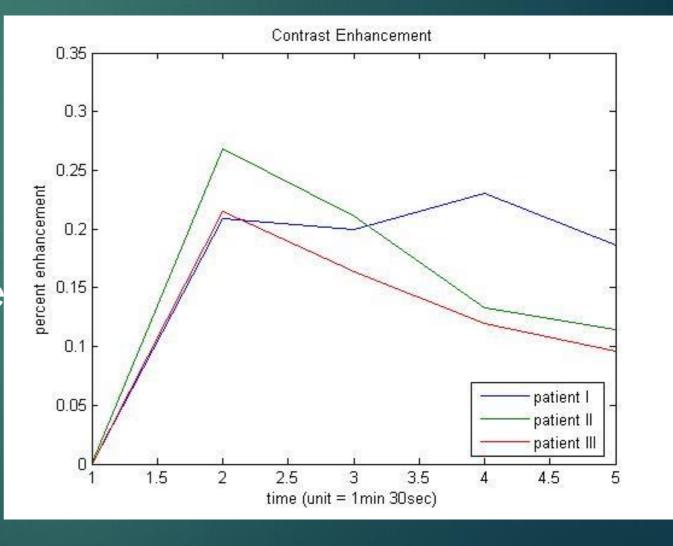
-10 minutes -1.5T -30 minutes for 3 locations



(Thomas JMRI2001)

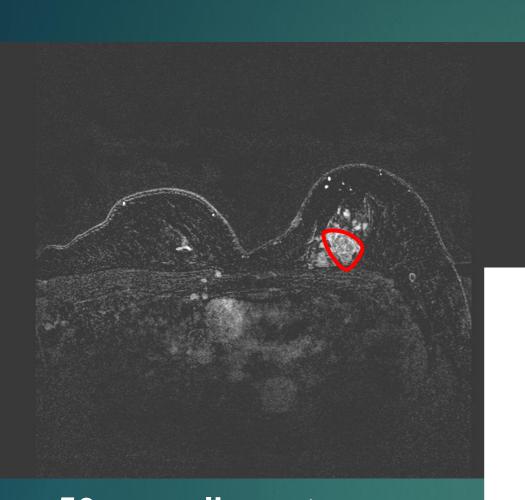
DCE-MRI

- Graphs of DCE-MRI curves for malignant patients
- Plots show uncertainty in enhancement curves
- Patient I shows a plateau shaped curve which cannot differentiate malignant from benign lesion

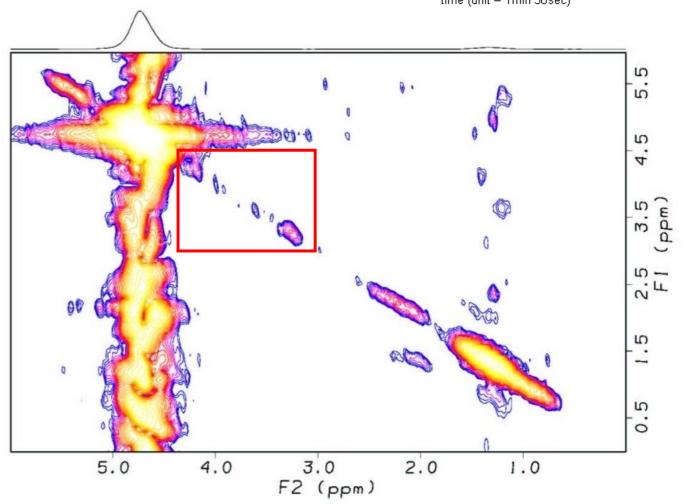


Malignant Patient with Type II

enhancement

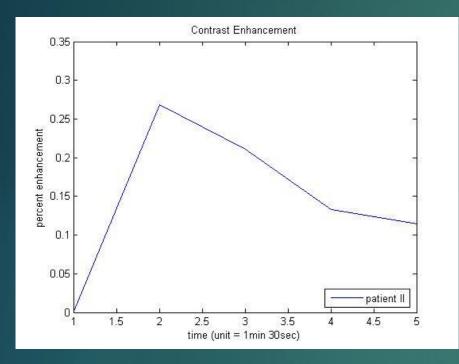


-56 yo malignant patient
-1x1x1 cm3
-45 t1 incr.
-8NEX/ ∆ t1
-12 minutes



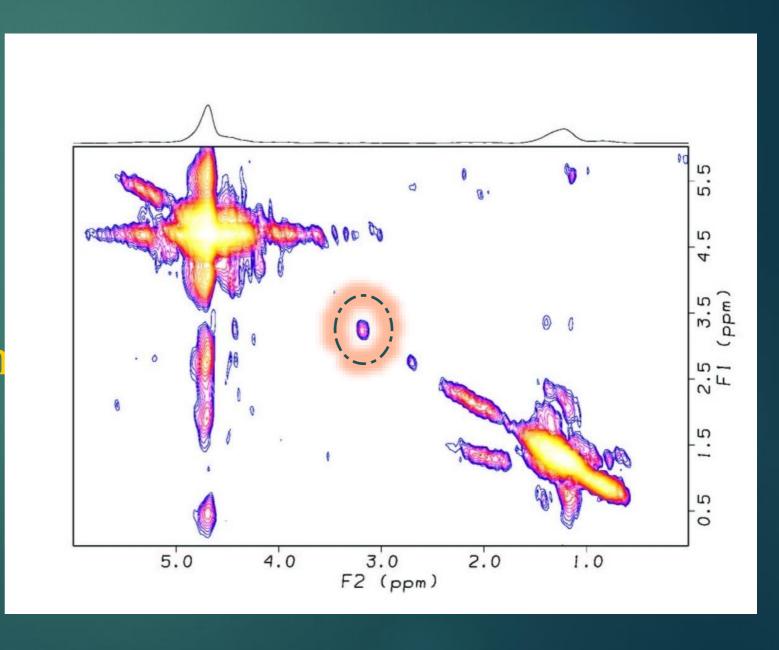
Lipnick 2010

2D L-COSY of Breast Cancer



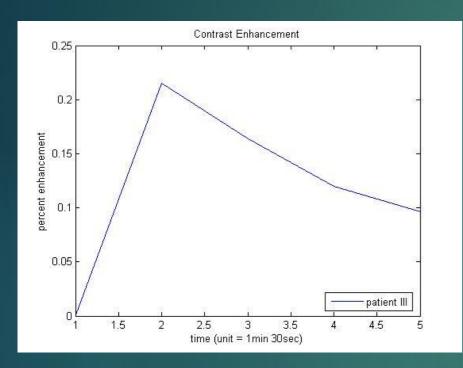
A 55 yo malignant patien

- -1x1x1 cm³
- -45 t₁ incr.
- -8NEX/ Δt_1
 - -12 minutes



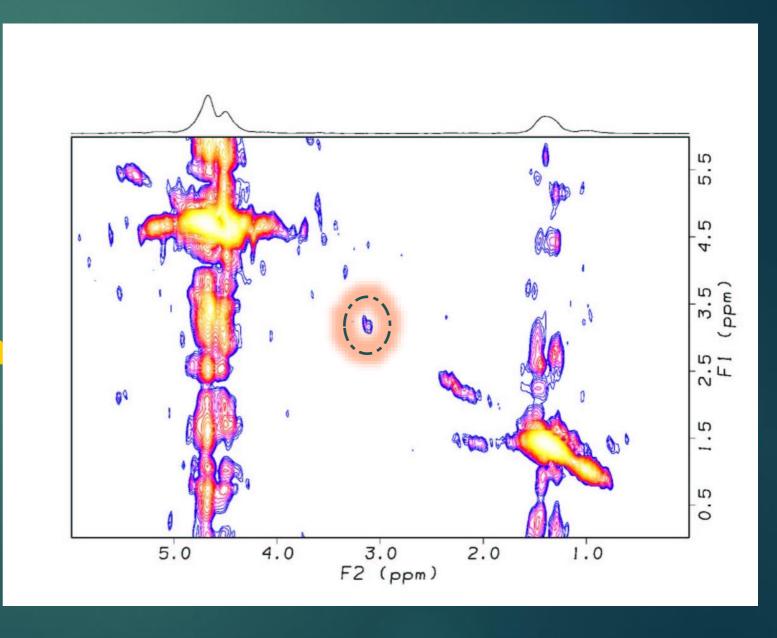
Lipnick 2010

2D L-COSY of Breast Cancer

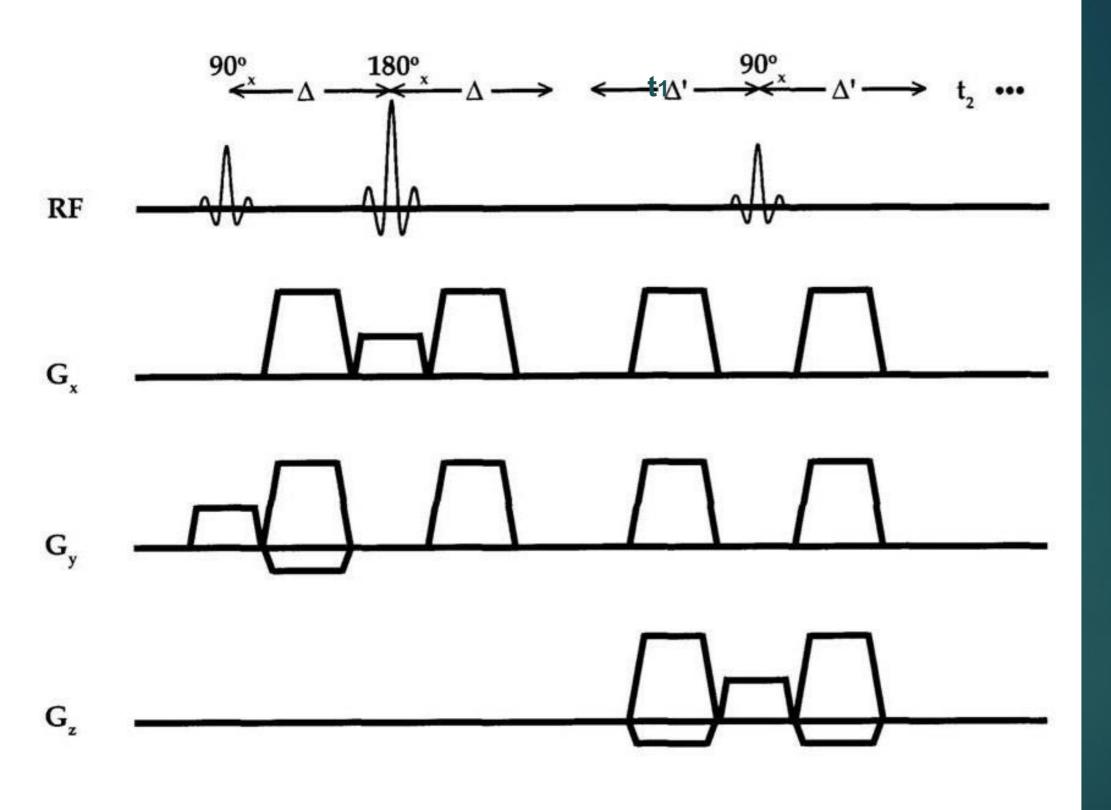


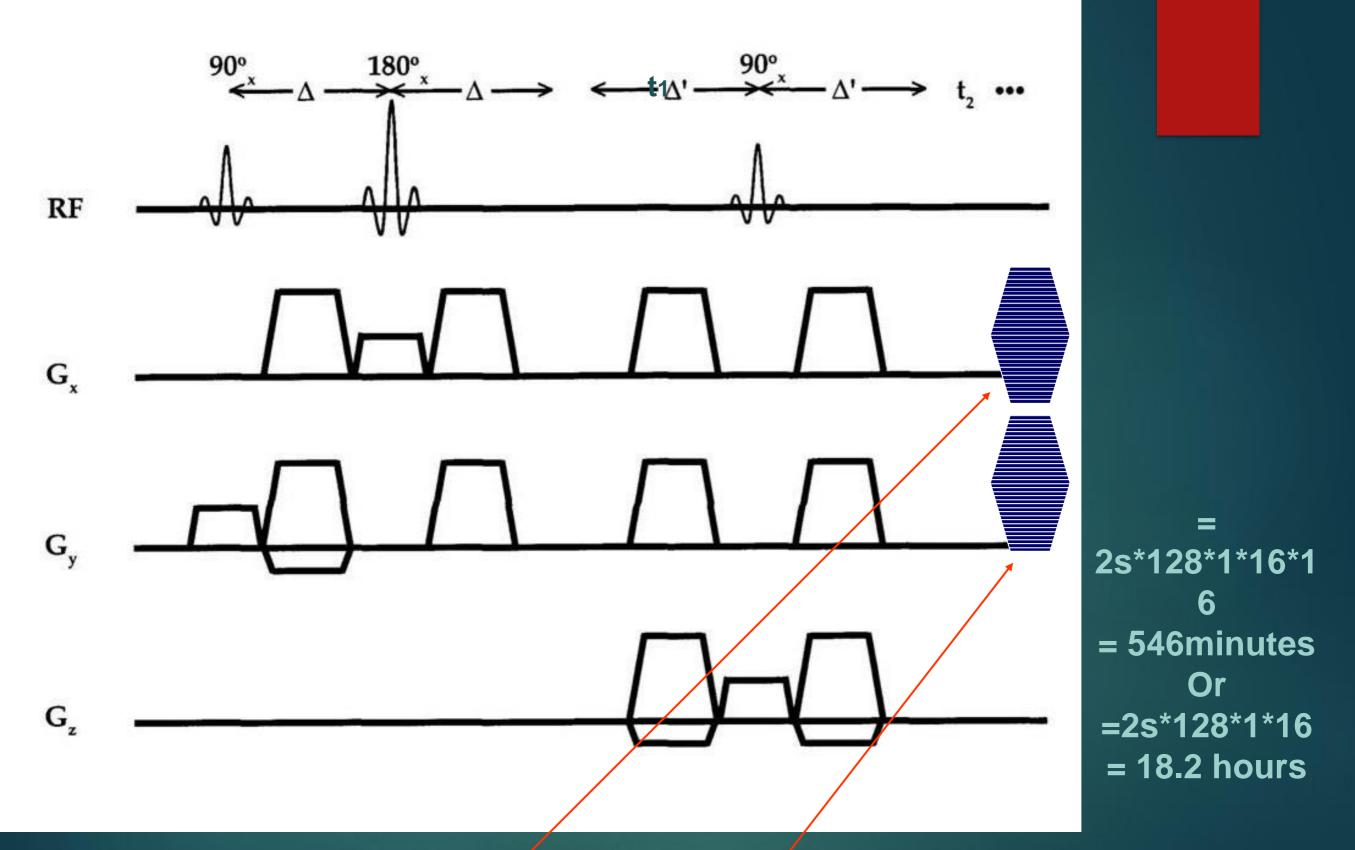
A 55 yo malignant patien

- -1x1x1 cm³
 -45 t₁ incr.
- -8NEX/ Δt_1
 - -12 minutes



4D ¹H MR Spectroscopic Imaging: 2 Spectral + 2 Spatial Dimensions

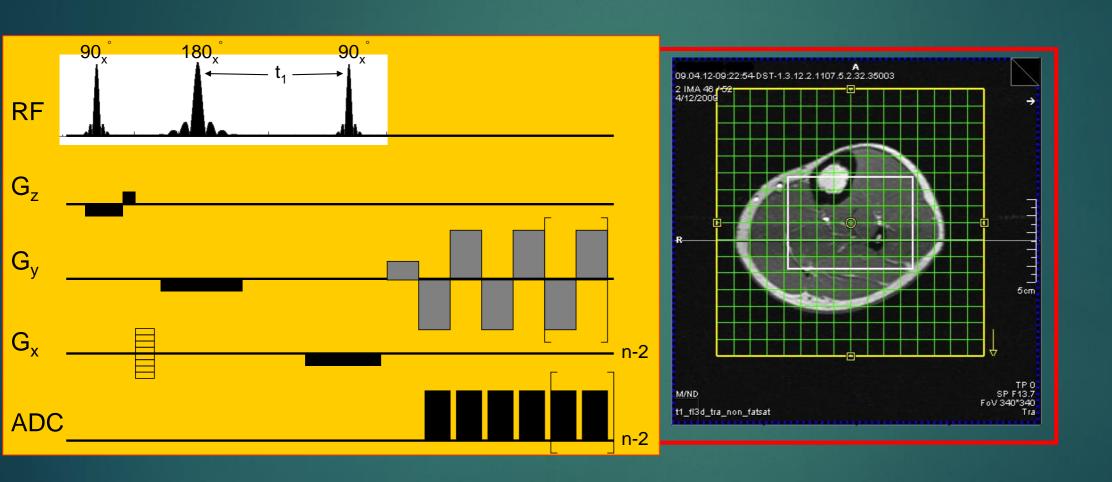




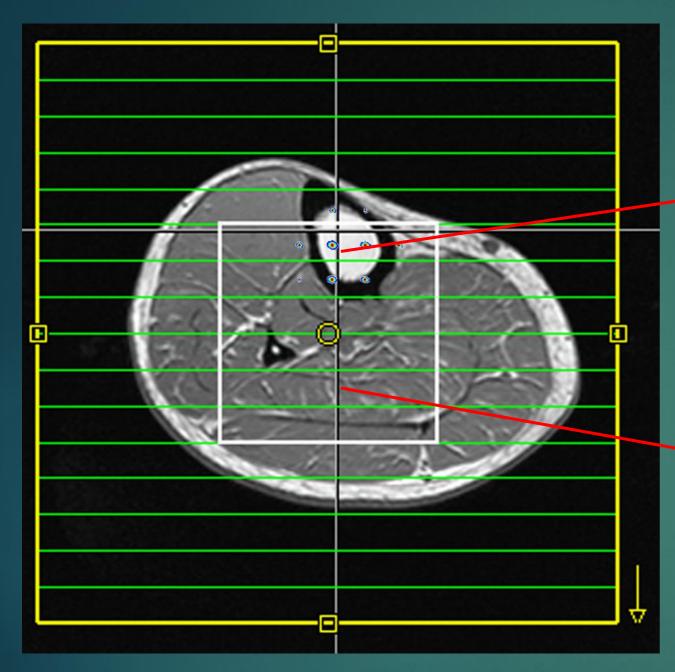
Total Scan time

TR* N (t1 Encodings) *N (y-Phase Encodings) N (X-Phase Encodings) * N (t1 Encodings) * Averages

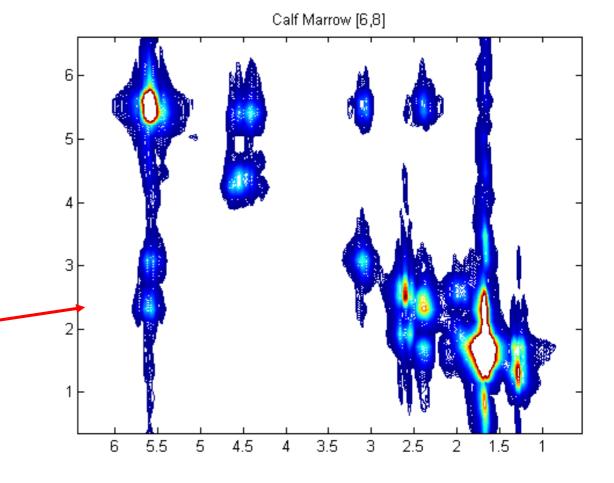
Echo-Planar Correlated Spectroscopic Imaging (EP-COSI)

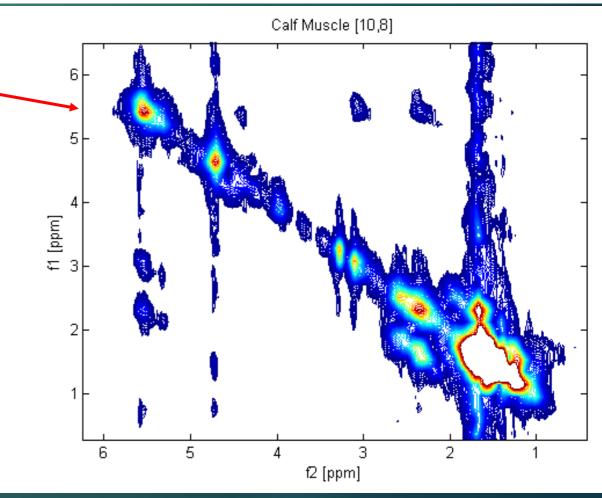


EP-COSI of Human Calf in vivo



3T MRI, TR/TE=1.5s/30ms, CP-Ext (T/R), 16x16 (x,y), FOV 16cm, Extracted VOI of 1x1x2cm³ and Total Duration of 20 minutes

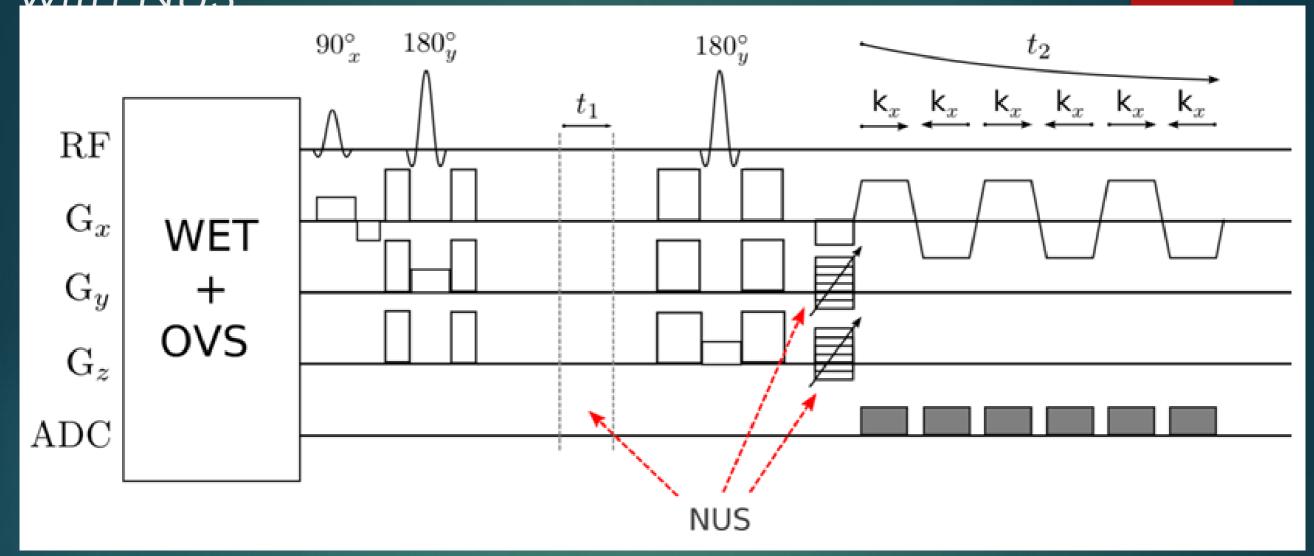




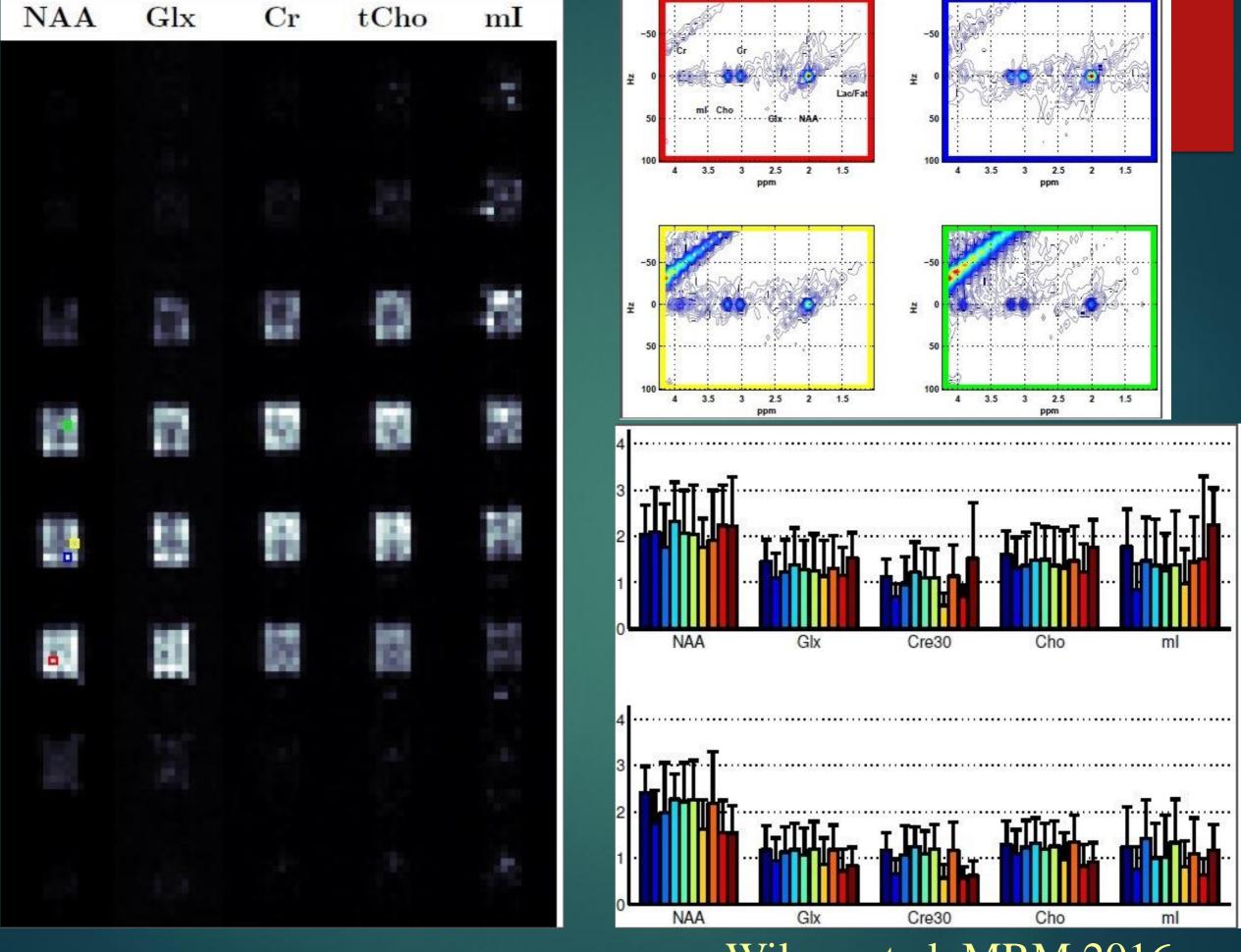


5. 2D spectral+ 3D Spatial Encoding

5D Echo-Planar J-resolved Spectroscopic Imaging with NUS



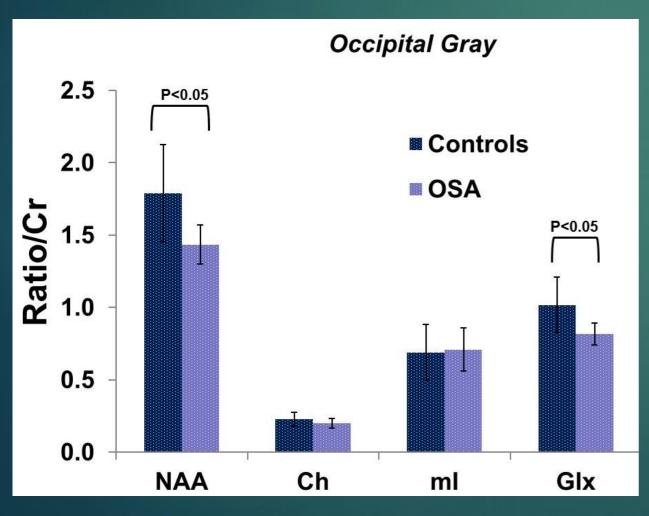
- 3D CSI/MRSI (32x32x16) -410 minutes
 - 3D EPSI (32x16) 12.8 minutes
- 3D EPSI+2DJRES (32x16x64)- 819 minutes
- 5D EPJRESI (16x8x64) 8X NUS- 21 minutes

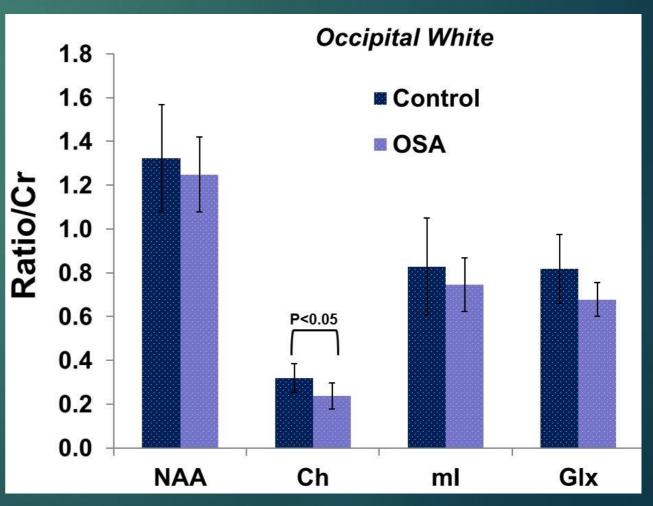


Wilson et al, MRM 2016

5D EP-JRESI 8X- OSA

Metabolites \rightarrow	NAA	Ch	ml	Glx
Healthy Controls				
Occipital White	16.94	8.52	14.33	6.08
Occipetal Gray	1.62	1.56	2.79	10.82
Left Insular Cortex	7.30	6.53	5.19	2.90
Left Parietal Insular Cortex	1.17	8.82	10.31	6.58
OSA patients post CPAP				
Occipital White	9.20	4.92	8.70	14.50
Occipetal Gray	6.03	3.20	4.00	10.00
Left Insular Cortex	2.70	1.22	18.69	1.40
Left Parietal Insular Cortex	2.70	1.97	14.81	9.56

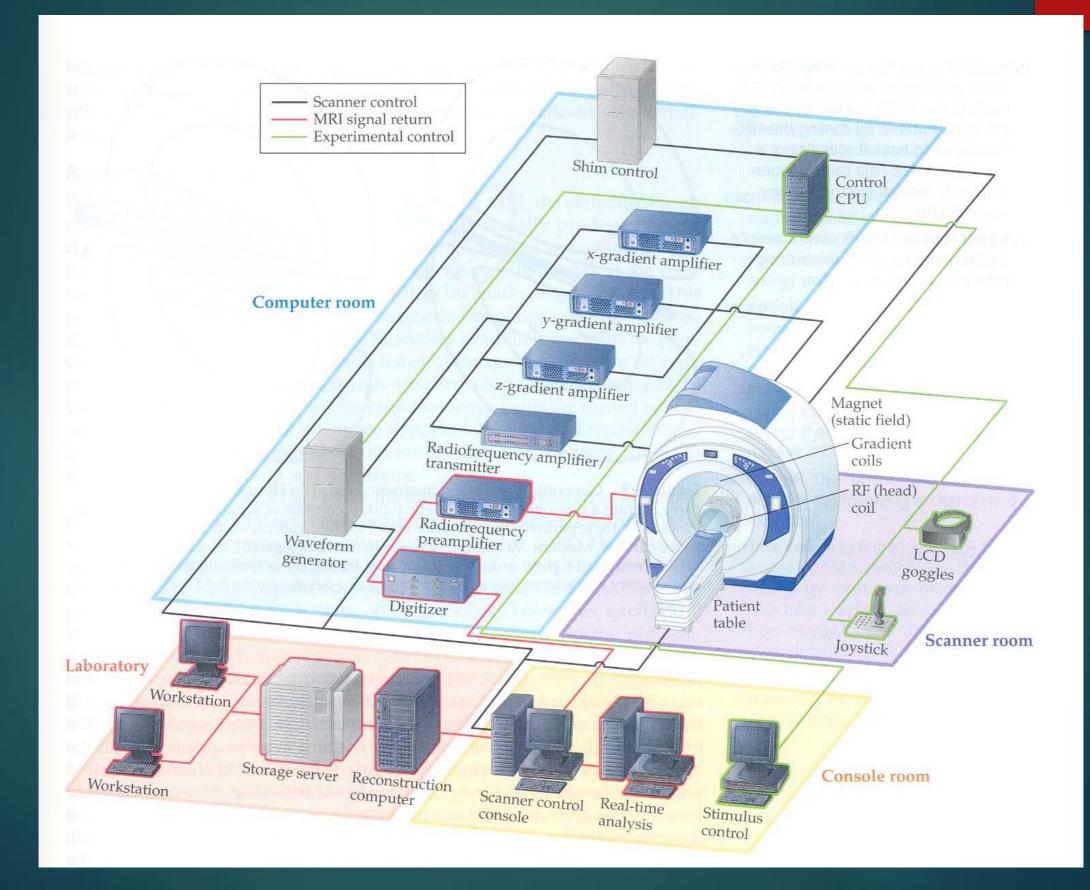




Thomas ISMRM 2016

Overview of an MRI scanner





Conclusions



- MRI has become a revolution in Medicine during our time, thanks to NMR!
 - MRI sequences can be easily translated into MR Spectroscopic Imaging
- EPSI, Spiral, SI-CONCEPT and Radial EPSI have been implemented on MRI scanners on 3T, 7T and 9.4T MRI scanners
- Accelerated Polar and Radial MRSI data need gridding to Cartesian; acquisition less than 5 minutes may facilitate functional MRSI
- 3spatial+2 spectral accelerated acquisition & the MRSI data can be post-processed using linear and non-linear reconstruction (Compressed Sensing)
 - 6D MRSI (3spatial+3 spectral) and more.....

